



SINGULARITIES OF ATTRACTIVE AND REPULSIVE TYPE TO FOURTH-ORDER NEUTRAL LIÉNARD EQUATIONS WITH TIME-DEPENDENT DEVIATING ARGUMENTS

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Abstract. In this paper, we are concerned with the existence of a positive periodic solution for a kind of fourth-order neutral singular Liénard equation with time-dependent deviating arguments. Our results are based on the coincidence degree theory. Two examples with singularities of attractive and repulsive type are given.

Keywords. Positive periodic solution; Neutral operator; Time-dependent deviating arguments; Singularities of attractive and repulsive type.

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1. INTRODUCTION

Recently, neutral differential equations have received much attention. There has been a rapid growth of interest in neutral differential equations which appear in the blood cell production models, control models and population models; see, e.g., [1, 2, 3]. Bai and Xu [1] discussed a two-phase size-structured population model with infinite states-at-birth and distributed delay in birth process. Recently, topological degree theory, the Krasnoselskii fixed point theorem, and the fixed point theorems in a cone have been employed to investigate the existence of a periodic solutions of neutral nonlinear differential equations; see, e.g., [4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14] and the references therein.

In recent years, some results have been performed on the existence of periodic solutions of neutral differential equations with singularity of repulsive type; see, e.g., [15, 16, 17]. In 2015, Kong, Lu and Liang [15] discussed the following second-order neutral Liénard equation with singularity of repulsive type:

$$(x(t) - cx(t - \tau))'' + f(x(t))x'(t) + g(t, x(t - \sigma)) = e(t), \quad (1.1)$$

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where c is a constant with $|c| < 1$, and the nonlinear term g repulsive singular at $x = 0$, i.e.,

$$\lim_{x \rightarrow 0^+} g_0(x) = -\infty, \text{ and } \int_0^1 g_0(s)ds = -\infty. \quad (1.2)$$

They obtained the existence of a positive periodic solution for equation (1.1) by using Mawhin's continuation theorem. In 2017, Xin and Cheng [16] investigated the following second order neutral Rayleigh equation with singularity of repulsive type:

$$(x(t) - cx(t - \tau))'' + f(t, x') + g(t, x(t)) = e(t), \quad (1.3)$$

where the nonlinear term g satisfies repulsive condition (1.2). Using coincidence degree theory, they obtained the existence of a positive periodic solution for equation (1.3). Recently, Kong and Lu [17] studied a kind of fourth-order Liénard equation with singularity of repulsive type

$$(x(t) - cx(t - \tau))^{(4)} + f(x(t))x'(t) + g(t, x(t - \sigma(t))) = e(t), \quad (1.4)$$

where c is a constant with $|c| < 1$, f is a continuous function, the nonlinear term $g \in C(\mathbb{R} \times (0, +\infty), \mathbb{R})$ is a T -periodic function about t and can be singular at $x = 0$. $e : \mathbb{R} \rightarrow \mathbb{R}$ is a continuous T -periodic function and $\int_0^T e(t)dt = 0$, $\sigma \in C^1(\mathbb{R}, \mathbb{R})$ is a T -periodic functions and $\sigma'(t) \neq 1$. By using the coincidence degree theory, they obtained the following conclusion.

Theorem 1.1. [17] *Assume that the following conditions hold:*

(F₁) *There exist positive constant d_1 and d_2 with $d_1 < d_2$ such that $g(t, x) < 0$ for all $(t, x) \in [0, T] \times (0, d_1)$, and $g(t, x) > 0$ for all $(t, x) \in [0, T] \times (d_2, +\infty)$.*

(F₂) $\bar{g}(x) := \frac{1}{T} \int_0^T g(t, x)dt < 0$ *for all $x \in (0, d_1)$, and $\bar{g}(x) > 0$ for all $x \in (d_2, +\infty)$.*

(F₃) *The nonlinear term $g(t, x(t - \sigma(t))) = g_1(t, x(t - \sigma(t))) + g_0(x(t))$, where $g_1 : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuo function, and $g_0 : (0, +\infty) \rightarrow \mathbb{R}$ is a continuous function and satisfying equation (1.2), (i.e. singularity of repulsive type).*

(F₄) *There exist positive constants m and n such that*

$$g(t, x) \leq mx + n, \text{ for all } (t, x) \in [0, T] \times (0, +\infty).$$

(F₅) *There exist positive constants α and β such that*

$$F(x) \leq \alpha x + \beta, \text{ for all } x \in (0, +\infty),$$

where $F(x) = \int_0^x f(s)ds$.

