



## GENERALIZED YOSIDA APPROXIMATION OPERATOR WITH AN APPLICATION TO A SYSTEM OF YOSIDA INCLUSIONS

MOHD AKRAM<sup>1,\*</sup>, JIA-WEI CHEN<sup>2</sup>, MOHD DILSHAD<sup>3</sup>

<sup>1</sup>Department of Mathematics, Faculty of Science, Islamic University of Madinah, Madinah 170, KSA

<sup>2</sup>School of Mathematics and Statistics, Southwest University, Chongqing 400715, China

<sup>3</sup>Department of Mathematics, Faculty of Science, University of Tabuk, Tabuk-71491, KSA

**Abstract.** In this article, we introduce and study a generalized Yosida approximation operator associated to  $H(\cdot, \cdot)$ -co-accretive mappings. We show the convergence of generalized Yosida approximation operator based on the concept of graph convergence and resolvent operator convergence. We establish a relationship between the graph convergence for  $H(\cdot, \cdot)$ -co-accretive operators and generalized Yosida approximation operators. Finally, the existence and uniqueness of solution of a system of generalized Yosida inclusions under some mild conditions is established in  $q$ -uniformly smooth Banach spaces.

**Keywords.** Graph convergence; Resolvent operator; Iterative algorithm; Yosida approximation operator; System of Yosida inclusions.

**2010 Mathematics Subject Classification.** 47H09, 49J40.

### 1. INTRODUCTION

The theory of classical variational inequalities is one of the most important mathematical subjects. It has many different generalizations with different approaches. One of the remarkable generalizations is the variational inclusion. Since a large number of problems arising in science, engineering, social sciences, management, finance, operations research and optimizations, etc., can be formulated as a variational inclusion; see, for example, [1]-[7] and the references therein, the variational inclusions have recently extensively investigated using novel and innovative techniques in various directions. The notion of monotone operators was first independently introduced and studied by Zarantonello [8] and Minty [9]. A significant interest has been shown by number of researchers as they have firm relations with the

\*Corresponding author.

E-mail addresses: akramkhan\_20@rediffmail.com (M. Akram), J.W.Chen713@163.com (J.W. Chen), mdilshaad@gmail.com (M. Dilshad).

Received January 26, 2017; Accepted April 18, 2018.

following evolution equation

$$\begin{cases} \frac{dx}{dt} + A(x) = 0; \\ x(0) = x_0, \end{cases}$$

which is the model of many physical problems of practical applications. It is very difficult to solve these types of models, if the involving function  $A$  is not continuous. To overcome this problem, a natural step is to find a sequence of Lipschitz functions that approximate  $A$  in some sense. This idea was introduced by Yosida. On the other hand, it is well known that two quite useful single-valued lipschitz continuous operators can be associated with a monotone operators, namely its resolvent operator and its Yosida approximation operator. The monotone operators on Hilbert spaces can be regularized into single-valued Lipschitzian monotone operators via a process known as the Yosida approximation [10]-[13]. Further, this process was extended to study the problems in Banach spaces; see, for example, [14]-[17]. The Yosida approximation operators are useful to approximate the solutions of variational inclusion problems using resolvent operators. Recently, many authors implemented Yosida approximation operators to study some of variational inclusion problems using different approaches; see, for example, [18]-[22] and the references therein.

The paper is organized as follows. In Section 2, we recall basic definitions and properties. In Section 3, we introduce a generalized Yosida approximation operator associated to  $H(\cdot, \cdot)$ -co-accretive mapping and discuss its Lipschitz continuity and strong monotonicity. In Section 4, we investigate the graph convergence of  $H(\cdot, \cdot)$ -co-accretive mappings and its relationship with the convergence of generalized Yosida approximation operators. An example is constructed to demonstrate the graph convergence of  $H(\cdot, \cdot)$ -co-accretive mappings and the convergence of generalized Yosida approximation operators. In the last section, we consider a system of generalized Yosida inclusions and establish the existence results. We also suggest an iterative algorithm and discuss its convergence analysis.

## 2. PRELIMINARIES

In this section, we collect some basic notions and auxiliary results needed in the subsequent sections. Let  $X$  be a real Banach space with norm  $\|\cdot\|$ . Let  $X^*$  be the topological dual of  $X$  and let  $d$  be the metric induced by norm  $\|\cdot\|$ . Let  $\langle \cdot, \cdot \rangle$  be the dual pair between  $X$  and  $X^*$  and let  $CB(X)$  (respectively  $2^X$ ) be the family of all nonempty closed and bounded subsets (respectively, all non empty subsets) of  $X$ . The generalized duality mapping  $J_q : X \rightarrow 2^{X^*}$  is defined by

$$J_q(x) = \left\{ f^* \in X^* : \langle x, f^* \rangle = \|x\|^q, \|f^*\| = \|x\|^{q-1} \right\}, \forall x \in X,$$

where  $q > 1$  is a constant. In particular,  $J_2$  is the usual normalized duality mapping. It is well known that  $J_q(x) = \|x\|^{q-1} J_2(x)$ ,  $\forall x (\neq 0) \in X$ . In the sequel, we assume that  $X$  is a real Banach space such that  $J_q$  is single-valued. If  $X \equiv H$ , a real Hilbert space then  $J_2$  becomes the identity mapping on  $X$ . The modulus of smoothness of  $X$  is the function  $\rho_X : [0, \infty) \rightarrow [0, \infty)$  defined by

$$\rho_X(t) = \sup \left\{ \frac{\|x+y\| + \|x-y\|}{2} - 1 : \|x\| \leq 1, \|y\| \leq t \right\}.$$

A Banach space  $X$  is said to be uniformly smooth if  $\lim_{t \rightarrow 0} \frac{\rho_X(t)}{t} = 0$ ;  $X$  is said to be  $q$ -uniformly smooth if there exists a constant  $c > 0$  such that  $\rho_X(t) \leq ct^q$ ,  $q > 1$ . Note that  $J_q$  is single-valued, if  $X$  is uniformly

smooth. In the study of characteristic inequalities in  $q$ -uniformly smooth Banach spaces, Xu [23] proved the following lemma.

**Lemma 2.1.** *Let  $q > 1$  be a real number and let  $X$  be a real uniformly smooth Banach space. Then  $X$  is  $q$ -uniformly smooth if and only if there exists a constant  $c_q > 0$  such that*

$$\|x + y\|^q \leq \|x\|^q + q\langle y, J_q(x) \rangle + c_q\|y\|^q, \quad \forall x, y \in X.$$

**Definition 2.2.** A mapping  $A : X \rightarrow X$  is said to be

(i) accretive if

$$\langle Ax - Ay, J_q(x - y) \rangle \geq 0, \quad \forall x, y \in X;$$

(ii) strictly accretive if

$$\langle Ax - Ay, J_q(x - y) \rangle > 0, \quad \forall x, y \in X,$$

and the equality holds if and only if  $x = y$ ;

(iii)  $\delta$ -strongly accretive if there exists a constant  $\delta > 0$  such that

$$\langle Ax - Ay, J_q(x - y) \rangle \geq \delta\|x - y\|^q, \quad \forall x, y \in X;$$

(iv)  $\beta$ -relaxed accretive if there exists a constant  $\beta > 0$  such that

$$\langle Ax - Ay, J_q(x - y) \rangle \geq (-\beta)\|x - y\|^q, \quad \forall x, y \in X;$$

(v)  $\mu$ -cocoercive if there exists a constant  $\mu > 0$  such that

$$\langle Ax - Ay, J_q(x - y) \rangle \geq \mu\|Ax - Ay\|^q, \quad \forall x, y \in X;$$

(vi)  $\gamma$ -relaxed cocoercive if there exists a constant  $\gamma > 0$  such that

$$\langle Ax - Ay, J_q(x - y) \rangle \geq (-\gamma)\|Ax - Ay\|^q, \quad \forall x, y \in X;$$

(vii)  $\sigma$ -Lipschitz continuous if there exists a constant  $\sigma > 0$  such that

$$\|Ax - Ay\| \leq \sigma\|x - y\|, \quad \forall x, y \in X;$$

(viii)  $\eta$ -expansive, if there exists a constant  $\eta > 0$  such that

$$\|Ax - Ay\| \geq \eta\|x - y\|, \quad \forall x, y \in X;$$

if  $\eta = 1$ , then it is expansive.

**Definition 2.3.** Let  $H : X \times X \rightarrow X$  and  $A, B : X \rightarrow X$  be three single-valued mappings. Then

(i)  $H(A, \cdot)$  is said to be  $\mu_1$ -cocoercive with respect to  $A$  if there exists a constant  $\mu_1 > 0$  such that

$$\langle H(Ax, u) - H(Ay, u), J_q(x - y) \rangle \geq \mu_1\|Ax - Ay\|^q, \quad \forall x, y, u \in X;$$

(ii)  $H(\cdot, B)$  is said to be  $\gamma_1$ -relaxed cocoercive with respect to  $B$  if there exists a constant  $\gamma_1 > 0$  such that

$$\langle H(u, Bx) - H(u, By), J_q(x - y) \rangle \geq (-\gamma_1)\|Bx - By\|^q, \quad \forall x, y, u \in X;$$

(iii)  $H(A, B)$  is said to be symmetric cocoercive with respect to  $A$  and  $B$  if  $H(A, \cdot)$  is cocoercive with respect to  $A$  and  $H(\cdot, B)$  is relaxed cocoercive with respect to  $B$ ;

(iv)  $H(A, \cdot)$  is said to be  $\alpha_1$ -strongly accretive with respect to  $A$  if there exists a constant  $\alpha_1 > 0$  such that

$$\langle H(Ax, u) - H(Ay, u), J_q(x - y) \rangle \geq \alpha_1\|x - y\|^q, \quad \forall x, y, u \in X;$$

