



## ON POSITIVE SOLUTIONS FOR A SECOND ORDER ORDINARY DIFFERENTIAL SYSTEM

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**Abstract.** By using the fixed point index theory, we study the existence and multiplicity of positive solutions for a second order ordinary differential system.

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### 1. INTRODUCTION

This paper deals with the existence of positive solutions of nonlinear differential system

$$\begin{cases} -u'' + bu = \phi u + f(t, u, \phi), & 0 < t < 1, \\ -\phi'' = \mu u, & 0 < t < 1, \\ u(0) = u(1) = \phi(0) = \phi(1) = 0, \end{cases} \quad (1.1)$$

where  $b, \mu > 0$  and  $f : [0, 1] \times \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous.

During the last few decades, the second order elliptic systems

$$\begin{cases} -\Delta u + bu = \phi u + f(u), & x \in \Omega, \\ -\Delta \phi = \mu u, & x \in \Omega, \\ u = \phi = 0, & x \in \partial\Omega \end{cases}$$

have been widely investigated because they have a lot of applications in quantum mechanics models [1, 2], semiconductor theory [3] or a time and space-dependent mathematical model of nuclear reactors

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in a closed container [4]. Recently, Gu and Wang [5] proved the existence of positive solutions of the following elliptic system

$$\begin{cases} -\Delta u + bu = \phi u, & x \in \Omega, \\ -\Delta \phi = u, & x \in \Omega, \\ u = \phi = 0, & x \in \partial\Omega \end{cases} \quad (1.2)$$

by using the abstract fixed point theorem. In addition, they also proved that every positive stationary solution of (1.2) is a threshold when  $\Omega \in R^N$  ( $2 \leq N < 6$ ) is a ball. In 2011, Wang and An [6] investigated the existence of positive solutions of the following one-dimensional system

$$\begin{cases} -u'' + bu = \phi u + f(t, u), & 0 < t < 1, \\ -\phi'' = \mu u, & 0 < t < 1, \\ u(0) = u(1) = \phi(0) = \phi(1) = 0. \end{cases} \quad (1.3)$$

By using Krasnosel'skii's fixed point theorem, they provided sufficient conditions for the existence of at least one positive solution to the BVP (1.3). In 2012, Chen and Ma [7] applied the bifurcation techniques to study the existence of solutions for (1.3). They also established some existence results for the BVP

$$\begin{cases} -\Delta u + bu = \phi u + f(|x|, u), & R_1 < |x| < R_2, x \in R^N, N \geq 1, \\ -\Delta \phi = \mu u, & R_1 < |x| < R_2, x \in R^N, N \geq 1, \\ u = \phi = 0, & \text{on } |x| = R_1, |x| = R_2 \end{cases}$$

by using bifurcation techniques. Recently, Wang and An [8] considered the existence of positive solutions for a second order differential system

$$\begin{cases} -u'' = a(t)\phi u + h(t)f(u), & 0 < t < 1, \\ -\phi'' = b(t)u, & 0 < t < 1, \\ u(0) = u(1) = \phi(0) = \phi(1) = 0, \end{cases}$$

where  $a(t)$ ,  $b(t)$ ,  $h(t)$  may change sign. By using the Krasnosel'skii's fixed point theorem, they obtained sufficient conditions that guarantee the existence of at least one positive solution.

In above results, one of the common techniques is the Green function, and the solution of the boundary value problem

$$-\phi'' = \mu u, \quad \phi(0) = \phi(1) = 0$$

can be expressed as

$$\phi(t) = \mu \int_0^1 G(t, s)u(s)ds. \quad (1.4)$$

Then, inserting (1.4) into the first equation of (1.3), we get a second-order nonlocal boundary value problem

$$\begin{cases} -u'' + \lambda u = \mu u \int_0^1 G(t, s)u(s)ds + f(t, u), & 0 < t < 1, \\ u(0) = u(1) = 0. \end{cases}$$

But, if we insert the second equation (1.1) into the first equation of (1.1), then we can obtain a fourth-order boundary value problem

$$\begin{cases} \phi^{(4)} - b\phi'' = -\phi\phi'' + \mu f(t, \phi, \frac{-\phi''}{\mu}), & 0 < t < 1, \\ \phi(0) = \phi(1) = 0, \phi''(0) = \phi''(1) = 0. \end{cases} \quad (1.5)$$

To the best of our knowledge, the existence and multiplicity of nontrivial solutions for the fourth-order differential equation

$$u^{(4)} = f(t, u, u', u'', u''')$$

with various boundary conditions have been widely studied by using variational methods, the method of upper and lower solutions, fixed point theorems, the alternative principle of Leray-Schauder or the topological degree theory. We refer the readers to [9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24] and the references therein. For fourth-order BVP (1.5), there are few literatures on the existence of positive solutions. In this paper, we apply the fixed point index theory in a cone to discuss the existence and multiplicity of positive solutions of the fourth-order BVP (1.5). Compared to the results in the previous works, our results presented in this paper has the following new features. First, we find some new conditions, which differ from those in the majority of results as we know. Second, the results we are going to present reveal how the behavior of the functions  $\phi\phi''$  and  $f$  have a profound effect on the existence and multiplicity of positive solutions of (1.5) under some appropriate conditions.

## 2. PRELIMINARIES

Let  $G(t, s)$  be the Green function of linear boundary value problem

$$-u'' + \lambda u = 0, \quad u(0) = u(1) = 0,$$

where  $\lambda > -\pi^2$ .