Then equation (1.4) has at least one positive T -periodic solution if

$$\frac{(2(1 + |c|)a + \alpha|c|)T^3}{\pi^2|1 - |c||^2} < 1.$$

In this paper, inspired by the recent results [15, 16, 17], we consider the existence of a positive T -periodic solution for equation (1.4) with singularities of attractive and repulsive type and time-dependent deviating argument, where c is a constant and $|c| \neq 1$. By using the coincidence degree theory, we get the following conclusion.

Theorem 1.2. *Assume that the following conditions hold:*

(H₁) *There exist positive constants D_1 and D_2 with $D_1 < D_2$ such that $\bar{g}(x) := \frac{1}{T} \int_0^T g(t, x)dt > 0$ for all $x \in (0, D_1)$, and $\bar{g}(x) < 0$ for all $x \in (D_2, +\infty)$.*

(H_2) The nonlinear term $g(t, x(t - \sigma(t))) = g_1(t, x(t - \sigma(t))) + g_0(x(t - \sigma(t)))$, where $g_1 : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuo function, $g_0 : (0, +\infty) \rightarrow \mathbb{R}$ is a continuous function.

(H_3) (Singularity of attractive type) $\lim_{x \rightarrow 0^+} g_0(x) = +\infty$, and $\int_0^1 g_0(s)ds = +\infty$.

(H_4) There exists positive constants m, n such that

$$-g(t, x) \leq mx + n, \text{ for } (t, x) \in \mathbb{R} \times (0, +\infty).$$

Then equation (1.4) has at least one positive T -periodic solution if

$$\frac{(1 + |c|)|c| + 2mT^2 \left(\frac{T}{2\pi}\right)^2}{|1 - |c||^2} < 1. \quad (1.5)$$

Remark 1.3. It is worth mentioning that attractive condition (H_3) contradicts the repulsive condition (1.2). Therefore, the above methods and conditions (F_1), (F_2), (F_4) in [15, 16, 17] are no long applicable to the existence of a positive periodic solution for equation (1.4) with singularity of attractive type. In this paper, we replace conditions (F_1), (F_2), (F_4) by conditions (H_1), (H_3), (H_4), and we employ another method to discuss this problem.

Remark 1.4. From condition (F_3) in [17], the singular term g_0 of equation (1.4) has a deviating argument (i.e. $\sigma \equiv 0$). The singular term g_0 of this paper satisfies time-dependent deviating argument (see condition (H_2)). For example, let

$$\sigma(t) = \cos^2(t).$$

It is easy to verify that the work on estimating a lower bounds of a positive periodic solution for equation (1.4) of this paper is more complex than the one in [17].

Remark 1.5. From condition (F_5) in [17], the maximum of the friction term $f(x)$ may be some constant, and the condition (F_5) is hard restrictive. In this paper, the friction term $f(x)$ is a continuous function.

From equation (1.5), we get $|c| < 1$, i.e., Theorem 1.2 obtains the existence of a positive periodic solution for equation (1.4) in the case that $|c| < 1$. Next, we consider the existence of a positive periodic solution for equation (1.4) in the case that $|c| \neq 1$, (i.e., $|c| < 1$ and $|c| > 1$).

Theorem 1.6. Assume that conditions (H_1) – (H_4) and (F_5) hold. Then equation (1.4) has at least one positive T -periodic solution if

$$\frac{(\alpha|c| + 2(1 + |c|)mT)T \left(\frac{T}{2\pi}\right)^2}{|1 - |c||^2} < 1. \quad (1.6)$$

Remark 1.7. It is easy to see that the coefficient c of neutral operator satisfies $|c| < 1$ in [17] and in Theorem 1.2. However, the coefficient c satisfies $|c| < 1$ and $|c| > 1$ in Theorem 1.6.

We also investigate the existence of a positive periodic solution for equation (1.4) with singularity of repulsive type. From Theorems 1.2 and 1.6, we get the following conclusions.

Theorem 1.8. Assume that conditions (F_2), (F_4), (H_3) and equations (1.2), (1.5) hold. Then equation (1.4) has at least one positive T -periodic solution.

Theorem 1.9. Assume that conditions (F_2), (F_4), (F_5), (H_3) and equations (1.2), (1.6) hold. Then equation (1.4) has at least one positive T -periodic solution.

Remark 1.10. Obviously, Theorem 1.9 implies Theorem 1.1, and condition (H_3) is relatively weaker than condition (F_3).

2. PRELIMINARIES

First, we recall the coincidence degree theory.