- (v)  $H(\cdot, B)$  is said to be  $\beta_1$ -relaxed accretive with respect to  $B$  if there exists a constant  $\beta_1 > 0$  such that
 
$$\langle H(u, Bx) - H(u, By), J_q(x - y) \rangle \geq (-\beta_1)\|x - y\|^q, \forall x, y, u \in X;$$
- (vi)  $H(A, B)$  is said to be symmetric accretive with respect to  $A$  and  $B$  if  $H(A, \cdot)$  is strongly accretive with respect to  $A$  and  $H(\cdot, B)$  is relaxed accretive with respect to  $B$ ;
- (vii)  $H(A, \cdot)$  is said to be  $\xi_1$ -Lipschitz continuous with respect to  $A$  if there exists a constant  $\xi_1 > 0$  such that
 
$$\|H(Ax, u) - H(Ay, u)\| \leq \xi_1\|x - y\|, \forall x, y, u \in X;$$
- (viii)  $H(\cdot, B)$  is said to be  $\xi_2$ -Lipschitz continuous with respect to  $B$  if there exists a constant  $\xi_2 > 0$  such that
 
$$\|H(u, Bx) - H(u, By)\| \leq \xi_2\|x - y\|, \forall x, y, u \in X.$$

**Definition 2.4.** Let  $f, g : X \rightarrow X$  be two single-valued mappings and let  $M : X \times X \rightarrow 2^X$  be a multi-valued mapping. Then

- (i)  $M(f, \cdot)$  is said to be  $\alpha$ -strongly accretive with respect to  $f$ , if there exists a constant  $\alpha > 0$  such that
 
$$\langle u - v, J_q(x - y) \rangle \geq \alpha\|x - y\|^q, \forall x, y, w \in X \text{ and } \forall u \in M(f(x), w), v \in M(f(y), w);$$
- (ii)  $M(\cdot, g)$  is said to be  $\beta$ -relaxed accretive with respect to  $g$ , if there exists a constant  $\beta > 0$  such that
 
$$\langle u - v, J_q(x - y) \rangle \geq (-\beta)\|x - y\|^q, \forall x, y, w \in X \text{ and } \forall u \in M(w, g(x)), v \in M(w, g(y));$$
- (iii)  $M(f, g)$  is said to be symmetric accretive with respect to  $f$  and  $g$ , if  $M(f, \cdot)$  is strongly accretive with respect to  $f$  and  $M(\cdot, g)$  is relaxed accretive with respect to  $g$ .

**Definition 2.5.** Let  $A, B, f, g : X \rightarrow X$  and  $H : X \times X \rightarrow X$  be the single-valued mappings. Let  $M : X \times X \rightarrow 2^X$  be a multi-valued mapping. The mapping  $M$  is said to be  $H(\cdot, \cdot)$ -co-accretive with respect to  $A, B, f$  and  $g$ , if  $H(A, B)$  is symmetric cocoercive with respect to  $A$  and  $B$ ,  $M(f, g)$  is symmetric accretive with respect to  $f$  and  $g$  and  $(H(A, B) + \lambda M(f, g))(X) = X$ , for every  $\lambda > 0$ .

**Lemma 2.6.** [24] Let  $A, B, f, g : X \rightarrow X$  and  $H : X \times X \rightarrow X$  be the single-valued mappings. Let  $M : X \times X \rightarrow 2^X$  be an  $H(\cdot, \cdot)$ -co-accretive mapping with respect to  $A, B, f$  and  $g$ . Let  $A$  be  $\eta$ -expansive and  $B$  be  $\sigma$ -Lipschitz continuous such that  $\alpha > \beta, \mu > \gamma$  and  $\eta > \sigma$ . Then the mapping  $[H(A, B) + \lambda M(f, g)]^{-1}$  is single-valued, for all  $\lambda > 0$ .

**Definition 2.7.** [24] Let  $A, B, f, g : X \rightarrow X$  and  $H : X \times X \rightarrow X$  be the single-valued mappings. Let  $M : X \times X \rightarrow 2^X$  be an  $H(\cdot, \cdot)$ -co-accretive mapping with respect to  $A, B, f$  and  $g$ . The resolvent operator  $R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} : X \rightarrow X$  is defined by

$$R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) = [H(A, B) + \lambda M(f, g)]^{-1}(u), \forall u \in X, \lambda > 0. \quad (2.1)$$

Note that the resolvent operator  $R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$ , defined in (2.1) is  $\theta$ -Lipschitz continuous, where

$$\theta = \frac{1}{\lambda(\alpha - \beta) + (\mu\eta^q - \gamma\sigma^q)}. \quad (2.2)$$

## 3. GENERALIZED YOSIDA APPROXIMATION OPERATORS

In this section, we define the generalized Yosida approximation operator associated to  $H(\cdot, \cdot)$ -co-accretive mappings and discuss some of its properties.

**Definition 3.1.** The generalized Yosida approximation operator  $J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} : X \rightarrow X$  is defined as

$$J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) = \frac{1}{\lambda} \left[ I - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](u), \quad \forall u \in X, \lambda > 0, \quad (3.1)$$

where,  $I$  is the identity mapping on  $X$  and  $R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  is the resolvent operator defined by (2.1).

**Lemma 3.2.** Let  $A, B, f, g : X \rightarrow X$  and  $H : X \times X \rightarrow X$  be the single-valued mappings. Suppose that  $M : X \times X \rightarrow 2^X$  is an  $H(\cdot, \cdot)$ -co-accretive mapping with respect to  $A, B, f$  and  $g$ . Let  $A$  be  $\eta$ -expansive and let  $B$  be  $\sigma$ -Lipschitz continuous such that  $\alpha > \beta, \mu > \gamma$  and  $\eta > \sigma$ . Then the generalized Yosida approximation operator  $J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  defined in (3.1) is

- (i)  $\kappa$ -Lipschitz continuous;
- (ii)  $\varsigma$ -strongly monotone;

where  $\kappa = \frac{1}{\lambda}(1 + \theta)$ ,  $\varsigma = \frac{1}{\lambda}(1 - \theta)$ ,  $\theta = \frac{1}{\lambda(\alpha - \beta) + (\mu\eta^q - \gamma\sigma^q)}$  and  $\lambda > 0$ .

*Proof.* (i). Let  $u, v$  be any given points in  $X$ . It follows from the definition of the generalized Yosida approximation operator and the Lipschitz continuity of resolvent operators that

$$\begin{aligned} \left\| J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right\| &= \frac{1}{\lambda} \left\| \left[ I(u) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) \right] - \left[ I(v) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right] \right\| \\ &\leq \frac{1}{\lambda} \left[ \|u - v\| + \left\| R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right\| \right] \\ &\leq \frac{1}{\lambda} \left[ \|u - v\| + \theta \|u - v\| \right] \\ &= \frac{1}{\lambda} (1 + \theta) \|u - v\|, \end{aligned}$$

i.e.,

$$\left\| J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right\| \leq \kappa \|u - v\|.$$

Thus, generalized Yosida approximation operator  $J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  is  $\kappa$ -Lipschitz continuous.

(ii) Let  $u, v$  be any given points in  $X$ . Using the definition of the generalized Yosida approximation operator, we get

$$\begin{aligned} &\left\langle J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v), J_q(u - v) \right\rangle \\ &= \frac{1}{\lambda} \left\langle \left( I(u) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) \right) - \left( I(v) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right), J_q(u - v) \right\rangle \\ &= \frac{1}{\lambda} \left[ \left\langle u - v, J_q(u - v) \right\rangle - \left\langle R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v), J_q(u - v) \right\rangle \right] \\ &\geq \frac{1}{\lambda} \left[ \|u - v\|^q - \left\| R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v) \right\| \|u - v\|^{q-1} \right]. \end{aligned}$$

Now using the Lipschitz continuity of resolvent operators, we have

$$\begin{aligned} \left\langle J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v), J_q(u - v) \right\rangle &\geq \frac{1}{\lambda} \left[ \|u - v\|^q - \theta \|u - v\|^q \right] \\ &= \frac{1}{\lambda} (1 - \theta) \|u - v\|^q, \end{aligned}$$

i.e.,

$$\left\langle J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(v), J_q(u - v) \right\rangle \geq \varsigma \|u - v\|^q.$$

Thus, generalized Yosida approximation operator  $J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  is  $\varsigma$ -strongly monotone. This completes the proof.  $\square$

#### 4. CONVERGENCE OF THE GENERALIZED YOSIDA APPROXIMATION OPERATOR

In this section, we discuss the convergence of the generalized Yosida approximation operator associated to  $H(\cdot, \cdot)$ -co-accretive mapping. We also illustrate an example to support the convergence result.

Let  $M : X \times X \rightarrow 2^X$  be a multi-valued mapping. The graph of the mapping  $M$  is defined by

$$\text{graph}(M) = \{(x, y), z) : z \in M(x, y)\}.$$

**Definition 4.1.** [24] Let  $A, B, f, g : X \rightarrow X$  and  $H : X \times X \rightarrow X$  be the single-valued mappings. Let  $M_n, M : X \times X \rightarrow 2^X$  be  $H(\cdot, \cdot)$ -co-accretive mappings, for  $n = 0, 1, 2, \dots$ . The sequence  $\{M_n\}$  is said to be graph convergence to  $M$ , denoted by  $M_n \xrightarrow{G} M$ , if for every  $((f(x), g(x)), z) \in \text{graph}(M)$ , there exists a sequence  $\{(f(x_n), g(x_n)), z_n\} \in \text{graph}(M_n)$  such that

$$f(x_n) \rightarrow f(x), g(x_n) \rightarrow g(x) \text{ and } z_n \rightarrow z \text{ as } n \rightarrow \infty.$$

**Theorem 4.2.** [24] Let  $A, B, f, g : X \rightarrow X$  be the single-valued mappings and let  $M_n, M : X \times X \rightarrow 2^X$  be  $H(\cdot, \cdot)$ -co-accretive mappings with respect to  $A, B, f$  and  $g$ . Let  $H : X \times X \rightarrow X$  be a single-valued mapping such that

- (i)  $H(A, B)$  is  $\xi_1$ -Lipschitz continuous with respect to  $A$  and  $\xi_2$ -Lipschitz continuous with respect to  $B$ ;
- (ii)  $f$  is  $\tau$ -expansive.