**Lemma 2.1.** [15] *Let  $\omega = \sqrt{|\lambda|}$ . Then  $G(t, s)$  can be expressed by*

$$\begin{aligned} (i) \quad G(t, s) &= \begin{cases} \frac{\sinh \omega t \sinh \omega(1-s)}{\omega \sinh \omega}, & 0 \leq t \leq s \leq 1, \\ \frac{\sinh \omega s \sinh \omega(1-t)}{\omega \sinh \omega}, & 0 \leq s \leq t \leq 1, \end{cases} \quad \text{if } \lambda > 0, \\ (ii) \quad G(t, s) &= \begin{cases} t(1-s), & 0 \leq t \leq s \leq 1, \\ s(1-t), & 0 \leq s \leq t \leq 1, \end{cases} \quad \text{if } \lambda = 0, \\ (iii) \quad G(t, s) &= \begin{cases} \frac{\sin \omega t \sin \omega(1-s)}{\omega \sin \omega}, & 0 \leq t \leq s \leq 1, \\ \frac{\sin \omega s \sin \omega(1-t)}{\omega \sin \omega}, & 0 \leq s \leq t \leq 1, \end{cases} \quad \text{if } -\pi^2 < \lambda < 0. \end{aligned}$$

**Lemma 2.2.** [15] *The function  $G(t, s)$  has the following properties:*

- (i)  $G(t, s) > 0, \forall t, s \in (0, 1)$ ,
- (ii)  $G(t, s) \leq CG(s, s), \forall t, s \in [0, 1]$ ,
- (iii)  $G(t, s) \geq \delta G(t, t)G(s, s), \forall t, s \in [0, 1]$ ,

where  $C = 1, \delta = \omega / \sinh \omega$ , if  $\lambda > 0$ ;  $C = 1, \delta = 1$ , if  $\lambda = 0$ ;  $C = 1 / \sin \omega, \delta = \omega \sin \omega$ , if  $-\pi^2 < \lambda < 0$ .

Let  $G(t, s)$ ,  $G_b(t, s)$  denote the Green function for  $\lambda = 0$  and  $\lambda = b$ , respectively. Now the solutions of (1.5) can be rewritten as fixed points of operators  $\mathfrak{T}$  in an appropriate Banach space, where

$$\begin{aligned}\mathfrak{T}\phi(t) &= -\int_0^1 \int_0^1 G(t, s)G_b(s, \tau)\phi(\tau)\phi''(\tau)d\tau ds \\ &\quad + \mu \int_0^1 \int_0^1 G(t, s)G_b(s, \tau)f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu})d\tau ds.\end{aligned}$$

Let  $E$  denote the the Banach space  $C^2[0, 1]$  with the norm

$$\|u\| = |u|_\infty + |u''|_\infty = \max_{t \in [0, 1]} |u(t)| + \max_{t \in [0, 1]} |u''(t)|, \text{ for } u \in C^2[0, 1].$$

Define a cone  $K \subset E$  by

$$K = \{u(t) \in C^2[0, 1] : u \geq 0, u'' \leq 0, \min_{t \in [\frac{1}{4}, \frac{3}{4}]} u(t) \geq \sigma_1 |u|_\infty, \max_{t \in [\frac{1}{4}, \frac{3}{4}]} u''(t) \leq -\sigma_2 |u''|_\infty\},$$

where  $\sigma_i \in (0, 1)$  (see [15]). Also, for  $r > 0$ , define  $K_r$  and  $\partial K_r$  by

$$K_r = \{u(t) \in K : \|u\| < r\}, \quad \partial K_r = \{u(t) \in K : \|u\| = r\}.$$

**Lemma 2.3.** *Let  $h \in C^+[0, 1]$ . Then the linear boundary value problem*

$$\begin{cases} u^{(4)} - bu'' = h(t), & 0 < t < 1, \\ u(0) = u(1) = 0, u''(0) = u''(1) = 0 \end{cases} \quad (2.1)$$

has a unique solution  $u(t)$ , which satisfies the following estimates:

- (i)  $u(t) \geq G(t, t)|u|_\infty$ , for every  $t \in [0, 1]$ , and  $|u|_\infty \leq \frac{\pi^3}{4} \int_0^1 u(t) \sin \pi t ds$ .
- (ii)  $u''(t) \leq -\delta_b G_b(t, t)|u''|_\infty$ , for every  $t \in [0, 1]$ , and

$$|u''|_\infty \leq \Gamma \cdot \int_0^1 u(t) \sin \pi t ds,$$

where

$$\Gamma = \left(\pi^3 + \frac{\pi^5}{4b^2}\right) \cdot \sinh \sqrt{b} \cdot \tanh \sqrt{b}.$$

*Proof.* Let  $v = -u''$ . Then,

$$v(t) = \int_0^1 G_b(t, s)h(s)ds$$

and

$$u(t) = \int_0^1 G(t, s)v(s)ds.$$

From Lemma 2.2, it follows that

$$\begin{aligned}u(t) &= \int_0^1 G(t, s)v(s)ds, \\ &\geq \int_0^1 G(t, t)G(s, s)v(s)ds \\ &\geq t(1-t)|u|_\infty.\end{aligned}$$

Multiplying both sides of the above inequality by  $\sin \pi t$  and integrating on  $[0, 1]$ , we get

$$\int_0^1 u(t) \sin \pi t dt \geq \int_0^1 t(1-t) \sin \pi t dt \cdot |u|_\infty,$$

namely,

$$|u|_\infty \leq \frac{\pi^3}{4} \int_0^1 u(t) \sin \pi t dt.$$

So, (i) of Lemma 2.3 holds. As the similar argument, we also have

$$v(t) \geq \delta_b G_b(t, t) |v|_\infty \Leftrightarrow u''(t) \leq -\delta_b G_b(t, t) |u''|_\infty, \forall t \in [0, 1]$$

and

$$|v|_\infty \leq \frac{1}{\int_0^1 \delta_b G_b(t, t) \sin \pi t dt} \int_0^1 v(t) \sin \pi t dt.$$