Lemma 2.1. [18] *Let X and Y be two Banach spaces, and let $L : D(L) \subset X \rightarrow Y$ be a Fredholm operator with index zero. Let $\Omega \subset X$ be an open bounded set, and let $N : \overline{\Omega} \rightarrow Y$ be L -compact on $\overline{\Omega}$. Assume that the following conditions hold:*

- (1) $Lx \neq \lambda Nx, \forall x \in \partial\Omega \cap D(L), \lambda \in (0, 1)$;
- (2) $Nx \notin \text{Im } L, \forall x \in \partial\Omega \cap \text{Ker } L$;
- (3) $\deg\{QN|_{\text{Ker } L}, \Omega \cap \text{Ker } L, 0\} \neq 0$.

Then the equation $Lx = Nx$ has a solution in $\overline{\Omega} \cap D(L)$.

Lemma 2.2. [19] *If $|c| \neq 1$, then $(Ax)(t) := x(t) - cx(t - \tau)$ has continuous bounded inverse on $C_T := \{x \in C(\mathbb{R}, \mathbb{R}) \mid x(t+T) - x(t) \equiv 0\}$ and*

$$\int_0^T |(A^{-1}x)(t)|^2 dt \leq \frac{1}{|1-c|^2} \int_0^T |x(t)|^2 dt, \forall x \in C_T.$$

Now, set

$$X := \{x \in C^1(\mathbb{R}, \mathbb{R}^2) : x(t+T) - x(t) \equiv 0\}$$

with the norm $\|x\|_\infty := \max\{\|x\|, \|x'\|\}$;

$$Y := \{x \in C(\mathbb{R}, \mathbb{R}) : x(t+T) - x(t) \equiv 0\}$$

with the norm $\|x\| := \max \|x\|$. Clearly, both X and Y are Banach spaces. Meanwhile, we define

$$L : D(L) := \{x \in C^4(\mathbb{R}, \mathbb{R}^2) : x(t+T) - x(t) \equiv 0, \text{ for } t \in \mathbb{R}\} \subset X \rightarrow Y$$

by

$$(Lx)(t) = (Ax)^{(4)}(t).$$

and $N : X \rightarrow Y$ by

$$(Nx)(t) = -f(x(t))x'(t) - g(t, x(t - \sigma(t))) + e(t). \quad (2.1)$$

Then equation (1.4) can be converted to the abstract equation $Lx = Nx$. From the definition of L , one can easily see that

$$\text{Ker } L \cong \mathbb{R}, \text{ Im } L = \{y \in Y : \int_0^T y(s) ds = 0\}.$$

So L is a Fredholm operator with index zero. Let $P : X \rightarrow \text{Ker } L$ and $Q : Y \rightarrow \text{Im } Q \subset \mathbb{R}$ be defined by

$$Px := (Ax)(0); \text{ and } Qy := \frac{1}{T} \int_0^T y(s) ds.$$

Then $\text{Im } P = \text{Ker } L$, and $\text{Ker } Q = \text{Im } L$. Denote $L_p = L|_{D(L) \cap \text{Ker } P}$ and let $L_p^{-1} : \text{Im } L \rightarrow D(L)$ be inverse of L_p . Then

$$\begin{aligned} [L_p^{-1}y](t) &= (A^{-1}Gy)(t), \\ (Gy)(t) &= \sum_{i=1}^3 \frac{1}{3!} a_i t^i + \frac{1}{3!} \int_0^t (t-s)^3 y(s) ds, \end{aligned} \quad (2.2)$$

where $a_i := (Ax)^{(i)}(0)$, $i = 1, 2, 3$ are defined as follows

$$\begin{pmatrix} (Ax)'''(0) \\ (Ax)''(0) \\ (Ax)'(0) \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ \frac{T}{2} & 1 & 0 \\ \frac{T^2}{3} & \frac{T}{2} & 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{T} \int_0^T (T-s)y(s)ds \\ -\frac{1}{2!T} \int_0^T (T-s)^2 y(s)ds \\ -\frac{1}{3!T} \int_0^T (T-s)^3 y(s)ds \end{pmatrix}.$$

From equations (2.1) and (2.2), we get that N is L -compact on $\bar{\Omega}$.

3. PROOF OF THEOREM 1.2

Consider the equation

$$Lx = \lambda Nx, \lambda \in (0, 1).$$

Set $\Omega_1 = \{x : Lx = \lambda Nx, \lambda \in (0, 1)\}$. If $x(t) \in \Omega_1$, then

$$((Ax)(t))^{(4)} + \lambda f(x(t))x'(t) + \lambda g(t, x(t - \sigma(t))) = \lambda e(t). \quad (3.1)$$