Then  $M_n \xrightarrow{G} M$ , if and only if

$$R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) \rightarrow R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u), \forall u \in X, \lambda > 0,$$

where

$$R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) = [H(A, B) + \lambda M_n(f, g)]^{-1}(u), \text{ and } R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(u) = [H(A, B) + \lambda M(f, g)]^{-1}(u).$$

In the following theorem, we establish the relationship between the convergence of the generalized Yosida approximation operator and the graph convergence for the  $H(\cdot, \cdot)$ -co-accretive mapping.

**Theorem 4.3.** Let  $A, B, f, g : X \rightarrow X$  be the single-valued mappings and let  $M_n, M : X \times X \rightarrow 2^X$  be  $H(\cdot, \cdot)$ -co-accretive mappings with respect to  $A, B, f$  and  $g$ . Let  $H : X \times X \rightarrow X$  be a single-valued mapping such that the conditions (i) and (ii) of the Theorem 4.2 hold. Then  $M_n \xrightarrow{G} M$ , if and only if

$$J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x), \forall x \in X, \lambda > 0,$$

where

$$J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) = \left[ I - R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](x), J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) = \left[ I - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](x),$$

and  $R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}, R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  are same as defined in Theorem 4.2.

*Proof.* Suppose that  $M_n \underline{G} M$ . For any given  $x \in X$ , let

$$z_n = J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) \text{ and } z = J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x).$$

Then  $z = J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) = \frac{1}{\lambda} \left[ I - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](x)$ . It follows that

$$x - \lambda z = R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) = [H(A, B) + \lambda M(f, g)]^{-1}(x),$$

which implies that

$$\begin{aligned} H(A, B)(x - \lambda z) + \lambda M(f, g)(x - \lambda z) &= x \\ \text{i.e., } \frac{1}{\lambda} [x - H(A, B)(x - \lambda z)] &\in M(f(x - \lambda z), g(x - \lambda z)) \end{aligned}$$

or

$$\left( (f(x - \lambda z), g(x - \lambda z)), \frac{1}{\lambda} (x - H(A(x - \lambda z), B(x - \lambda z))) \right) \in \text{graph}(M).$$

Then by the definition of graph convergence, there exists a sequence  $\left\{ (f(z'_n), g(z'_n)), y'_n \right\} \in \text{graph}(M_n)$  such that

$$f(z'_n) \rightarrow f(x - \lambda z), g(z'_n) \rightarrow g(x - \lambda z) \text{ and } y'_n \rightarrow \frac{1}{\lambda} (x - H(A(x - \lambda z), B(x - \lambda z))) \text{ as } n \rightarrow \infty. \quad (4.1)$$

Since  $y'_n \in M_n(f(z'_n), g(z'_n))$ , we have

$$H(A(z'_n), B(z'_n)) + \lambda y'_n \in [H(A, B) + \lambda M_n(f, g)](z'_n).$$

It follows that

$$\begin{aligned} z'_n &= R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \left[ H(A(z'_n), B(z'_n)) + \lambda y'_n \right] \\ &= \left( I - \lambda J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \right) \left[ H(A(z'_n), B(z'_n)) + \lambda y'_n \right], \end{aligned}$$

which implies that

$$\frac{1}{\lambda} z'_n = \frac{1}{\lambda} H(A(z'_n), B(z'_n)) + y'_n - J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \left[ H(A(z'_n), B(z'_n)) + \lambda y'_n \right].$$

Note that

$$\begin{aligned} \|z_n - z\| &= \left\| J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) - z \right\| \\ &= \left\| J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) + \frac{1}{\lambda} z'_n - \frac{1}{\lambda} z'_n - z \right\| \\ &= \left\| J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) + \frac{1}{\lambda} (H(A(z'_n), B(z'_n))) + y'_n \right. \\ &\quad \left. - J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} [H(A(z'_n), B(z'_n)) + \lambda y'_n] - \frac{1}{\lambda} z'_n - z \right\| \\ &\leq \left\| J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} [H(A(z'_n), B(z'_n)) + \lambda y'_n] \right\| \\ &\quad + \left\| \frac{1}{\lambda} H(A(z'_n), B(z'_n)) + y'_n - \frac{1}{\lambda} z'_n - z \right\|. \end{aligned}$$

Using the Lipschitz continuity of the generalized Yosida approximation operator, we get

$$\begin{aligned}
\|z_n - z\| &\leq \kappa \|x - H(A(z'_n), B(z'_n)) - \lambda y'_n\| + \left\| \frac{1}{\lambda} H(A(z'_n), B(z'_n)) + y'_n - \frac{1}{\lambda} x \right\| \\
&\quad + \left\| \frac{1}{\lambda} z'_n - \frac{1}{\lambda} x + z \right\| \\
&= \left( \kappa + \frac{1}{\lambda} \right) \left\| x - H(A(z'_n), B(z'_n)) - \lambda y'_n \right\| + \frac{1}{\lambda} \|z'_n - x + \lambda z\| \\
&= \left( \kappa + \frac{1}{\lambda} \right) \left\| x - H(A(z'_n), B(z'_n)) + H(A, B)(x - \lambda z) - H(A, B)(x - \lambda z) - \lambda y'_n \right\| \\
&\quad + \frac{1}{\lambda} \|z'_n - x + \lambda z\| \\
&\leq \left( \kappa + \frac{1}{\lambda} \right) \left\| x - H(A, B)(x - \lambda z) - \lambda y'_n \right\| + \left( \kappa + \frac{1}{\lambda} \right) \left\| H(A, B)(x - \lambda z) \right. \\
&\quad \left. - H(A(z'_n), B(z'_n)) \right\| + \frac{1}{\lambda} \|z'_n - x + \lambda z\|.
\end{aligned} \tag{4.2}$$

Since  $H$  is  $\xi_1$ -Lipschitz continuous with respect to  $A$  and  $\xi_2$ -Lipschitz continuous with respect to  $B$ , we have

$$\begin{aligned}
\|H(A, B)(x - \lambda z) - H(A(z'_n), B(z'_n))\| &= \|H(A(x - \lambda z), B(x - \lambda z)) - H(A(z'_n), B(z'_n))\| \\
&\leq \|H(A(x - \lambda z), B(x - \lambda z)) - H(A(x - \lambda z), B(z'_n))\| \\
&\quad + \|H(A(x - \lambda z), B(z'_n)) - H(A(z'_n), B(z'_n))\| \\
&\leq (\xi_1 + \xi_2) \|x - \lambda z - z'_n\|.
\end{aligned} \tag{4.3}$$

Thus, it follows from (4.2) and (4.3) that

$$\begin{aligned}
\|z_n - z\| &\leq \left( \kappa + \frac{1}{\lambda} \right) \left\| x - H(A(x - \lambda z), B(x - \lambda z)) - \lambda y'_n \right\| \\
&\quad + \left[ \left( \kappa + \frac{1}{\lambda} \right) (\xi_1 + \xi_2) + \frac{1}{\lambda} \right] \|x - \lambda z - z'_n\|.
\end{aligned} \tag{4.4}$$

Since  $f$  is  $\tau$ -expansive, we have

$$\|f(z'_n) - f(x - \lambda z)\| \geq \tau \|z'_n - (x - \lambda z)\| \geq 0. \tag{4.5}$$

Since  $f(z'_n) \rightarrow f(x - \lambda z)$  as  $n \rightarrow \infty$ . By (4.5), we have  $z'_n \rightarrow x - \lambda z$  as  $n \rightarrow \infty$ . Also from (4.1), we have  $y'_n \rightarrow \frac{1}{\lambda} \left( x - H(A(x - \lambda z), B(x - \lambda z)) \right)$  as  $n \rightarrow \infty$ . Thus, it follows from (4.4) that  $\|z_n - z\| \rightarrow 0$  as  $n \rightarrow \infty$ , which implies that

$$J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x).$$

Conversely, suppose that

$$J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x), \quad \forall x \in X, \lambda > 0.$$

For any  $((f(x), g(x)), y) \in \text{graph}(M)$ , we have  $y \in M(f(x), g(x))$ , which in turn implies

$$H(A(x), B(x)) + \lambda y \in [H(A, B) + \lambda M(f, g)](x).$$

Hence

$$x = R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}[H(A(x), B(x)) + \lambda y] = [I - \lambda J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}][H(A(x), B(x)) + \lambda y]. \tag{4.6}$$

Letting

$$x_n = [I - \lambda J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}][H(A(x), B(x)) + \lambda y], \tag{4.7}$$

we have

$$\frac{1}{\lambda} [H(A(x), B(x)) - H(A(x_n), B(x_n)) + \lambda y] \in M_n(f(x_n), g(x_n)).$$



Let  $y'_n = \frac{1}{\lambda} [H(A(x), B(x)) - H(A(x_n), B(x_n)) + \lambda y]$ . Note that

$$\begin{aligned} \|y'_n - y\| &= \left\| \frac{1}{\lambda} [H(A(x), B(x)) - H(A(x_n), B(x_n)) + \lambda y] - y \right\| \\ &= \frac{1}{\lambda} \left\| H(A(x), B(x)) - H(A(x_n), B(x_n)) \right\|. \end{aligned}$$

Then by using the same argument as in (4.3), we get

$$\|y'_n - y\| \leq \frac{(\xi_1 + \xi_2)}{\lambda} \|x_n - x\|. \quad (4.8)$$

From (4.6) and (4.7), we have

$$\begin{aligned} \|x_n - x\| &= \left\| \left[ I - \lambda J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \right] [H(A(x), B(x)) + \lambda y] - \left[ I - \lambda J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right] [H(A(x), B(x)) + \lambda y] \right\| \\ &= \lambda \left\| \left[ J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right] [H(A(x), B(x)) + \lambda y] \right\|. \end{aligned}$$

Since  $J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$ , we have  $\|x_n - x\| \rightarrow 0$  as  $n \rightarrow \infty$ . From (4.8), we have  $\|y'_n - y\| \rightarrow 0$  as  $n \rightarrow \infty$ . Hence  $M_n \xrightarrow{G} M$ . This completes the proof.  $\square$

**Remark 4.4.** One can easily verify that the convergence of the resolvent operator  $R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \rightarrow R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  and the convergence of generalized Yosida approximation operator  $J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  are equivalent, if and only if  $M_n \xrightarrow{G} M$ .