Letting  $\omega = \sqrt{b}$ , we find

$$\begin{aligned} \int_0^1 \delta_b G_b(t, t) \sin \pi t dt &= \int_0^1 \frac{\omega}{\sinh \omega} \frac{\sinh \omega t \cdot \sinh \omega(1-t)}{\omega_1 \sinh \omega} \sin \pi t dt \\ &= \frac{1}{(\sinh \omega)^2} \int_0^1 \sinh \omega t \cdot \sinh \omega(1-t) \sin \pi t dt \\ &= \frac{1}{4(\sinh \omega)^2} \frac{-1}{\pi} \int_0^1 e^\omega - e^{\omega-2\omega t} - e^{2\omega t-\omega} + e^{-\omega} d \cos \pi t \\ &= \frac{1}{4(\sinh \omega)^2} \frac{-1}{\pi} [-2(e^\omega + e^{-\omega}) - \int_0^1 e^{\omega-2\omega t} + e^{2\omega t-\omega} d \cos \pi t] \\ &= \frac{1}{4(\sinh \omega)^2} \frac{-1}{\pi} [-2(e^\omega + e^{-\omega}) - (-2(e^\omega + e^{-\omega})) \\ &\quad + \int_0^1 \cos \pi t (-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega} dt] \\ &= \frac{1}{4(\sinh \omega)^2} \frac{-1}{\pi} \int_0^1 \cos \pi t [(-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega}] dt. \end{aligned}$$

Let

$$\Lambda(t) = \int_0^1 \cos \pi t (-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega} dt.$$

Then,

$$\begin{aligned} \Lambda(t) &= \frac{1}{\pi} \int_0^1 (-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega} d(\sin \pi t) \\ &= \frac{1}{\pi} [0 - \int_0^1 \sin \pi t d[(-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega}] \\ &= \frac{2\omega}{\pi} \int_0^1 \sin \pi t [(-2\omega) e^{\omega-2\omega t} - (2\omega) e^{2\omega t-\omega}] dt \\ &= \frac{2\omega-1}{\pi} \int_0^1 (-2\omega) e^{\omega-2\omega t} - (2\omega) e^{2\omega t-\omega} d(\cos \pi t) \\ &= \frac{4\omega^4}{\pi^2} [-2(e^\omega + e^{-\omega}) - \int_0^1 \cos \pi t [(-2\omega) e^{\omega-2\omega t} + (2\omega) e^{2\omega t-\omega}] dt \\ &= \frac{4\omega^4}{\pi^2} [-2(e^\omega + e^{-\omega}) - \Lambda(t)] \\ &= \frac{4b^2}{\pi^2} [-2(e^{\sqrt{b}} + e^{-\sqrt{b}}) - \Lambda(t)], \end{aligned}$$

which yields

$$\Lambda(t) = \frac{-8b^2(e^{\sqrt{b}} + e^{-\sqrt{b}})}{\pi^2 + 4b^2}.$$

It is easy to see that

$$\int_0^1 \delta_b G_b(t, t) \sin \pi t dt = \frac{2b^2(e^{\sqrt{b}} + e^{-\sqrt{b}})}{(\sinh \sqrt{b})^2 \cdot \pi \cdot (\pi^2 + 4b^2)}.$$

Furthermore,

$$\begin{aligned} \|u''\| &\leq \frac{1}{\int_0^1 \delta_b G_b(t, t) \sin \pi t ds} \int_0^1 (-u''(t)) \sin \pi t dt \\ &= \frac{(\sinh \sqrt{b})^2 \cdot \pi^3 \cdot (\pi^2 + 4b^2)}{2b^2(e^{\sqrt{b}} + e^{-\sqrt{b}})} \int_0^1 u(t) \sin \pi t ds \\ &= \sinh \sqrt{b} \tanh \sqrt{b} \cdot (\pi^3 + \frac{\pi^5}{4b^2}) \int_0^1 u(t) \sin \pi t ds, \end{aligned}$$

which implies that (ii) of Lemma 2.3 holds.  $\square$

**Lemma 2.4.** *If  $f : [0, 1] \times R^+ \times R^+ \rightarrow R^+$  is continuous, then  $\mathfrak{T}(K) \subseteq K$  and  $\mathfrak{T} : K \rightarrow K$  is completely continuous.*

*Proof.* For any  $\phi(t) \in K$ , we have

$$\begin{aligned} \mathfrak{T}\phi(t) &= - \int_0^1 \int_0^1 G(t, s) G_b(s, \tau) \phi(\tau) \phi''(\tau) d\tau ds \\ &\quad + \mu \int_0^1 \int_0^1 G(t, s) G_b(s, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau ds \geq 0 \end{aligned}$$

and

$$\begin{aligned} \mathfrak{T}''\phi(t) &= \int_0^1 G_b(t, \tau) \phi(\tau) \phi''(\tau) d\tau \\ &\quad - \mu \int_0^1 G_b(t, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \leq 0. \end{aligned}$$