Integrating both side of equation (3.1) over $[0, T]$, we have

$$\int_0^T g(t, x(t - \sigma(t)))dt = 0. \quad (3.2)$$

Then by condition (H_1) , there exist positive constants D_1, D_2 and $\eta \in (0, T)$ such that

$$D_1 \leq x(\eta - \sigma(\eta)) \leq D_2. \quad (3.3)$$

Setting $\xi = \eta - \sigma(\eta) \in (0, T)$, we have

$$D_1 \leq x(\xi) \leq D_2. \quad (3.4)$$

It follows that

$$\|x\| = \max_{t \in [0, T]} |x(t)| = \max_{t \in [0, T]} \left| x(\xi) + \int_{\xi}^t x'(s)ds \right| \leq D_2 + \int_0^T |x'(s)|ds. \quad (3.5)$$

Multiplying both sides of equation (3.1) by $x(t)$ and integrating over the interval $[0, T]$, we get

$$\int_0^T ((Ax)(t))^{(4)} x(t)dt = -\lambda \int_0^T f(x(t))x'(t)x(t)dt - \lambda \int_0^T g(t, x(t - \sigma(t)))x(t)dt + \lambda \int_0^T e(t)x(t)dt. \quad (3.6)$$

Substituting $\int_0^T ((Ax)(t))^{(4)} x(t)dt = \int_0^T (Ax)''(t)x''(t)dt$, $\int_0^T f(x(t))x'(t)x(t)dt = 0$ into equation (3.6), we see that

$$\int_0^T (Ax)''(t)x''(t)dt = -\lambda \int_0^T g(t, x(t - \sigma(t)))x(t)dt + \lambda \int_0^T e(t)x(t)dt. \quad (3.7)$$

Furthermore,

$$\begin{aligned} \int_0^T (Ax)''(t)x''(t)dt &= \int_0^T (Ax)''(t)((Ax)''(t) + cx''(t - \tau))dt \\ &= \int_0^T |(Ax)''(t)|^2 dt + c \int_0^T x''(t - \tau)(Ax'')(t)dt, \end{aligned} \quad (3.8)$$

since $(Ax)''(t) = (Ax'')(t)$. Substituting equation (3.8) into equation (3.7), we deduce

$$\begin{aligned} \int_0^T |(Ax)''(t)|^2 dt &= -c \int_0^T x''(t - \tau)(Ax'')(t)dt - \lambda \int_0^T g(t, x(t - \sigma(t)))x(t)dt + \lambda \int_0^T e(t)x(t)dt \\ &= |c| \int_0^T |x''(t - \tau)|| (Ax'')(t) |dt + \|x\| \int_0^T |g(t, x(t - \sigma(t)))|dt + \int_0^T |e(t)||x(t)|dt. \end{aligned} \quad (3.9)$$

Applying the Hölder inequality and the Minkouski inequality, it is clear that

$$\begin{aligned}
& \int_0^T |x''(t-\tau)| |(Ax'')(t)| dt \\
& \leq \left(\int_0^T |x''(t-\tau)|^2 dt \right)^{\frac{1}{2}} \left(\int_0^T |(Ax'')(t)|^2 dt \right)^{\frac{1}{2}} \\
& \leq \left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} \left(\left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} + |c| \left(\int_0^T |x''(t-\tau)|^2 dt \right)^{\frac{1}{2}} \right) \\
& \leq \left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} \left(\left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} + |c| \left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} \right) \\
& = (1+|c|) \int_0^T |x''(t)|^2 dt,
\end{aligned} \tag{3.10}$$

since $\int_0^T |x''(t-\tau)|^2 dt = \int_0^T |x''(t)|^2 dt$. On the other hand, form (H_2) and equation (3.2), we have

$$\begin{aligned}
& \int_0^T |g(t, x(t-\sigma(t)))| dt \\
& = \int_{g(t, x(t-\sigma(t))) \geq 0} g^+(t, x(t-\sigma(t))) dt - \int_{g(t, x(t-\sigma(t))) \leq 0} g^-(t, x(t-\sigma(t))) dt \\
& = -2 \int_{g(t, x(t-\sigma(t))) \leq 0} g^-(t, x(t-\sigma(t))) dt \\
& \leq 2m \int_0^T x(t-\sigma(t)) dt + 2nT \\
& \leq 2m\|x\|T + 2nT,
\end{aligned} \tag{3.11}$$

where $g^+ := \max\{g(t, x), 0\}$, $g^- := \min\{g(t, x), 0\}$. Substituting equations (3.10) and (3.11) into equation (3.9), we get from the Hölder inequality that