**Example 4.5.** Letting  $X = \mathbb{R}^2$ , we define the inner product by

$$\langle (x_1, x_2), (y_1, y_2) \rangle = x_1 y_1 + x_2 y_2, \quad \forall (x_1, x_2), (y_1, y_2) \in \mathbb{R}^2.$$

Let  $A, B : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the mappings defined by

$$A(x_1, x_2) = \left( \frac{x_1}{3}, \frac{x_2}{4} \right), \quad \forall (x_1, x_2) \in \mathbb{R}^2,$$

$$B(x_1, x_2) = \left( -x_1, -\frac{3}{2}x_2 \right), \quad \forall (x_1, x_2) \in \mathbb{R}^2.$$

Let  $H : \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a mapping defined by  $H(A(x), B(x)) = A(x) + B(x)$ ,  $\forall x \in \mathbb{R}^2$ . Then for any  $u \in \mathbb{R}^2$ , we have

$$\begin{aligned} \langle H(A(x), u) - H(A(y), u), x - y \rangle &= \langle A(x) - A(y), x - y \rangle \\ &= \left\langle \left( \frac{1}{3}(x_1 - y_1), \frac{1}{4}(x_2 - y_2) \right), (x_1 - y_1, x_2 - y_2) \right\rangle \\ &= \frac{1}{3}(x_1 - y_1)^2 + \frac{1}{4}(x_2 - y_2)^2, \end{aligned}$$

and

$$\begin{aligned} \|A(x) - A(y)\|^2 &= \langle A(x) - A(y), A(x) - A(y) \rangle \\ &= \left\langle \left( \frac{1}{3}(x_1 - y_1), \frac{1}{4}(x_2 - y_2) \right), \left( \frac{1}{3}(x_1 - y_1), \frac{1}{4}(x_2 - y_2) \right) \right\rangle \\ &= \frac{1}{9}(x_1 - y_1)^2 + \frac{1}{16}(x_2 - y_2)^2, \end{aligned}$$

which imply that

$$\begin{aligned}
\langle H(A(x), u) - H(A(y), u), x - y \rangle &= \frac{1}{3}(x_1 - y_1)^2 + \frac{1}{4}(x_2 - y_2)^2 \\
&= \frac{48(x_1 - y_1)^2 + 36(x_2 - y_2)^2}{144} \\
&= 3 \left[ \frac{16(x_1 - y_1)^2 + 12(x_2 - y_2)^2}{144} \right] \\
&\geq 3 \left[ \frac{16(x_1 - y_1)^2 + 9(x_2 - y_2)^2}{144} \right] \\
&= 3\|A(x) - A(y)\|^2,
\end{aligned}$$

i.e.,

$$\langle H(A(x), u) - H(A(y), u), x - y \rangle \geq 3\|A(x) - A(y)\|^2.$$

Hence,  $H(A, B)$  is 3-cocoercive with respect to  $A$  and

$$\begin{aligned}
\langle H(u, B(x)) - H(u, B(y)), x - y \rangle &= \langle B(x) - B(y), x - y \rangle \\
&= \left\langle \left( -(x_1 - y_1), -\frac{3}{2}(x_2 - y_2) \right), (x_1 - y_1, x_2 - y_2) \right\rangle \\
&= - \left[ (x_1 - y_1)^2 + \frac{3}{2}(x_2 - y_2)^2 \right],
\end{aligned}$$

and

$$\begin{aligned}
\|B(x) - B(y)\|^2 &= \langle B(x) - B(y), B(x) - B(y) \rangle \\
&= \left\langle \left( -(x_1 - y_1), -\frac{3}{2}(x_2 - y_2) \right), \left( -(x_1 - y_1), -\frac{3}{2}(x_2 - y_2) \right) \right\rangle \\
&= (x_1 - y_1)^2 + \frac{9}{4}(x_2 - y_2)^2,
\end{aligned}$$

which imply that

$$\begin{aligned}
\langle H(u, B(x)) - H(u, B(y)), x - y \rangle &= - \left[ (x_1 - y_1)^2 + \frac{3}{2}(x_2 - y_2)^2 \right] \\
&= - \left[ \frac{4(x_1 - y_1)^2 + 6(x_2 - y_2)^2}{4} \right] \\
&\geq - \left[ \frac{4(x_1 - y_1)^2 + 9(x_2 - y_2)^2}{4} \right] \\
&= (-1)\|B(x) - B(y)\|^2,
\end{aligned}$$

i.e.,

$$\langle H(u, B(x)) - H(u, B(y)), x - y \rangle \geq (-1)\|B(x) - B(y)\|^2.$$

Hence,  $H(A, B)$  is 1-relaxed cocoercive with respect to  $B$ . Thus,  $H(A, B)$  is symmetric cocoercive with respect to  $A$  and  $B$ . Now, we show the symmetric accretivity of  $M(f, g)$ . Let  $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the single-valued mappings such that

$$\begin{aligned}
f(x_1, x_2) &= \left( \frac{1}{2}x_1 - x_2, x_1 + \frac{1}{3}x_2 \right), \quad \forall (x_1, x_2) \in \mathbb{R}^2, \\
g(x_1, x_2) &= \left( \frac{1}{3}x_1 + \frac{1}{3}x_2, -\frac{1}{3}x_1 + \frac{1}{4}x_2 \right), \quad \forall (x_1, x_2) \in \mathbb{R}^2.
\end{aligned}$$

Let  $M : \mathbb{R}^2 \times \mathbb{R}^2 \times \rightarrow \mathbb{R}^2$  be a mapping defined by  $M(f(x), g(x)) = f(x) - g(x)$ . Now, for any  $w \in \mathbb{R}^2$ ,

$$\begin{aligned} \langle M(f(x), w) - M(f(y), w), x - y \rangle &= \langle f(x) - f(y), x - y \rangle \\ &= \left\langle \left( \frac{1}{2}(x_1 - y_1) - (x_2 - y_2), (x_1 - y_1) + \frac{1}{3}(x_2 - y_2) \right), \right. \\ &\quad \left. (x_1 - y_1, x_2 - y_2) \right\rangle \\ &= \left[ \frac{1}{2}(x_1 - y_1)^2 + \frac{1}{3}(x_2 - y_2)^2 \right], \end{aligned}$$

and  $\|x - y\|^2 = \langle (x_1 - y_1, x_2 - y_2), (x_1 - y_1, x_2 - y_2) \rangle = (x_1 - y_1)^2 + (x_2 - y_2)^2$ , which imply that

$$\begin{aligned} \langle M(f(x), w) - M(f(y), w), x - y \rangle &= \left[ \frac{1}{2}(x_1 - y_1)^2 + \frac{1}{3}(x_2 - y_2)^2 \right] \\ &\geq \frac{1}{3} \left[ (x_1 - y_1)^2 + (x_2 - y_2)^2 \right] \\ &= \frac{1}{3} \|x - y\|^2, \end{aligned}$$

i.e.,

$$\langle u - v, x - y \rangle \geq \frac{1}{3} \|x - y\|^2, \quad \forall x, y \in \mathbb{R}^2, u \in M(f(x), w) \text{ and } v \in M(f(y), w).$$

Hence,  $M(f, g)$  is  $\frac{1}{3}$ -strongly accretive with respect to  $f$  and

$$\begin{aligned} \langle M(w, g(x)) - M(w, g(y)), x - y \rangle &= -\langle g(x) - g(y), x - y \rangle \\ &= -\left\langle \left( \frac{1}{3}(x_1 - y_1) + \frac{1}{3}(x_2 - y_2), -\frac{1}{3}(x_1 - y_1) \right. \right. \\ &\quad \left. \left. + \frac{1}{4}(x_2 - y_2) \right), (x_1 - y_1, x_2 - y_2) \right\rangle \\ &= -\left[ \frac{1}{3}(x_1 - y_1)^2 + \frac{1}{4}(x_2 - y_2)^2 \right], \end{aligned}$$

and

$$\|x - y\|^2 = \langle (x_1 - y_1, x_2 - y_2), (x_1 - y_1, x_2 - y_2) \rangle = (x_1 - y_1)^2 + (x_2 - y_2)^2,$$

which implies that

$$\begin{aligned} \langle M(w, g(x)) - M(w, g(y)), x - y \rangle &= -\left[ \frac{1}{3}(x_1 - y_1)^2 + \frac{1}{4}(x_2 - y_2)^2 \right] \\ &\geq -\frac{1}{3} \left[ (x_1 - y_1)^2 + (x_2 - y_2)^2 \right] \\ &= -\frac{1}{3} \|x - y\|^2, \end{aligned}$$

i.e.,

$$\langle u - v, x - y \rangle \geq -\frac{1}{3} \|x - y\|^2, \quad \forall x, y \in \mathbb{R}^2, u \in M(w, g(x)) \text{ and } v \in M(w, g(y)).$$

Hence,  $M(f, g)$  is  $\frac{1}{3}$ -relaxed accretive with respect to  $g$ . Thus,  $M(f, g)$  is symmetric accretive with respect to  $f$  and  $g$ . Also for any  $x \in \mathbb{R}^2$ , we have

$$\begin{aligned} [H(A, B) + \lambda M(f, g)](x) &= H(A(x), B(x)) + \lambda M(f(x), g(x)) \\ &= (A(x) + B(x)) + \lambda (f(x) - g(x)) \\ &= \left(-\frac{2}{3}x_1, -\frac{5}{4}x_2\right) + \lambda \left(\frac{1}{6}x_1 - \frac{4}{3}x_2, \frac{4}{3}x_1 + \frac{1}{12}x_2\right) \\ &= \left[\left(\frac{\lambda}{6} - \frac{2}{3}\right)x_1 - \frac{4\lambda}{3}x_2, \frac{4\lambda}{3}x_1 + \left(\frac{\lambda}{12} - \frac{5}{4}\right)x_2\right]. \end{aligned}$$

It can be easily verify that the vector on right hand side generates the whole  $\mathbb{R}^2$ , i.e.,

$$[H(A, B) + \lambda M(f, g)](\mathbb{R}^2) = \mathbb{R}^2, \forall \lambda > 0.$$

Hence,  $M$  is  $H(\cdot, \cdot)$ -co-accretive with respect to  $A, B, f$  and  $g$ .