Moreover,

$$\begin{aligned} \min_{t \in [\frac{1}{4}, \frac{3}{4}]} \mathfrak{T}\phi(t) &= \min_{t \in [\frac{1}{4}, \frac{3}{4}]} - \int_0^1 \int_0^1 G(t, s) G_b(s, \tau) \phi(\tau) \phi''(\tau) d\tau ds \\ &\quad + \min_{t \in [\frac{1}{4}, \frac{3}{4}]} \mu \int_0^1 \int_0^1 G(t, s) G_b(s, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau ds \\ &\geq \min_{t \in [\frac{1}{4}, \frac{3}{4}]} - \int_0^1 \int_0^1 G(t, t) G(s, s) G_b(s, \tau) \phi(\tau) \phi''(\tau) d\tau ds \\ &\quad + \min_{t \in [\frac{1}{4}, \frac{3}{4}]} \mu \int_0^1 \int_0^1 G(t, t) G(s, s) G_b(s, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau ds \\ &= \min_{t \in [\frac{1}{4}, \frac{3}{4}]} G(t, t) [- \int_0^1 \int_0^1 G(s, s) G_b(s, \tau) \phi(\tau) \phi''(\tau) d\tau ds] \\ &\quad + \min_{t \in [\frac{1}{4}, \frac{3}{4}]} G(t, t) [\mu \int_0^1 \int_0^1 G(s, s) G_b(s, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau ds] \\ &= \sigma_1 |\mathfrak{T}\phi|_\infty \end{aligned}$$

and

$$\begin{aligned}
\max_{t \in [\frac{1}{4}, \frac{3}{4}]} \mathfrak{T}'' \phi(t) &= \max_{t \in [\frac{1}{4}, \frac{3}{4}]} \left[ \int_0^1 G_b(t, \tau) \phi(\tau) \phi''(\tau) d\tau - \mu \int_0^1 G_b(t, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \right] \\
&= - \min_{t \in [\frac{1}{4}, \frac{3}{4}]} \left[ - \int_0^1 G_b(t, \tau) \phi(\tau) \phi''(\tau) d\tau + \mu \int_0^1 G_b(t, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \right] \\
&\leq - \min_{t \in [\frac{1}{4}, \frac{3}{4}]} \left[ - \int_0^1 G_b(t, t) G_b(\tau, \tau) \phi(\tau) \phi''(\tau) d\tau \right. \\
&\quad \left. + \mu \int_0^1 G_b(t, t) G_b(\tau, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \right] \\
&\leq - \min_{t \in [\frac{1}{4}, \frac{3}{4}]} G_b(t, t) \left[ - \int_0^1 G_b(\tau, \tau) \phi(\tau) \phi''(\tau) d\tau \right. \\
&\quad \left. + \mu \int_0^1 G_b(\tau, \tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \right] \\
&= \sigma_2 |\mathfrak{T}'' \phi|_\infty.
\end{aligned}$$

So,  $\mathfrak{T}(K) \subseteq K$ . Finally, it is standard to verify that  $\mathfrak{T}$  is completely continuous, see, e.g., [25]. This completes the proof.  $\square$

At the end of this section, we give the following two crucial lemmas.

**Lemma 2.5.** [25] *Let  $\mathfrak{T} : K \rightarrow K$  be a completely continuous mapping. If  $\lambda \mathfrak{T}u \neq u$  for every  $u \in \partial K_r$  and  $0 < \lambda \leq 1$ , then  $i(\mathfrak{T}, K_r, K) = 1$ .*

**Lemma 2.6.** [25] *Let  $\mathfrak{T} : K \rightarrow K$  be a completely continuous mapping. If there exists an  $e \in K \setminus \theta$  such that  $u - \mathfrak{T}u \neq \tau e$  for every  $u \in \partial K_r$ , then  $i(\mathfrak{T}, K_r, K) = 0$ .*

### 3. MAIN RESULTS

**Theorem 3.1.** *Assume that  $f : [0, 1] \times \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$  is continuous and satisfies the following assumptions:*

(F<sub>1</sub>) *There exist  $\alpha_1 > 0, \beta_1 \geq 0, r_1 > 0, 0 < \frac{\mu\alpha_1}{\pi^4} + \frac{\beta_1 - b}{\pi^2} + \frac{\min\{1, \mu^2\}}{2\pi^4} r_1 < 1$ , such that*

$$f(t, \phi, u) \leq \alpha_1 \phi + \beta_1 u, \forall t \in [0, 1], \phi \in [0, r_1], u \in [0, \mu r_1].$$

(F<sub>2</sub>) *There exist  $\alpha_2 \geq 0, \beta_2 \geq 0, \frac{\alpha_2}{2\pi^4} + \frac{\beta_2 - b}{\pi^2} > 1$ , and  $h(t) \in C^+[0, 1]$ , such that*

$$f(t, \phi, u) \geq \alpha_2 \phi + \beta_2 u - h(t), \forall t \in [0, 1], \phi \geq 0, u \geq 0.$$

*Then (1.5) has at least one positive solution.*

*Proof.* Set  $r = \frac{\min\{1, \mu^2\}}{2} r_1$ . We prove that  $\lambda \mathfrak{T}\phi \neq \phi$  for  $\phi \in \partial K_r$  and  $0 < \lambda \leq 1$ . On the contrary, there exist  $\bar{\phi} \in \partial K_r$  and  $0 < \bar{\lambda} \leq 1$  such that  $\bar{\lambda} \mathfrak{T}\bar{\phi} = \bar{\phi}$ , namely,

$$\bar{\phi}^{(4)}(t) - b\bar{\phi}''(t) = -\bar{\lambda}\bar{\phi}(t)\bar{\phi}''(t) + \bar{\lambda}\mu f(t, \bar{\phi}(t), -\frac{1}{\mu}\bar{\phi}''(t)), \quad 0 \leq t \leq 1$$

and

$$\bar{\phi}(0) = \bar{\phi}(1) = \bar{\phi}''(0) = \bar{\phi}''(1) = 0.$$

For  $\bar{\phi} \in \partial K_r$ , we have

$$|\bar{\phi}|_\infty \leq \frac{r_1}{2}, \quad \left| \frac{1}{\mu} \bar{\phi}'' \right|_\infty \leq \frac{\min\{1, \mu^2\}}{\mu} r_1 \leq \frac{\mu^2}{\mu} r_1 < \mu r_1.$$