$$\begin{aligned}
& \int_0^T |(Ax)''(t)|^2 dt \\
& \leq (1+|c|)|c| \int_0^T |x''(t)|^2 dt + 2mT\|x\|^2 + 2nT\|x\| + \|e\|\|x\|T \\
& \leq (1+|c|)|c| \int_0^T |x''(t)|^2 dt + 2mT \left(D_2 + \int_0^T |x'(t)| dt \right)^2 + \left(D_2 + \int_0^T |x'(t)| dt \right) \\
& \quad (nT + \|e\|T) \\
& \leq (1+|c|)|c| \int_0^T |x''(t)|^2 dt + 2mT^2 \int_0^T |x'(t)|^2 dt + E_1 \left(\int_0^T |x'(t)|^2 dt \right)^{\frac{1}{2}} + E_2,
\end{aligned}$$

where

$$E_1 := 4mTD_2 + (2nT + \|e\|T)T^{\frac{1}{2}}$$

and

$$E_2 := 2mTD_2^2 + D_2(2nT + \|e\|T).$$

From the Wirtinger inequality (see [20]), we have

$$\begin{aligned} \int_0^T |(Ax)''(t)|^2 dt &\leq (1+|c|)|c| \int_0^T |x''(t)|^2 dt + 2mT^2 \left(\frac{T}{2\pi}\right)^2 \int_0^T |x''(t)|^2 dt \\ &\quad + E_1 \left(\frac{T}{2\pi}\right) \left(\int_0^T |x''(t)|^2 dt\right)^{\frac{1}{2}} + E_2. \end{aligned} \quad (3.12)$$

Since $(Ax)''(t) = (Ax'')(t)$. Form Lemma 2.2 and equation (3.14), we obtain

$$\begin{aligned} &\int_0^T |x''(t)|^2 dt \\ &= \int_0^T |(A^{-1}Ax'')(t)|^2 dt \\ &\leq \frac{1}{|1-|c||^2} \int_0^T |(Ax)''(t)|^2 dt \\ &\leq \frac{1}{|1-|c||^2} \left(\left((1+|c|)|c| + 2mT^2 \left(\frac{T}{2\pi}\right)^2 \right) \int_0^T |x''(t)|^2 dt \right. \\ &\quad \left. + E_1 \left(\frac{T}{2\pi}\right) \left(\int_0^T |x''(t)|^2 dt\right)^{\frac{1}{2}} + E_2 \right) \\ &= \frac{(1+|c|)|c| + 2mT^2 \left(\frac{T}{2\pi}\right)^2}{|1-|c||^2} \int_0^T |x''(t)|^2 dt + \frac{E_1 \frac{T}{2\pi}}{|1-|c||^2} \left(\int_0^T |x''(t)|^2 dt\right)^{\frac{1}{2}} + \frac{E_2}{|1-|c||^2}. \end{aligned} \quad (3.13)$$

Since

$$\frac{(1+|c|)|c| + 2mT^2 \left(\frac{T}{2\pi}\right)^2}{|1-|c||^2} < 1,$$

we see that there exists a positive constant M'_1 such that

$$\int_0^T |x''(t)|^2 dt \leq M'_1.$$

From equation (3.6) and the Wirtinger inequality, we have

$$\begin{aligned} \|x\| &\leq D_2 + \int_0^T |x'(t)| dt \\ &\leq D_2 + \sqrt{T} \left(\frac{T}{2\pi}\right) \left(\int_0^T |x''(t)|^2 dt\right)^{\frac{1}{2}} \\ &\leq D_2 + \sqrt{T} \left(\frac{T}{2\pi}\right) (M'_1)^{\frac{1}{2}} := M_1. \end{aligned} \quad (3.14)$$

In view of $x(0) = x(T)$, we know that there exists a point $t_2 \in (0, T)$ such that $x'(t_2) = 0$, we get from equation (3.5) and the Hölder inequality that

$$\begin{aligned} \|x'\| &\leq \int_0^T |x''(t)| dt \\ &\leq \sqrt{T} \left(\int_0^T |x''(t)|^2 dt\right)^{\frac{1}{2}} \\ &\leq \sqrt{T} (M'_1)^{\frac{1}{2}} := M_2. \end{aligned} \quad (3.15)$$

It follows from equation (3.1) and $g(t, x) = g_0(x) + g_1(t, x)$ that

$$((Ax)(t))^{(4)} + \lambda f(x(t))x'(t) + \lambda(g_0(x(t - \sigma(t))) + g_1(t, x(t - \sigma(t)))) = \lambda e(t). \quad (3.16)$$