Now, we show  $M_n \xrightarrow{G} M$ . Let

$$\begin{aligned} f(x_n) &= \left(\frac{1}{2}x_1 - x_2 + \frac{1}{n}, x_1 + \frac{1}{3}x_2 + \frac{2}{n}\right), \\ g(x_n) &= \left(\frac{1}{3}x_1 + \frac{1}{3}x_2 + \frac{1}{n^2}, -\frac{1}{3}x_1 + \frac{1}{4}x_2 + \frac{2}{n^2}\right). \end{aligned}$$

Then

$$y(x_n) = M_n(f(x_n), g(x_n)) = f(x_n) - g(x_n) = \left(\frac{1}{6}x_1 - \frac{4}{3}x_2 + \frac{1}{n} - \frac{1}{n^2}, \frac{4}{3}x_1 + \frac{1}{12}x_2 + \frac{2}{n} - \frac{2}{n^2}\right).$$

Since,

$$\begin{aligned} \lim_{n \rightarrow \infty} f(x_n) &= \lim_{n \rightarrow \infty} \left[\frac{1}{2}x_1 - x_2 + \frac{1}{n}, x_1 + \frac{1}{3}x_2 + \frac{2}{n}\right] = \left(\frac{1}{2}x_1 - x_2, x_1 + \frac{1}{3}x_2\right), \\ \lim_{n \rightarrow \infty} g(x_n) &= \lim_{n \rightarrow \infty} \left[\frac{1}{3}x_1 + \frac{1}{3}x_2 + \frac{1}{n^2}, -\frac{1}{3}x_1 + \frac{1}{4}x_2 + \frac{2}{n^2}\right] = \left(\frac{1}{3}x_1 + \frac{1}{3}x_2, -\frac{1}{3}x_1 + \frac{1}{4}x_2\right). \end{aligned}$$

we have  $\lim_{n \rightarrow \infty} f(x_n) = f(x)$ ,  $\lim_{n \rightarrow \infty} g(x_n) = g(x)$  as  $n \rightarrow \infty$ . Also,

$$\begin{aligned} \lim_{n \rightarrow \infty} y_n &= \lim_{n \rightarrow \infty} \left(\frac{1}{6}x_1 - \frac{4}{3}x_2 + \frac{1}{n} - \frac{1}{n^2}, \frac{4}{3}x_1 + \frac{1}{12}x_2 + \frac{2}{n} - \frac{2}{n^2}\right) \\ &= \left(\frac{1}{6}x_1 - \frac{4}{3}x_2, \frac{4}{3}x_1 + \frac{1}{12}x_2\right) = f(x) - g(x), \end{aligned}$$

which shows that  $\lim_{n \rightarrow \infty} f(x_n) = f(x)$ ,  $\lim_{n \rightarrow \infty} g(x_n) = g(x)$  and  $\lim_{n \rightarrow \infty} y_n \rightarrow y$  as  $n \rightarrow \infty$  and hence,  $M_n \xrightarrow{G} M$  as  $n \rightarrow \infty$ .

Finally, we show that  $J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}$  as  $M_n \xrightarrow{G} M$ . Now for any  $\lambda = 1$ , the resolvent operators are given by

$$\begin{aligned} R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) &= [H(A, B) + \lambda M_n(f, g)]^{-1}(x) \\ &= [(A(x) + B(x)) + (f(x) - g(x))]^{-1}(x), \\ &= \left[\left(-\frac{1}{2}x_1 - \frac{4}{3}x_2 + \frac{1}{n} - \frac{1}{n^2}, \frac{4}{3}x_1 - \frac{7}{6}x_2 + \frac{2}{n} - \frac{2}{n^2}\right)\right]^{-1} \\ &= \frac{1}{85} \left[\left(-42x_1 + 48x_2 - \frac{54}{n} + \frac{54}{n^2}\right), \left(-48x_1 - 18x_2 + \frac{84}{n} - \frac{84}{n^2}\right)\right] \end{aligned}$$

and

$$\begin{aligned}
 R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) &= [H(A, B) + \lambda M(f, g)]^{-1}(x) \\
 &= [(Ax + Bx) + (fx - gx)]^{-1}(x), \\
 &= \left[ \left( -\frac{1}{2}x_1 - \frac{4}{3}x_2, \frac{4}{3}x_1 - \frac{7}{6}x_2 \right) \right]^{-1} \\
 &= \frac{1}{85} \left[ \left( -42x_1 + 48x_2 \right), \left( -48x_1 - 18x_2 \right) \right].
 \end{aligned}$$

For  $\lambda = 1$ , the generalized Yosida approximation operators are given by

$$\begin{aligned}
 J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) &= \frac{1}{\lambda} \left[ I - R_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](x) \\
 &= \left[ x_1 - \frac{1}{85} \left( -42x_1 + 48x_2 - \frac{54}{n} + \frac{54}{n^2} \right), x_2 - \frac{1}{85} \left( -48x_1 - 18x_2 + \frac{84}{n} - \frac{84}{n^2} \right) \right] \\
 &= \frac{1}{85} \left[ \left( 127x_1 - 48x_2 + \frac{54}{n} - \frac{54}{n^2} \right), \left( 48x_1 + 103x_2 - \frac{84}{n} + \frac{84}{n^2} \right) \right]
 \end{aligned}$$

and

$$\begin{aligned}
 J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) &= \frac{1}{\lambda} \left[ I - R_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)} \right](x) \\
 &= \left[ x_1 - \frac{1}{85} \left( -42x_1 + 48x_2 \right), x_2 - \frac{1}{85} \left( -48x_1 - 18x_2 \right) \right] \\
 &= \frac{1}{85} \left[ 127x_1 - 48x_2, 48x_1 + 103x_2 \right],
 \end{aligned}$$

which show that

$$\|J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) - J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x)\| \rightarrow 0, \text{ as } n \rightarrow \infty.$$

Thus, we have

$$J_{\lambda, M_n(\cdot, \cdot)}^{H(\cdot, \cdot)}(x) \rightarrow J_{\lambda, M(\cdot, \cdot)}^{H(\cdot, \cdot)}(x), \text{ as } M_n \xrightarrow{G} M.$$

## 5. A SYSTEM OF THE GENERALIZED YOSIDA INCLUSIONS AND EXISTENCE RESULT

This section begins with the formulation of a system of the generalized Yosida inclusions and we discuss the existence of the unique solution. Let for each  $i = 1, 2$ ;  $X_i$  be a  $q_i$ -uniformly smooth Banach spaces equipped with norms  $\|\cdot\|_i$ . Let  $A_i, B_i, f_i, g_i, P_i : X_i \rightarrow X_i$  and  $N_i, F_i : X_1 \times X_2 \rightarrow X_i$ ;  $H_i : X_i \times X_i \rightarrow X_i$  be the single-valued mappings. Let  $Q_i : X_i \rightarrow 2^{X_i}$  be the multi-valued mappings. Let  $M_1 : X_1 \times X_1 \rightarrow 2^{X_1}$  be an  $H_1(\cdot, \cdot)$ -co-accretive mapping with respect to  $A_1, B_1, f_1$  and  $g_1$  and  $M_2 : X_2 \times X_2 \rightarrow 2^{X_2}$  be an  $H_2(\cdot, \cdot)$ -co-accretive mapping with respect to  $A_2, B_2, f_2$  and  $g_2$ . We consider the following system of the generalized Yosida inclusions (in short: SGYI): Find  $(x, y) \in X_1 \times X_2, u \in Q_1(x), v \in Q_2(y)$  such that

$$\begin{cases} 0 \in J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x) + F_1(P_1(x), v) + M_1(f_1(x), g_1(x)), \\ 0 \in J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y) + F_2(u, P_2(y)) + M_2(f_2(y), g_2(y)). \end{cases} \quad (5.1)$$

### Special Cases:

- (1) If  $J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}, J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)} \equiv 0$ , then SGYI (5.1) coincides with the system of generalized variational inclusions (5.1) of Ahmad *et al.* [24].

- (2) If  $J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}, J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)} \equiv J_{\lambda, M}^{H(\cdot, \cdot)}, F_1, F_2 \equiv 0, f_1, f_2, g_1, g_2 \equiv I$ , the identity mappings and  $M_1(\cdot, \cdot), M_2(\cdot, \cdot) = M(\cdot)$ , then SGYI (5.1) reduces to the following Yosida inclusion problem.

Find  $x \in X$  such that

$$0 \in J_{\lambda, M}^{H(\cdot, \cdot)}(x) + M(x). \quad (5.2)$$

Problem (5.2) was studied in [12].

- (3) If  $J_{\lambda, M}^{H(\cdot, \cdot)} = T$ , where  $T : X \rightarrow X$  is a mapping, then problem (5.2) further reduces to variational inclusion problem (10) of Li and Huang [25].

Note that for suitable choices of mappings involved in the formulation of SGYI (5.1), one can obtain many problems existing in the literature.

**Definition 5.1.** A mapping  $F : X_1 \times X_2 \rightarrow X_i$  is said to be  $(\beta, \gamma)$ -mixed Lipschitz continuous, if there exist constants  $\beta > 0, \gamma > 0$  such that

$$\|F(x_1, y_1) - F(x_2, y_2)\|_i \leq \beta \|x_1 - x_2\|_1 + \gamma \|y_1 - y_2\|_2, \forall x_1, x_2 \in X_1, y_1, y_2 \in X_2. \quad (5.3)$$

**Lemma 5.2.** For any  $(x, y) \in X_1 \times X_2, u \in Q_1(x), v \in Q_2(y); (x, y)$  is a solution of SGYI (5.1), if and only if  $(x, y)$  satisfies

$$\begin{aligned} x &= R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)}[H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)]; \\ y &= R_{\lambda_2, M_2(g_2(\cdot), f_2(\cdot))}^{H_2(\cdot, \cdot)}[H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)], \end{aligned}$$

where  $\lambda_1$  and  $\lambda_2 > 0$  are constants.