From  $(F_1)$ , it follows that

$$\begin{aligned} \bar{\phi}^{(4)}(t) - b\bar{\phi}''(t) &= -\bar{\lambda}\bar{\phi}(t)\bar{\phi}''(t) + \bar{\lambda}\mu f(t, \bar{\phi}(t), -\frac{1}{\mu}\bar{\phi}''(t)) \\ &\leq -\bar{\lambda}\bar{\phi}(t)\bar{\phi}''(t) + \bar{\lambda}\mu[\alpha_1\bar{\phi}(t) - \beta_1\frac{1}{\mu}\bar{\phi}''(t)] \\ &= -\bar{\lambda}\bar{\phi}(t)\bar{\phi}''(t) + \bar{\lambda}\mu\alpha_1\bar{\phi}(t) - \bar{\lambda}\beta_1\bar{\phi}''(t) \\ &\leq -\bar{\phi}(t)\bar{\phi}''(t) + \mu\alpha_1\bar{\phi}(t) - \beta_1\bar{\phi}''(t) \\ &\leq \bar{\phi}(t)\frac{\min\{1, \mu^2\}}{2}r_1 + \mu\alpha_1\bar{\phi}(t) - \beta_1\bar{\phi}''(t). \end{aligned} \quad (3.1)$$

Furthermore, multiplying this inequality by  $\sin \pi t$  and integrating on  $[0, 1]$ , we have

$$\int_0^1 \bar{\phi}(t) \sin \pi t dt \leq \frac{[\mu\alpha_1 + \frac{\min\{1, \mu^2\}}{2}r_1 + (\beta_1 - b)\pi^2]}{\pi^4} \int_0^1 \bar{\phi}(t) \sin \pi t dt. \quad (3.2)$$

By Lemma 2.3, we have

$$\|\bar{\phi}\| = |\phi|_\infty + |\bar{\phi}''|_\infty \leq \left(\Gamma + \frac{\pi^3}{4}\right) \int_0^1 \bar{\phi}(t) \sin \pi t dt,$$

which implies  $\int_0^1 \bar{\phi}(t) \sin \pi t dt > 0$ . Using (3.2), we get

$$1 \leq \frac{[\mu\alpha_1 + \frac{\min\{1, \mu^2\}}{2}r_1 + (\beta_1 - b)\pi^2]}{\pi^4} < 1,$$

which is a contradiction. Thus,  $i(\mathfrak{I}, K_r, K) = 1$ .

Now, we choose a sufficiently large  $R > \max\{r, \mu r\}$  and  $e = \sin \pi t \in K \setminus 0$ . Then  $\phi - \mathfrak{I}\phi \neq \tau \sin \pi t$ , for every  $\phi \in \partial K_R$  and  $\tau \geq 0$ . If there exist  $\phi_0 \in \partial K_R$  and  $\tau \geq 0$  such that  $\phi_0 - \mathfrak{I}\phi_0 = \tau \sin \pi t$ , then

$$\phi_0^{(4)}(t) - b\phi_0''(t) - \tau(\pi^4 + b\pi^2) \sin \pi t = -\phi_0(t)\phi_0''(t) + \mu f(t, \phi_0(t), -\frac{\phi_0''(t)}{\mu})$$

and

$$\phi_0(0) = \phi_0(1) = \phi_0''(0) = \phi_0''(1) = 0.$$

From  $(F_2)$ , it follows that

$$\begin{aligned} \phi_0^{(4)}(t) - b\phi_0''(t) &= -\phi_0(t)\phi_0''(t) + \mu f(t, \phi_0(t), -\frac{\phi_0''(t)}{\mu}) \\ &\quad + \tau(\pi^4 + b\pi^2) \sin \pi t \\ &\geq -\phi_0(t)\phi_0''(t) + \mu[\alpha_2\phi_0(t) - \beta_2\frac{\phi_0''(t)}{\mu} - h(t)] \\ &\geq \mu\alpha_2\phi_0(t) - \beta_2\phi_0''(t) - \mu h(t). \end{aligned}$$

Multiplying this inequality by  $\sin \pi t$  and integrating on  $[0, 1]$ , we have

$$\pi^4 \int_0^1 \phi_0(t) \sin \pi t dt \geq [\mu\alpha_2 + (\beta_2 - b)\pi^2] \int_0^1 \phi_0(t) \sin \pi t dt - \mu \int_0^1 h(t) \sin \pi t dt,$$



which yields

$$\int_0^1 \phi_0(t) \sin \pi t dt \leq \frac{\mu \int_0^1 h(t) \sin \pi t dt}{\mu \alpha_2 + (\beta_2 - b) \pi^2 - \pi^4}.$$

Furthermore, we have

$$\begin{aligned} \|\phi_0\| &\leq \left(\Gamma + \frac{\pi^3}{4}\right) \int_0^1 \phi_0(t) \sin \pi t dt \\ &\leq \left(\Gamma + \frac{\pi^3}{4}\right) \frac{\mu}{\frac{1}{2} \alpha_2 + (\beta_2 - b) \pi^2 - \pi^4} \int_0^1 h(t) \sin \pi t dt = \bar{R}. \end{aligned}$$

Let  $R > \max\{\bar{R}, r_1, \mu r_1\}$ . Then  $i(\mathfrak{T}, K_R, K) = 0$ .