Let $\eta \in [0, T]$ be as in equation (3.3), for any $\eta \leq t \leq T$. From equations (3.3) and (3.15), we have

$$x(\eta - \sigma(\eta)) \geq D_1.$$

Next, we show that, for any $t \in [\eta, T]$, there exists a constant $D_3 \in (0, D_1)$ such that each positive T -periodic solution of equation (1.4) satisfies

$$x(t - \sigma(t)) > D_3.$$

In fact, multiplying both sides of equation (3.16) by $x'(t - \sigma(t))(1 - \sigma'(t))$ and integrating on $[\eta, t]$ yield that

$$\begin{aligned} \lambda \int_{x(\eta - \sigma(\eta))}^{x(t - \sigma(t))} g_0(u) du &= \lambda \int_{\eta}^t g_0(x(s - \sigma(s)))x'(s - \sigma(s))(1 - \sigma'(s)) ds \\ &= - \int_{\eta}^t ((Ax)(s))^{(4)} x'(s - \sigma(s))(1 - \sigma'(s)) ds \\ &\quad - \lambda \int_{\eta}^t f(x(s))x'(s)x'(s - \sigma(s))(1 - \sigma'(s)) ds \\ &\quad - \lambda \int_{\eta}^t g_1(s, x(s - \sigma(s)))x'(s - \sigma(s))(1 - \sigma'(s)) ds \\ &\quad + \lambda \int_{\eta}^t e(s)x'(s - \sigma(s))(1 - \sigma'(s)) ds. \end{aligned}$$

Furthermore, we have

$$\begin{aligned} \lambda \left| \int_{x(\eta - \sigma(\eta))}^{x(t - \sigma(t))} g_0(v) dv \right| &\leq \left| \int_{\eta}^t ((Ax)(s))^{(4)} x'(s - \sigma(s))(1 - \sigma'(s)) ds \right| \\ &\quad + \lambda \left| \int_{\eta}^t f(x(s))x'(s)x'(s - \sigma(s))(1 - \sigma'(s)) ds \right| \\ &\quad + \lambda \left| \int_{\eta}^t g_1(s, x(s - \sigma(s)))x'(s - \sigma(s))(1 - \sigma'(s)) ds \right| \\ &\quad + \lambda \left| \int_{\eta}^t e(s)x'(s - \sigma(s))(1 - \sigma'(s)) ds \right|. \end{aligned} \quad (3.17)$$

By using equations (3.1), (3.14) and (3.15), we have

$$\begin{aligned} \left| \int_{\eta}^t ((Ax)(s))^{(4)} x'(s - \sigma(s))(1 - \sigma'(s)) ds \right| &\leq \int_{\eta}^t |((Ax)(s))^{(4)}| |x'(s - \sigma(s))| |1 - \sigma'(s)| ds \\ &\leq \sigma^1 \|x'\| \int_0^T |((Ax)(s))^{(4)}| dt \\ &\leq \lambda \sigma^1 M_2 \left(\int_0^T |f(x(s))| |x'(s)| dt \right. \\ &\quad \left. + \int_0^T |g(s, x(s - \sigma(s)))| dt + \int_0^T |e(s)| dt \right) \\ &\leq \lambda \sigma^1 M_2 (\|f\|_{M_1} M_2 T + 2mTM_1 + 2nT + T\|e\|), \end{aligned}$$

where $|f|_{M_1} := \max_{0 < x \leq M_1} |f(x)|$ and $\sigma^1 := \max_{t \in [0, T]} |1 - \sigma'(t)|$. Besides, we have

$$\begin{aligned} \left| \int_{\eta}^t f(x(s))x'(s)x'(s - \sigma(s))(1 - \sigma'(s))ds \right| &\leq \sigma^1 M_2^2 \int_0^T |f(x(u(s)))|ds \leq (1 - \sigma_0^1) M_2^2 T |f|_{M_1}. \\ \left| \int_{\eta}^t g_1(s, x(s - \sigma(s)))x'(s - \sigma(s))(1 - \sigma'(s))ds \right| &\leq \sigma^1 M_2 \sqrt{T} \|g_{M_1}\|_2. \\ \left| \int_{\eta}^t e(s)x'(s - \sigma(s))(1 - \sigma'(s))ds \right| &\leq \sigma^1 M_2 T \|e\|. \end{aligned}$$

where $g_{M_1} = \max_{0 < x \leq M_1} |g_1(t, x)| \in L^2(0, T)$. From those inequalities and equation (3.17), we derive

$$\left| \int_{x(\eta - \sigma(\eta))}^{x(t - \sigma(t))} g_0(u)du \right| \leq \sigma^1 \left(2M_2 T \left(M_2 |f|_{M_1} + mM_1 + n + \frac{1}{2\sqrt{T}} \|g_{M_1}\|_2 + \|e\| \right) \right) := M_3. \quad (3.18)$$