*Proof.* One can prove the lemma easily by using the definition of resolvent operators.  $\square$

**Theorem 5.3.** For each  $i = 1, 2$ , let  $X_i$  be a  $q_i$ -uniformly smooth Banach space equipped with norms  $\|\cdot\|_i$ . Let  $A_i, B_i, f_i, g_i : X_i \rightarrow X_i$  be the single-valued mappings such that  $A_i$  be  $\eta_i$ -expansive,  $B_i$  is  $\sigma_i$ -Lipschitz continuous and  $f_i$  is  $\tau_i$ -Lipschitz continuous. Let  $H_i : X_i \times X_i \rightarrow X_i$  be a symmetric cocoercive mapping with respect to  $A_i$  and  $B_i$  with constants  $\mu_i$  and  $\gamma_i$ , respectively and  $(v_i, \delta_i)$ -mixed Lipschitz continuous. Let  $P_i : X_i \rightarrow X_i; N_i : X_1 \times X_2 \rightarrow X_i$  be the single-valued mappings and let  $Q_i : X_i \rightarrow 2^{X_i}$  be  $\mathcal{D}$ -Lipschitz continuous multi-valued mappings with constants  $\lambda_{\mathcal{D}_{Q_i}}$ . Let  $F_1 : X_1 \times X_2 \rightarrow E_1$  be  $\rho_1$ -strongly accretive mapping in the first argument,  $\lambda_{F_1}$ -Lipschitz continuous in the second argument and  $N_{F_1}$ -Lipschitz continuous with respect to  $P_1$  in the first argument and let  $F_2 : X_1 \times X_2 \rightarrow X_2$  be  $\rho_2$ -strongly accretive mapping in the second argument,  $\lambda_{F_2}$ -Lipschitz continuous in the first argument and  $S_{F_2}$ -Lipschitz continuous with respect to  $P_2$  in the second argument. Let  $M_1 : X_1 \times X_1 \rightarrow 2^{X_1}$  be an  $H_1(\cdot, \cdot)$ -co-accretive mapping with respect to  $A_1, B_1, f_1$  and  $g_1$  and  $M_2 : X_2 \times X_2 \rightarrow 2^{X_2}$  be an  $H_2(\cdot, \cdot)$ -co-accretive mapping with respect to  $A_2, B_2, f_2$  and  $g_2$ . Suppose that there exist constants  $\lambda_1, \lambda_2 > 0$  satisfying

$$\begin{cases} k_1 = l_1 + \theta_2 \lambda_2 \lambda_{F_2} \lambda_{D_{Q_1}} + \vartheta_1 \tau_1 < 1; \\ k_2 = l_2 + \theta_1 \lambda_1 \lambda_{F_1} \lambda_{D_{Q_2}} + \vartheta_2 \tau_2 < 1, \end{cases} \quad (5.4)$$

where

$$\begin{aligned} l_1 &= \theta_1 [\sqrt[q_1]{1 - q_1(\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1}) + c_{q_1}(v_1 + \delta_1)^{q_1}} + \sqrt[q_1]{1 - \lambda_1 q_1 \rho_1 + c_{q_1} \lambda_1^{q_1} N_{F_1}^{q_1}} + \lambda_1 m_1]; \\ l_2 &= \theta_2 [\sqrt[q_2]{1 - q_2(\mu_2 \eta_2^{q_2} - \gamma_2 \sigma_2^{q_2}) + c_{q_2}(v_2 + \delta_2)^{q_2}} + \sqrt[q_2]{1 - \lambda_2 q_2 \rho_2 + c_{q_2} \lambda_2^{q_2} S_{F_2}^{q_2}} + \lambda_2 m_2]; \\ \theta_1 &= \frac{1}{\lambda_1(\alpha_1 - \beta_1) + (\mu_1 \eta_1^q - \gamma_1 \sigma_1^q)}; \theta_2 = \frac{1}{\lambda_2(\alpha_2 - \beta_2) + (\mu_2 \eta_2^q - \gamma_2 \sigma_2^q)}; \end{aligned}$$

and  $m_1 = \frac{1}{\lambda}(1 + \theta_1)$ ,  $m_2 = \frac{1}{\lambda}(1 + \theta_2)$ . In addition, the following conditions hold

$$\|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x)\| \leq \vartheta_2 \|f_2(y_1) - f_2(y_2)\|_2, \quad (5.5)$$

$$\|J_{\lambda_2, N_2(f_1(x_1), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y) - J_{\lambda_2, N_2(f_1(x_2), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)\| \leq \vartheta_1 \|f_1(x_1) - f_1(x_2)\|_1 \quad (5.6)$$

Then SGYI (5.1) has a unique solution.

*Proof.* It is clear from (2.2) and Lemma 3.2 that resolvent operators  $R_{\lambda_1, M_1(\cdot, \cdot)}^{H_1(\cdot, \cdot)}$  and  $R_{\lambda_2, M_2(\cdot, \cdot)}^{H_2(\cdot, \cdot)}$  are  $\theta_1$  and  $\theta_2$ -Lipschitz continuous, respectively and generalized Yosida approximation operators  $J_{\lambda_1, M_1(\cdot, \cdot)}^{H_1(\cdot, \cdot)}$  and  $J_{\lambda_2, M_2(\cdot, \cdot)}^{H_2(\cdot, \cdot)}$  are  $\kappa_1$  and  $\kappa_2$ -Lipschitz continuous, respectively, where

$$\theta_1 = \frac{1}{\lambda_1(\alpha_1 - \beta_1) + (\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1})},$$

$$\theta_2 = \frac{1}{\lambda_2(\alpha_2 - \beta_2) + (\mu_2 \eta_2^{q_2} - \gamma_2 \sigma_2^{q_2})}$$

and  $\kappa_1 = \frac{1}{\lambda_1}(1 + \theta_1)$ ,  $\kappa_2 = \frac{1}{\lambda_2}(1 + \theta_2)$ .

Next, we define a mapping  $T : X_1 \times X_2 \rightarrow X_1 \times X_2$  by

$$T(x, y) = (N(x, y), S(x, y)), \forall (x, y) \in X_1 \times X_2, \quad (5.7)$$

where  $N : X_1 \times X_2 \rightarrow X_1$ ,  $S : X_1 \times X_2 \rightarrow X_2$  are the single-valued mappings defined by

$$N(x, y) = R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)}[H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)], \lambda_1 > 0, \quad (5.8)$$

$$S(x, y) = R_{\lambda_2, M_2(g_2(\cdot), f_2(\cdot))}^{H_2(\cdot, \cdot)}[H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)], \lambda_2 > 0. \quad (5.9)$$

Using (5.8) and Lipschitz continuity of resolvent operator  $R_{\lambda_1, M_1(\cdot, \cdot)}^{H_1(\cdot, \cdot)}$ , we have

$$\begin{aligned} & \|N(x_1, y_1) - N(x_2, y_2)\|_1 \\ &= \|R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)}[H_1(A_1(x_1), B_1(x_1)) - \lambda_1 F_1(P_1(x_1), v_1) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1)] \\ &\quad - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)}[H_1(A_1(x_2), B_1(x_2)) - \lambda_1 F_1(P_1(x_2), v_2) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)]\|_1 \\ &\leq \theta_1 \|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)) - \lambda_1 (F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1))\|_1 \\ &\quad + \theta_1 \lambda_1 \|F_1(P_1(x_2), v_1) - F_1(P_1(x_2), v_2)\|_1 \\ &\quad + \theta_1 \lambda_1 \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)\| \\ &\leq \theta_1 [\|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)) - (x_1 - x_2)\|_1 \\ &\quad + \|(x_1 - x_2) - \lambda_1 (F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1))\|_1] \\ &\quad + \theta_1 \lambda_1 \|F_1(P_1(x_2), v_1) - F_1(P_1(x_2), v_2)\|_1 \\ &\quad + \theta_1 \lambda_1 \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)\|. \end{aligned} \quad (5.10)$$

It follows from Lemma 2.1, symmetric cocoercivity and  $(v_1, \delta_1)$ -mixed Lipschitz continuity of  $H_1$  that

$$\begin{aligned} & \|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)) - (x_1 - x_2)\|_1^{q_1} \\ &\leq \|x_1 - x_2\|_1^{q_1} - q_1 \langle H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)), \\ &\quad J_{q_1}(x_1 - x_2) \rangle_1 + c_{q_1} \|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2))\|_1^{q_1} \\ &\leq \|x_1 - x_2\|_1^{q_1} - q_1 (\mu_1 \|A_1(x_1) - A_1(x_2)\|_1^{q_1} \\ &\quad - \gamma_1 \|B_1(x_1) - B_1(x_2)\|_1^{q_1}) + c_{q_1} (v_1 + \delta_1)^{q_1} \|x_1 - x_2\|_1^{q_1}. \end{aligned} \quad (5.11)$$

Since  $A_1$  is  $\eta_1$ -expansive and  $B_1$  is  $\sigma_1$ -Lipschitz continuous, we have

$$\begin{aligned} & \|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)) - (x_1 - x_2)\|_1^{q_1} \\ & \leq [1 - q_1(\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1}) + c_{q_1}(v_1 + \delta_1)^{q_1}] \|x_1 - x_2\|_1^{q_1}, \end{aligned}$$

which implies that

$$\begin{aligned} & \|H_1(A_1(x_1), B_1(x_1)) - H_1(A_1(x_2), B_1(x_2)) - (x_1 - x_2)\|_1 \\ & \leq \sqrt[q_1]{1 - q_1(\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1}) + c_{q_1}(v_1 + \delta_1)^{q_1}} \|x_1 - x_2\|_1. \end{aligned} \quad (5.12)$$

Since  $F_1$  is  $\rho_1$ -strongly accretive and  $N_{F_1}$ -Lipschitz continuous with respect to  $P_1$  in the first argument, we find from Lemma 2.1 that

$$\begin{aligned} & \|(x_1 - x_2) - \lambda_1(F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1))\|_1^{q_1} \\ & \leq \|x_1 - x_2\|_1^{q_1} - \lambda_1 q_1 \langle F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1), \\ & \quad J_{q_1}(x_1 - x_2) \rangle_1 + c_{q_1} \lambda_1^{q_1} \|F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1)\|_1^{q_1} \\ & \leq (1 - \lambda_1 q_1 \rho_1 + c_{q_1} \lambda_1^{q_1} N_{F_1}^{q_1}) \|x_1 - x_2\|_1^{q_1}, \end{aligned} \quad (5.13)$$

which implies that

$$\|(x_1 - x_2) - \lambda_1(F_1(P_1(x_1), v_1) - F_1(P_1(x_2), v_1))\|_1 \leq \sqrt[q_1]{1 - \lambda_1 q_1 \rho_1 + c_{q_1} \lambda_1^{q_1} N_{F_1}^{q_1}} \|x_1 - x_2\|_1. \quad (5.14)$$