Finally,

$$i(\mathfrak{T}, K_R \setminus K_r, K) = i(\mathfrak{T}, K_R, K) - i(\mathfrak{T}, K_r, K) = -1.$$

Therefore  $\mathfrak{T}$  has a fixed point in  $K_R \setminus K_r$ , which is the positive solution of (1.5).  $\square$

**Corollary 3.2.** Assume that  $(F_2)$  holds. In addition,  $f$  satisfies the following assumption:

$(F_3)$  There exist  $\alpha_3 > 0, \beta_3 \geq 0, r_2 > 0, 0 < \frac{\mu \alpha_3}{\pi^4} + \frac{\beta_3 + \frac{\min\{1, \mu^2\}}{2} r_2 - b}{\pi^2} < 1$  such that

$$f(t, \phi, u) \leq \alpha_3 \phi + \beta_3 u, \forall t \in I, \phi \in [0, r_2], u \in [0, \mu r_2].$$

Then (1.5) has at least one positive solution.

*Proof.* The proof is similar to Theorem 3.1. We only need to revise (3.1) as

$$\begin{aligned} \bar{\phi}^{(4)}(t) - b \bar{\phi}''(t) &= -\bar{\lambda} \bar{\phi}(t) \bar{\phi}''(t) + \bar{\lambda} \mu f(t, \bar{\phi}(t), -\frac{1}{\mu} \bar{\phi}''(t)) \\ &\leq -\bar{\lambda} \bar{\phi}(t) \bar{\phi}''(t) + \bar{\lambda} \mu [\alpha_3 \bar{\phi}(t) - \beta_3 \frac{1}{\mu} \bar{\phi}''(t)] \\ &\leq -\bar{\phi}(t) \bar{\phi}''(t) + \mu \alpha_3 \bar{\phi}(t) - \beta_3 \bar{\phi}''(t) \\ &\leq -\bar{\phi}''(t) \cdot \frac{\min\{1, \mu^2\}}{2} r_2 + \mu \alpha_3 \bar{\phi}(t) - \beta_3 \bar{\phi}''(t). \end{aligned}$$

$\square$

**Corollary 3.3.** Assume that  $(F_2)$  holds. In addition,  $f$  satisfies the following assumption:

$(F_4)$  There exist  $\alpha_4 > 0, \beta_4 \geq 0, r_3 > 0, 0 < \frac{\mu \alpha_4 + (\frac{\min\{1, \mu^2\}}{2} r_3)^2}{\pi^4} + \frac{\beta_4 - b}{\pi^2} < 1$  such that

$$f(t, \phi, u) \leq \alpha_4 \phi + \beta_4 u, \forall t \in I, \phi \in [0, r_3], u \in [0, \mu r_3].$$

Then (1.5) has at least one positive solution.

*Proof.* The proof is similar to Theorem 3.1. We only need to revise (3.1) as

$$\begin{aligned} \bar{\phi}^{(4)}(t) - b \bar{\phi}''(t) &= -\bar{\lambda} \bar{\phi}(t) \bar{\phi}''(t) + \bar{\lambda} \mu f(t, \bar{\phi}(t), -\frac{1}{\mu} \bar{\phi}''(t)) \\ &\leq -\bar{\lambda} \bar{\phi}(t) \bar{\phi}''(t) + \bar{\lambda} \mu [\alpha_4 \bar{\phi}(t) - \beta_4 \frac{1}{\mu} \bar{\phi}''(t)] \\ &\leq -\bar{\phi}(t) \bar{\phi}''(t) + \mu \alpha_4 \bar{\phi}(t) - \beta_4 \bar{\phi}''(t) \\ &\leq \left(\frac{\min\{1, \mu^2\}}{2} r_3\right)^2 + \mu \alpha_4 \bar{\phi}(t) - \beta_4 \bar{\phi}''(t). \end{aligned}$$

$\square$

**Corollary 3.4.** Assume that  $(F_2)$  holds. In addition,  $f$  satisfies the following assumption:

$$0 < \frac{1}{2\pi^4} + \frac{1-2b}{2\pi^2} + \mu \frac{\max_{(t,\phi,u) \in [0,1] \times [0,1] \times [0, \frac{1}{\mu}]} f(t, \phi, u)}{\pi^4} < 1.$$

Then (1.5) has at least one positive solution.

*Proof.* The proof is similar to Theorem 3.1. Choosing  $r < 1$ , we only need to revise (3.1) as

$$\begin{aligned} \bar{\phi}^{(4)}(t) - b\bar{\phi}''(t) &= -\bar{\lambda}\bar{\phi}(t)\bar{\phi}''(t) + \bar{\lambda}\mu f(t, \bar{\phi}(t), -\frac{1}{\mu}\bar{\phi}''(t)) \\ &\leq -\bar{\phi}(t)\bar{\phi}''(t) + \mu \max_{(t,\phi,-\phi'') \in [0,1] \times [0,1] \times [0,1]} f(t, \bar{\phi}, -\frac{1}{\mu}\bar{\phi}'') \\ &\leq \frac{\bar{\phi}(t)}{2} + \frac{-\bar{\phi}''(t)}{2} + \mu \max_{(t,\phi,-\phi'') \in [0,1] \times [0,1] \times [0,1]} f(t, \bar{\phi}, -\frac{1}{\mu}\bar{\phi}''). \end{aligned}$$