In view of attractive condition (H_4) and $x(\eta - \sigma(\eta)) \geq D_1$, there exists $D_3 \in (0, D_1)$ such that

$$\left| \int_{D_1}^{D_3} g_0(v)dv \right| > M_3.$$

Thus, if there exists a point $\delta \in [0, T]$ such that $x(\eta - \sigma(\eta)) \leq D_3$, then

$$\left| \int_{x(\eta - \sigma(\eta))}^{x(\delta - \sigma(\delta))} g_0(v)dv \right| \geq \left| \int_{D_1}^{D_3} g_0(v)dv \right| > M_3,$$

which contradicts equation (3.18). Therefore, we can obtain that

$$x(t - \sigma(t)) \geq D_3, \quad \forall t \in [0, T]. \quad (3.19)$$

Letting $u = t - \sigma(t)$, we have

$$x(u) \geq D_3, \quad \forall u \in [\sigma(0), T - \sigma(T)],$$

i.e., $x(u) \geq D_3, \forall u \in [0, T]$, since $\sigma(0) = \sigma(T)$. Define

$$\Omega = \{x \in C_T^1(\mathbb{R}, \mathbb{R}) | E_1 \leq x \leq E_2, \|x'\| \leq E_3, \forall t \in [0, T]\},$$

where $0 < E_1 < \min(D_3, D_1)$, $E_2 > \max(M_1, D_2)$, $E_3 > M_2$. Let $\Omega_2 = \{x : x \in \partial\Omega \cap \text{Ker } L\}$. Then $\forall x \in \partial\Omega \cap \text{Ker } L$,

$$QNx = -\frac{1}{T} \int_0^T g(t, x(t - \sigma(t)))dt,$$

since $\int_0^T f(x(t))x'(t)dt = 0$ and $\int_0^T e(t)dt = 0$. If $QNx = 0$, then $x(t) = E_1$ or $x(t) = E_2$. But if $x(t) = E_2$, we know

$$\int_0^T g(t, E_2)dt = 0.$$

From condition (H_1) , we have $x(t) \leq E_2 \leq D_2$, which yields a contradiction. Similarly if $x_1 = E_1$, we also have $QNx \neq 0$, i.e., $\forall x \in \partial\Omega \cap \text{Ker } L$, $x \notin \text{Im } L$. So assumptions (1) and (2) of Lemma 2.1 are both satisfied. Let

$$H(\mu, x) = -\mu x - \frac{1 - \mu}{T} \int_0^T g(t, x(t - \sigma(t)))dt, \quad (\mu, x) \in [0, 1] \times \Omega.$$

From condition (H_1) , it is obvious that $xH(\mu, x) \neq 0, \forall (\mu, x) \in [0, 1] \times (\partial\Omega \cap \text{Ker } L)$. Hence

$$\begin{aligned} \deg\{QN|_{\text{Ker } L}, \Omega \cap \text{Ker } L, 0\} &= \deg\{H(0, x), \Omega \cap \text{Ker } L, 0\} \\ &= \deg\{H(1, x), \Omega \cap \text{Ker } L, 0\} \neq 0. \end{aligned}$$

So assumption (3) of Lemma 2.1 is satisfied. Applying Lemma 2.1, we conclude that equation $Lx = Nx$ has a solution x on $\bar{\Omega} \cap D(L)$, i.e., equation (1.4) has a positive T -periodic solution $x(t)$. This completes the proof.

4. PROOF OF THEOREM 1.6

We follow the same strategy and notation as in the proof of Theorem 1.2. We consider that there exists a positive constant M'_1 such that

$$\int_0^T |x''(t)|^2 dt \leq M'_1. \quad (4.1)$$

In fact, multiplying both side of equation (3.1) by $(Ax)(t)$ and integrating over $[0, T]$, we deduce

$$\begin{aligned} \int_0^T (Ax)^{(4)}(t)(Ax)(t)dt &= -\lambda \int_0^T f(x(t))x'(t)(Ax)(t)dt - \lambda \int_0^T g(t, x(t - \sigma(t)))(Ax)(t)dt \\ &\quad + \lambda \int_0^T e(t)(Ax)(t)dt. \end{aligned} \quad (4.2)$$