Also,  $F_1$  is  $\lambda_{F_1}$ -Lipschitz continuous in the second argument and  $Q_2$  is  $\mathcal{D}$ -Lipschitz continuous with constant  $\lambda_{D_{Q_2}}$ , we have

$$\begin{aligned} \|F_1(P_1(x_2), v_1) - F_1(P_1(x_2), v_2)\|_1 & \leq \lambda_{F_1} \|v_1 - v_2\| \leq \lambda_{F_1} \mathcal{D}(Q_2(y_1), Q_2(y_2)) \\ & \leq \lambda_{F_1} \lambda_{D_{Q_2}} \|y_1 - y_2\|_2. \end{aligned} \quad (5.15)$$

Using the Lipschitz continuity of  $J_{\lambda_1, N_1(\cdot, \cdot)}^{H_1(\cdot, \cdot)}$ , condition (5.5) and  $\tau_2$ -Lipschitz continuity of  $f_2$ , we have

$$\begin{aligned} & \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)\|_1 \\ & = \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_2) \\ & \quad + J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)\|_1 \\ & \leq \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_2)\|_1 \\ & \quad + \|J_{\lambda_1, N_1(g_1(\cdot), f_2(y_1))}^{H_1(\cdot, \cdot)}(x_1) - J_{\lambda_1, N_1(g_1(\cdot), f_2(y_2))}^{H_1(\cdot, \cdot)}(x_2)\|_1 \\ & \leq \kappa_1 \|x_1 - x_2\|_1 + \vartheta_2 \|f_2(y_1) - f_2(y_2)\|_2 \\ & \leq \kappa_1 \|x_1 - x_2\|_1 + \vartheta_2 \tau_2 \|y_1 - y_2\|_2. \end{aligned} \quad (5.16)$$

Using (5.12), (5.14), (5.15) and (5.16), (5.10) becomes

$$\begin{aligned} \|N(x_1, y_1) - N(x_2, y_2)\|_1 & \leq \theta_1 [\sqrt[q_1]{1 - q_1(\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1}) + c_{q_1}(v_1 + \delta_1)^{q_1}} \\ & \quad + \sqrt[q_1]{1 - \lambda_1 q_1 \rho_1 + c_{q_1} \lambda_1^{q_1} N_{F_1}^{q_1} + \lambda_1 \kappa_1}] \|x_1 - x_2\|_1 \\ & \quad + [\theta_1 \lambda_1 \lambda_{F_1} \lambda_{D_{Q_2}} + \vartheta_2 \tau_2] \|y_1 - y_2\|_2. \end{aligned} \quad (5.17)$$



Now, using (5.9) and Lipschitz continuity of resolvent operator  $R_{\lambda_2, M_2(\cdot, \cdot)}^{H_2(\cdot, \cdot)}$ , we have

$$\begin{aligned}
& \|S(x_1, y_1) - S(x_2, y_2)\|_2 \\
&= \|R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)}[H_2(A_2(y_1), B_2(y_1)) - \lambda_2 F_2(u_1, P_2(y_1)) - \lambda_2 J_{\lambda_2, N_2(f_1(x_1), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_1)] \\
&\quad - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)}[H_2(A_2(y_2), B_2(y_2)) - \lambda_2 F_2(u_2, P_2(y_2)) - \lambda_2 J_{\lambda_2, N_2(f_1(x_2), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_2)]\|_2 \\
&\leq \theta_2 \|H_2(A_2(y_1), B_2(y_1)) - H_2(A_2(y_2), B_2(y_2)) - \lambda_2 (F_2(u_1, P_2(y_1)) - F_2(u_1, P_2(y_2)))\|_2 \\
&\quad + \theta_2 \lambda_2 \|F_2(u_1, P_2(y_2)) - F_2(u_2, P_2(y_2))\|_2 \\
&\quad + \theta_2 \lambda_2 \|J_{\lambda_2, N_2(f_1(x_1), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_1) - J_{\lambda_2, N_2(f_1(x_2), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_2)\|_2 \\
&\leq \theta_2 [\|H_2(A_2(y_1), B_2(y_1)) - H_2(A_2(y_2), B_2(y_2)) - (y_1 - y_2)\|_2 \\
&\quad + \|(y_1 - y_2) - \lambda_2 (F_2(u_1, P_2(y_1)) - F_2(u_1, P_2(y_2)))\|_2] \\
&\quad + \theta_2 \lambda_2 \|F_2(u_1, P_2(y_2)) - F_2(u_2, P_2(y_2))\|_2 \\
&\quad + \theta_2 \lambda_2 \|J_{\lambda_2, N_2(f_1(x_1), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_1) - J_{\lambda_2, N_2(f_1(x_2), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_2)\|_2
\end{aligned} \tag{5.18}$$

Using the same arguments (5.11)-(5.16) as used for mapping  $N$ , we have

$$\begin{aligned}
\|S(x_1, y_1) - S(x_2, y_2)\|_2 &\leq \theta_2 [\sqrt[q_2]{1 - q_2(\mu_2 \eta_2^{q_2} - \gamma_2 \sigma_2^{q_2}) + c_{q_2}(v_2 + \delta_2)^{q_2}} \\
&\quad + \sqrt[q_2]{1 - \lambda_2 q_2 \rho_2 + c_{q_2} \lambda_2^{q_2} S_{F_2}^{q_2} + \lambda_2 \kappa_2}] \|y_1 - y_2\|_2 \\
&\quad + [\theta_2 \lambda_2 \lambda_{F_2} \lambda_{D_{Q_1}} + \vartheta_1 \tau_1] \|x_1 - x_2\|_1.
\end{aligned} \tag{5.19}$$

It follows from (5.17) and (5.19) that

$$\begin{aligned}
\|N(x_1, y_1) - N(x_2, y_2)\|_1 &+ \|S(x_1, y_1) - S(x_2, y_2)\|_2 \\
&\leq k_1 \|x_1 - x_2\|_1 + k_2 \|y_1 - y_2\|_2 \\
&\leq \max \{k_1, k_2\} (\|x_1 - x_2\|_1 + \|y_1 - y_2\|_2),
\end{aligned} \tag{5.20}$$

where

$$\begin{cases} k_1 = l_1 + \theta_2 \lambda_2 \lambda_{F_2} \lambda_{D_{Q_1}} + \vartheta_1 \tau_1; \\ k_2 = l_2 + \theta_1 \lambda_1 \lambda_{F_1} \lambda_{D_{Q_2}} + \vartheta_2 \tau_2, \end{cases} \tag{5.21}$$

and

$$\begin{aligned}
l_1 &= \theta_1 [\sqrt[q_1]{1 - q_1(\mu_1 \eta_1^{q_1} - \gamma_1 \sigma_1^{q_1}) + c_{q_1}(v_1 + \delta_1)^{q_1}} + \sqrt[q_1]{1 - \lambda_1 q_1 \rho_1 + c_{q_1} \lambda_1^{q_1} N_{F_1}^{q_1} + \lambda_1 \kappa_1}]; \\
l_2 &= \theta_2 [\sqrt[q_2]{1 - q_2(\mu_2 \eta_2^{q_2} - \gamma_2 \sigma_2^{q_2}) + c_{q_2}(v_2 + \delta_2)^{q_2}} + \sqrt[q_2]{1 - \lambda_2 q_2 \rho_2 + c_{q_2} \lambda_2^{q_2} S_{F_2}^{q_2} + \lambda_2 \kappa_2}].
\end{aligned}$$

Now, we define a norm  $\|\cdot\|_*$  on  $X_1 \times X_2$  by

$$\|(x, y)\|_* = \|x\|_1 + \|y\|_2, \quad \forall (x, y) \in X_1 \times X_2. \tag{5.22}$$

It is easy to see that  $(X_1 \times X_2, \|\cdot\|_*)$  is a Banach space. Hence, from (5.7), (5.20) and (5.22), we have

$$\|T(x_1, y_1) - T(x_2, y_2)\|_* \leq \max \{k_1, k_2\} \|(x_1, y_1) - (x_2, y_2)\|_*. \tag{5.23}$$

Since  $\max \{k_1, k_2\} < 1$  by condition (5.4), we find from (5.23) that  $T$  is a contraction mapping. Hence by Banach Contraction mapping Principle, there exists a unique point  $(x, y) \in X_1 \times X_2$  such that

$$T(x, y) = (x, y).$$

Thus, we have

$$\begin{aligned}
x &= R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)}[H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)], \\
y &= R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)}[H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)].
\end{aligned}$$

Hence by Lemma 5.2,  $(x, y)$  is a unique solution of SGYI (5.1). This completes the proof.  $\square$

Next, we suggest the following iterative algorithm to discuss the convergence analysis of SGYI (5.1).

**Algorithm 5.4.** For any  $(x_0, y_0) \in X_1 \times X_2$ , compute the sequence  $\{(x_n, y_n)\} \in X_1 \times X_2$  by the following iterative scheme:

$$x_{n+1} = R_{\lambda_1, M_{1n}(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)]; \quad (5.24)$$

$$y_{n+1} = R_{\lambda_2, M_{2n}(g_2(\cdot), f_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)], \quad (5.25)$$

where  $n = 0, 1, 2, \dots$ ;  $\lambda_1, \lambda_2 > 0$  are constants.