□

**Theorem 3.5.** Assume that  $(F_2)$  holds. In addition,  $f$  satisfies the following assumptions:

$(F_4)$  There exist  $\tilde{R} > r_4 > 0$ ,  $\alpha_5 > 0$ ,  $\beta_5 \geq 0$ ,  $\frac{\mu\alpha_5}{\pi^4} + \frac{\beta_5 - b}{\pi^2} > 1$  such that

$$\frac{7}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) [\tilde{R}^2 + \mu \max_{t \in [0,1] \times [0, \tilde{R}] \times [0, \frac{1}{\mu} \tilde{R}]} f(t, \phi, u)] < \tilde{R}$$

and

$$f(t, \phi, u) \geq \alpha_5 \phi + \beta_5 u, \forall t \in [0, 1], \phi \in [0, r_4], u \in [0, \mu r_4].$$

Then (1.5) has at least two positive solutions.

*Proof.* Choosing  $r = \frac{\min\{1, \mu^2\}}{2} r_4$  and  $e = \sin \pi t \in K \setminus \{0\}$ , we have  $\phi - \mathfrak{T}\phi \neq \tau \sin \pi t$ , for every  $\phi \in \partial K_r$  and  $\tau \geq 0$ . If there exist  $\phi_0 \in \partial K_r$  and  $\tau \geq 0$  such that  $\phi_0 - \mathfrak{T}\phi_0 = \tau \sin \pi t$ , then

$$\phi_0^{(4)}(t) - b\phi_0''(t) - \tau(\pi^4 + b\pi^2) \sin \pi t = -\phi_0(t)\phi_0''(t) + \mu f(t, \phi_0(t), -\frac{\phi_0''(t)}{\mu})$$

and

$$\phi_0(0) = \phi_0(1) = \phi_0''(0) = \phi_0''(1) = 0.$$

For  $\phi_0 \in \partial K_r$ , we have

$$|\phi_0|_\infty \leq \frac{r_4}{2}, \quad \left| \frac{1}{\mu} \phi_0'' \right|_\infty \leq \frac{\min\{1, \mu^2\}}{2} r_4 \leq \frac{\mu^2}{2} r_4 < \mu r_4.$$

From  $(F_4)$ , it follows that

$$\begin{aligned} \phi_0^{(4)}(t) - b\phi_0''(t) &= -\phi_0(t)\phi_0''(t) + \mu f(t, \phi_0(t), -\frac{\phi_0''(t)}{\mu}) \\ &\quad + \tau(\pi^4 + b\pi^2) \sin \pi t \\ &\geq -\phi_0(t)\phi_0''(t) + \mu [\alpha_5 \phi_0(t) - \beta_5 \frac{\phi_0''(t)}{\mu}] \\ &\geq \mu \alpha_5 \phi_0(t) - \beta_5 \phi_0''(t). \end{aligned}$$

Multiplying this inequality by  $\sin \pi t$  and integrating on  $[0, 1]$ , we have

$$\pi^4 \int_0^1 \phi_0(t) \sin \pi t dt \geq [\mu \alpha_5 + (\beta_5 - b)\pi^2] \int_0^1 \phi_0(t) \sin \pi t dt.$$

Since  $\int_0^1 \phi_0(t) \sin \pi t dt > 0$ , we have

$$\pi^4 \geq \mu \alpha_5 + (\beta_5 - b) \pi^2,$$

which contradicts  $(F_4)$ . Then,  $i(\mathfrak{T}, K_r, K) = 0$ .

Now, we prove that  $\lambda \mathfrak{T}\phi \neq \phi$  for  $\phi \in \partial K_{\tilde{R}}$  and  $0 < \lambda \leq 1$ . For any  $\phi \in \partial K_{\tilde{R}}$ , we have

$$\begin{aligned} \|\lambda \mathfrak{T}\phi\| &\leq \|\mathfrak{T}\phi\| = |\mathfrak{T}\phi|_\infty + |(\mathfrak{T}\phi)''|_\infty \\ &\leq \left| \int_0^1 \int_0^1 G(t,s) G_b(s,\tau) \phi(\tau) \phi''(\tau) d\tau ds \right|_\infty \\ &\quad + \left| \mu \int_0^1 \int_0^1 G(t,s) G_b(s,\tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau ds \right|_\infty \\ &\quad + \left| \int_0^1 G_b(t,\tau) \phi(\tau) \phi''(\tau) d\tau \right|_\infty \\ &\quad + \left| \mu \int_0^1 G_b(t,\tau) f(\tau, \phi(\tau), \frac{-\phi''(\tau)}{\mu}) d\tau \right|_\infty \\ &\leq \frac{1}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \tilde{R}^2 + \mu \frac{1}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \max_{t \in [0,1] \times [0,\tilde{R}] \times [0,\frac{1}{\mu}\tilde{R}]} f(t, \phi, -\frac{1}{\mu} \phi'') \\ &\quad + \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \tilde{R}^2 + \mu \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \max_{t \in [0,1] \times [0,\tilde{R}] \times [0,\frac{1}{\mu}\tilde{R}]} f(t, \phi, -\frac{1}{\mu} \phi'') \\ &= \frac{7}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \tilde{R}^2 + \mu \frac{7}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) \max_{t \in [0,1] \times [0,\tilde{R}] \times [0,\frac{1}{\mu}\tilde{R}]} f(t, \phi, -\frac{1}{\mu} \phi'') \\ &< \tilde{R}, \end{aligned}$$

which implies that  $i(\mathfrak{T}, K_{\tilde{R}}, K) = 1$ . In the same proof of Theorem 3.1, it follows from  $(F_2)$  that there exist a sufficiently large

$$R > \max \left\{ \frac{\min\{1, \mu^2\}}{2} r_4, \tilde{R}, \bar{R} \right\}$$

such that  $i(\mathfrak{T}, K_R, K) = 0$ .

Finally,

$$i(\mathfrak{T}, K_{\tilde{R}} \setminus K_r, K) = i(\mathfrak{T}, K_{\tilde{R}}, K) - i(\mathfrak{T}, K_r, K) = 1,$$

$$i(\mathfrak{T}, K_R \setminus K_{\tilde{R}}, K) = i(\mathfrak{T}, K_R, K) - i(\mathfrak{T}, K_{\tilde{R}}, K) = -1,$$

Therefore  $\mathfrak{T}$  has two fixed points in  $K_{\tilde{R}} \setminus K_r$  and  $K_R \setminus K_{\tilde{R}}$ , which are the positive solutions of (1.5).  $\square$

**Example 3.6.** Let us consider the following system

$$\begin{cases} -u'' + u = \phi u + \frac{1}{10} \{2\pi^4(e^\phi - 1) + u^2 + 2u\}, & 0 < t < 1, \\ -\phi'' = \frac{1}{10} u, \\ \phi(0) = \phi(1) = 0, \phi''(0) = \phi''(1) = 0. \end{cases} \quad (3.3)$$

Let

$$\alpha_1 = 2\pi^4 e, \beta_1 = 3, r_1 = 1.$$

It is clear that

$$\begin{aligned} 0 &< \frac{\mu\alpha_1}{\pi^4} + \frac{\beta_1 - b}{\pi^2} + \frac{\min\{1, \mu^2\}}{2\pi^4} r_1 \\ &= \frac{2e}{10} + \frac{2}{\pi^2} + \frac{1}{200\pi^4} \\ &< 1. \end{aligned}$$

For  $t \in [0, 1]$ ,  $\phi \in [0, 1]$ ,  $u \in [0, \frac{1}{10}]$ , we have

$$f(t, \phi, u) = 2\pi^4(e^\phi - 1) + u^2 + 2u \leq 2\pi^4 e\phi + u + 2u \leq \alpha_1\phi + \beta_1 u,$$

which yields that  $(F_1)$  holds.

On the other hand, let

$$\alpha_2 = 2\pi^4, \beta_2 = 2, h(t) = t^2.$$

Then,

$$\frac{\alpha_2}{2\pi^4} + \frac{\beta_2 - b}{\pi^2} = 1 + \frac{1}{\pi^2} > 1$$

and

$$f(t, \phi, u) = 2\pi^4(e^\phi - 1) + u^2 + 2u \geq 2\pi^4\phi + 2u \geq \alpha_2\phi + \beta_2 u - h(t),$$

which guarantee that  $(F_2)$  holds. Therefore, by Theorem 3.1, (3.3) has at least one positive solution.

**Example 3.7.** Let us consider the following system

$$\begin{cases} -u'' + u = \phi u + \frac{\phi}{2 + \sin u} + (\pi^2 + 1)e^u + \cos u - \sin t, & 0 < t < 1, \\ -\phi'' = \frac{1}{156}u, \\ \phi(0) = \phi(1) = 0, \phi''(0) = \phi''(1) = 0. \end{cases} \quad (3.4)$$

Let

$$\alpha_2 = \frac{1}{3}, \beta_2 = \pi^2 + 1.$$

It is clear that

$$\frac{\alpha_2}{2\pi^4} + \frac{\beta_2 - b}{\pi^2} = \frac{1}{2\pi^4} + 1 > 1$$

and

$$f(t, \phi, u) = \frac{\phi}{2 + \sin u} + (\pi^2 + 1)e^u + \cos u - \sin t \geq \alpha_2\phi + \beta_2 u - (\sin t + 1),$$

which yields that  $(F_2)$  holds.

On the other hand, let

$$\alpha_5 = \frac{1}{3}, \beta_5 = \pi^2 + 1, \tilde{R} = 1, r_4 = \frac{1}{2}.$$

Then,

$$\frac{\mu\alpha_5}{\pi^4} + \frac{\beta_5 - b}{\pi^2} > 1.$$

In addition, we also have

$$\begin{aligned} &\frac{7}{6} \left( \frac{\coth \sqrt{b}}{2\sqrt{b}} - \frac{1}{2b} \right) [\tilde{R}^2 + \mu \max_{t \in [0, 1] \times [0, \tilde{R}] \times [0, \frac{1}{\mu} \tilde{R}]} f(t, \phi, u)] \\ &\leq \frac{7}{6(e^2 - 1)} \left[ 1 + \frac{\frac{1}{2} + (\pi^2 + 1)e^{\frac{1}{156}} + 1}{156} \right] < 1 = \tilde{R} \end{aligned}$$

and

$$\begin{aligned} f(t, \phi, u) &= \frac{\phi}{2 + \sin u} + (\pi^2 + 1)e^u + \cos u - \sin t \\ &\geq \alpha_5 \phi + \beta_5 u, \end{aligned}$$

for  $t \in [0, 1]$ ,  $\phi \in [0, \frac{1}{2}]$ ,  $u \in [0, \frac{1}{312}]$ , so that  $(F_4)$  holds. Therefore, by Theorem 3.5, (3.4) has at least two positive solution.

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