**Theorem 5.5.** Let, for each  $i = 1, 2$ ,  $X_i$  be a  $q_i$ -uniformly smooth Banach spaces. Let the mappings  $A_i$ ,  $B_i$ ,  $f_i$ ,  $g_i$ ,  $H_i$ ,  $F_i$ ,  $P_i$ ,  $Q_i$ ,  $N_i$  and  $M_i$  be same as in Theorem 5.3. Let  $M_{in} : X_i \times X_i \rightarrow 2^{X_i}$  be  $H_i(\cdot, \cdot)$ -co-accretive mappings and  $N_{in} : X_1 \times X_2 \rightarrow X_i$  be the single-valued mappings such that  $M_{in} \xrightarrow{G} M_i$  and the condition (5.4) holds. Then the approximate solution  $(x_n, y_n)$  generated by Algorithm 5.4 converges strongly to unique solution  $(x, y)$  of SGVI (5.1).

*Proof.* It follows from Algorithm 5.4 and Theorem 5.3 that

$$\begin{aligned} & \|x_{n+1} - x\|_1 \\ &= \|R_{\lambda_1, M_{1n}(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)] \\ &\quad - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)]\|_1 \\ &\leq \|R_{\lambda_1, M_{1n}(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)] \\ &\quad - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)]\|_1 \\ &\quad + \|R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)] \\ &\quad - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)]\|_1 \\ &\leq a_n + \|R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)] \\ &\quad - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_1(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)]\|_1, \end{aligned} \quad (5.26)$$

where

$$\begin{aligned} a_n = & \|R_{\lambda_1, M_{1n}(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)] \\ & - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y_n))}^{H_1(\cdot, \cdot)}(x_n)]\|_1 \end{aligned} \quad (5.27)$$

and

$$\begin{aligned} & \|y_{n+1} - y\|_2 \\ &= \|R_{\lambda_2, M_{2n}(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] \\ &\quad - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)]\|_2 \\ &\leq \|R_{\lambda_2, M_{2n}(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] \\ &\quad - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)]\|_2 \\ &\quad + \|R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] \\ &\quad - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)]\|_2 \\ &\leq b_n + \|R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] \\ &\quad - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_2(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)]\|_2, \end{aligned} \quad (5.28)$$

where

$$b_n = \left\| R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x_n), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] \right\|_2. \quad (5.29)$$

By using similar arguments from (5.10)-(5.17), we obtain that

$$\begin{aligned} & \left\| R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x_n), B_1(x_n)) - \lambda_1 F_1(P_1(x_n), v_n) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x_n)] - R_{\lambda_1, M_1(g_1(\cdot), f_1(\cdot))}^{H_1(\cdot, \cdot)} [H_1(A_1(x), B_1(x)) - \lambda_1 F_1(P_1(x), v) - \lambda_1 J_{\lambda_1, N_{1n}(g_1(\cdot), f_2(y))}^{H_1(\cdot, \cdot)}(x)] \right\|_1, \\ & \leq l_1 \|x_n - x\|_1 + [\theta_1 \lambda_1 \lambda_{F_1} \lambda_{D_{Q_2}} + \vartheta_2 \tau_2] \|y_n - y\|_2. \end{aligned} \quad (5.30)$$

Also using the same arguments from (5.18)-(5.19), we have

$$\begin{aligned} & \left\| R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y_n), B_2(y_n)) - \lambda_2 F_2(u_n, P_2(y_n)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y_n)] - R_{\lambda_2, M_2(f_2(\cdot), g_2(\cdot))}^{H_2(\cdot, \cdot)} [H_2(A_2(y), B_2(y)) - \lambda_2 F_2(u, P_2(y)) - \lambda_2 J_{\lambda_2, N_{2n}(f_1(x), g_2(\cdot))}^{H_2(\cdot, \cdot)}(y)] \right\|_2 \\ & \leq l_2 \|y_n - y\|_2 + [\theta_2 \lambda_2 \lambda_{F_2} \lambda_{D_{Q_1}} + \vartheta_1 \tau_1] \|x_n - x\|_1. \end{aligned} \quad (5.31)$$

From (5.26)-(5.31), we have

$$\begin{aligned} \|x_{n+1} - x\|_1 + \|y_{n+1} - y\|_2 & \leq k_1 \|x_n - x\|_1 + k_2 \|y_n - y\|_2 + a_n + b_n \\ & \leq \max \{k_1, k_2\} (\|x_n - x\|_1 + \|y_n - y\|_2) + a_n + b_n. \end{aligned} \quad (5.32)$$

Since  $(X_1 \times X_2, \|\cdot\|_*)$  is a Banach space as defined by (5.22), we have

$$\begin{aligned} \|(x_{n+1}, y_{n+1}) - (x, y)\|_* & = \|(x_{n+1} - x, y_{n+1} - y)\|_* = \|x_{n+1} - x\|_1 + \|y_{n+1} - y\|_2 \\ & \leq \max \{k_1, k_2\} (\|(x_n, y_n) - (x, y)\|_*) + a_n + b_n. \end{aligned} \quad (5.33)$$

It follows from (5.27), (5.29) and Theorem 4.2 that

$$a_n, b_n \rightarrow 0, \text{ as } n \rightarrow \infty. \quad (5.34)$$

Thus, from (5.4), (5.32), (5.33) and (5.34), one has

$$\|(x_{n+1}, y_{n+1}) - (x, y)\|_* \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Hence  $\{(x_n, y_n)\}$  converges strongly to the unique solution  $(x, y)$  of SGYI (5.1). This completes the proof.  $\square$

### Acknowledgements

The authors are very grateful to the anonymous referees for their valuable comments. The first author was partially supported by the DSR, Islamic University of Madinah, KSA. The second author was partially supported by the Natural Science Foundation of China (Grant No.11401487). The third author was partially supported by the DSR, University of Tabuk, KSA.

### REFERENCES

- [1] A. Moudafi, A Duality algorithm for solving general variational inclusions, Adv. Model. Optim. 13 (2011), 213-220.
- [2] A. Moudafi, The asymptotic behavior of an inertial alternating proximal algorithm for monotone inclusions. Appl. Math. Lett. 23 (2010), 620-624.
- [3] B.A. Bin Dehaish, A. Latif, H.O. Bakodah, X. Qin, Weak and strong convergence of algorithms for the sum of two accretive operators with applications, J. Nonlinear Convex Anal. 16 (2015), 1321-1336.

- [4] Y.P. Fang, N. J. Huang,  $H$ -Monotone operator and resolvent operator technique for variational inclusions, Appl. Math. Comput. 145 (2003), 795-803.
- [5] S.Y. Cho, B.A. Bin Dehaish, X. Qin, Weak convergence of a splitting algorithm in Hilbert spaces, J. Appl. Anal. Comput. 7 (2017), 427-438.
- [6] S.Y. Cho, X. Qin, L. Wang, Strong convergence of a splitting algorithm for treating monotone operators, Fixed Point Theory Appl. 2014 (2014), Article ID 94.
- [7] E. Zeidler, Nonlinear functional analysis and its applications, Nonlinear Monotone Operators, Springer, IIB, (1990).
- [8] E.H. Zarantonello, Solving functional equations by contractive averaging, Tech. Report 160, Math. Res. Center U.S. Army, Madison, University of Wisconsin, June 1960.
- [9] G.J. Minty, Monotone (nonlinear) operators in Hilbert space, Duke Math. J. 29 (1962), 341-346.
- [10] H.Y. Lan, Generalized Yosida approximations based on relatively  $A$ -maximal  $m$ -relaxed monotonicity frameworks, Abstr. Appl. Anal. (2013), article ID 157190.
- [11] X. Qin, S.Y. Cho, L. Wang, A regularization method for treating zero points of the sum of two monotone operators, Fixed Point Theory Appl. 2014 (2014), Article ID 75.
- [12] R. Ahmad, M. Ishtyak, M. Rahaman, I. Ahmad, Graph convergence and generalized Yosida approximation operator with an application, Math Sci. 11 (2017), 155-163.
- [13] H.W. Cao, Yosida approximation equations technique for system of generalized set-valued variational inclusions, J. Inequal. Appl. 2013 (2013), Article ID 455.
- [14] L.C. Ceng, C.F. Wen, Y. Yao, Iteration approaches to hierarchical variational inequalities for infinite nonexpansive mappings and finding zero points of  $m$ -accretive operators, J. Nonlinear Var. Anal. 1 (2017), 213-235.
- [15] X. Qin, A. Petrusel, J.C. Yao, CQ iterative algorithms for fixed points of nonexpansive mappings and split feasibility problems in Hilbert spaces, J. Nonlinear Convex Anal. 19 (2018), 251-264.
- [16] X. Qin, J.C. Yao, Weak convergence of a Mann-like algorithm for nonexpansive and accretive operators, J. Inequal. Appl. 2016 (2016), Article ID 232.
- [17] J.R. Graef, J. Henderson, A. Ouahab, Some Krasnoselskii type random fixed point theorems, J. Nonlinear Funct. Anal. 2017 (2017), Article ID 46.
- [18] L. Wei, Y.C. Ba, R.P. Agarwal, New ergodic convergence theorems for nonexpansive mappings and  $m$ -accretive mappings, J. Inequal. Appl. 2016 (2016), Article ID 22.
- [19] L.C. Zeng, S.M. Guu, J.C. Yao, Characterization of  $H$ -monotone operators with applications to variational inclusions, Comput. Math. Appl. 50 (2005), 329-337.
- [20] J.-P. Penot, R. Ratsimahalo, On the Yosida approximaton of operators, Proc. Royal Soc. Edinb. Math. 131 (2001), 945-966.
- [21] Y. Yu, Convergence analysis of a Halpern type algorithm for accretive operators, Nonlinear Anal. 75 (2012), 5027-5031.
- [22] X. Qin, J.C. Yao, Projection splitting algorithms for nonself operators, J. Nonlinear Convex Anal. 18 (2017), 925-935.
- [23] H.K. Xu, Inequalities in Banach spaces with applications, Nonlinear Anal. 16 (1991), 1127-1138.
- [24] R. Ahmad, M. Akram, M. Dilshad, Graph Convergence for the  $H(\cdot, \cdot)$ -co-accretive mapping with an application, Bull. Malays. Math. Sci. Soc. 38 (2015), 1481-1506.
- [25] X. Li, N.J. Huang, Graph convergence for the  $H(\cdot, \cdot)$ -accretive operator in Banach spaces with an application, Appl. Math. Comput. 217 (2011), 9053-9061.