Note that

$$\begin{aligned} \int_0^T f(x(t))x'(t)(Ax)(t)dt &= \int_0^T f(x(t))x'(t)(x(t) - cx(t - \tau))dt \\ &= -c \int_0^T f(x(t))x'(t)x(t - \tau)dt \\ &= c \int_0^T F(x(t))x'(t - \tau)dt, \end{aligned} \quad (4.3)$$

where $F(x) = \int_0^x f(s)ds$. Substituting $\int_0^T (Ax)^{(4)}(t)(Ax)(t)dt = \int_0^T |(Ax)''(t)|^2 dt$ and (4.3) into (4.2), we see from condition (F_5) and equation (3.11) that

$$\begin{aligned} \int_0^T |(Ax)''(t)|^2 dt &\leq |c| \int_0^T |F(x(t))||x'(t - \tau)|dt + (1 + |c|)\|x\| \int_0^T |g(t, x(t - \sigma(t)))|dt \\ &\quad + (1 + |c|)\|x\| \int_0^T |e(t)|dt \\ &\leq \alpha |c| \int_0^T |x(t)||x'(t - \tau)|dt + \beta |c| \int_0^T |x'(t - \tau)|dt \\ &\quad + (1 + |c|)\|x\|(2mT\|x\| + 2nT) + (1 + |c|)T\|x\|\|e\| \\ &\leq \alpha |c|\|x\| \int_0^T |x'(t)|dt + \beta |c| \int_0^T |x'(t)|dt + (1 + |c|)2mT\|x\|^2 + N_1\|x\|, \end{aligned} \quad (4.4)$$

where

$$N_1 := (1 + |c|)(2nT + \|e\|T)$$

and

$$\int_0^T |x'(t - \tau)|dt = \int_0^T |x'(t)|dt.$$

Substituting (3.5) into (4.4), and applying the Hölder inequality and the Wirtinger inequality, we obtain

$$\begin{aligned}
\int_0^T |(Ax)''(t)|^2 dt &\leq \alpha|c| \left(D_2 + \int_0^T |x'(t)| dt \right) \int_0^T |x'(t)| dt + \beta|c| \int_0^T |x'(t)| dt \\
&\quad + (1+|c|)2mT \left(D_2 + \int_0^T |x'(t)| dt \right)^2 + N_1 \left(D_2 + \int_0^T |x'(t)| dt \right) \\
&= (\alpha|c| + (1+|c|)2mT) \left(\int_0^T |x'(t)| dt \right)^2 + (\alpha|c|D_2 + |c|\beta + (1+|c|)4mTD_2 + N_1) \\
&\quad \cdot \int_0^T |x'(t)| dt + (1+|c|)2mTD_2 + N_1D_2 \\
&\leq (\alpha|c| + (1+|c|)2mT)T \int_0^T |x'(t)|^2 dt + N_2T^{\frac{1}{2}} \left(\int_0^T |x'(t)|^2 dt \right)^{\frac{1}{2}} + N_3 \\
&\leq (\alpha|c| + (1+|c|)2mT)T \left(\frac{T}{2\pi} \right)^2 \int_0^T |x''(t)|^2 dt + N_2T^{\frac{1}{2}} \left(\frac{T}{2\pi} \right) \left(\int_0^T |x''(t)|^2 dt \right)^{\frac{1}{2}} + N_3,
\end{aligned} \tag{4.5}$$

where

$$N_2 := \alpha|c|D_2 + |c|\beta + (1+|c|)4mTD_2 + N_1$$

and

$$N_3 := (1+|c|)2mTD_2 + N_1D_2.$$

From (3.15), (4.5) and Lemma 2.2, we get

$$\begin{aligned}
\int_0^T |x''(t)|^2 dt &\leq \frac{(\alpha|c| + (1+|c|)2mT)T \left(\frac{T}{2\pi} \right)^2}{|1-|c||^2} \int_0^T |x''(t)|^2 dt \\
&\quad + \frac{N_2T \left(\frac{T}{2\pi} \right)}{|1-|c||^2} \left(\int_0^T |x''(t)| dt \right)^{\frac{1}{2}} + \frac{N_3}{|1-|c||^2}.
\end{aligned} \tag{4.6}$$

From equation (1.6), it is easy to verify that equation (4.1) hold. The proof left is as same as Theorem 1.2. This completes the proof.

5. PROOF OF THEOREMS 1.8 AND 1.9

Since the proof is similar, we only give the proof to Theorem 1.8. With the same method, we can prove Theorem 1.9. We follow the same strategy and notation as in the proof of Theorem 1.2. We only consider $\int_0^T |g(t, x(t - \sigma(t)))| dt$. From equations (3.11) and condition (F_4) , we have

$$\begin{aligned}
\int_0^T |g(t, x(t - \sigma(t)))| dt &= \int_{g(t, x) \geq 0} g(t, x(t - \sigma(t))) dt - \int_{g(t, x) \leq 0} g(t, x(t - \sigma(t))) dt \\
&= 2 \int_{g(t, x) \leq 0} g^+(t, x(t - \sigma(t))) dt \\
&\leq 2m \int_0^T x(t - \sigma(t)) dt + 2n \\
&\leq 2mT \|x\| + 2n,
\end{aligned} \tag{5.1}$$

The proof left is as same as Theorem 1.2.

6. EXAMPLES

In this section, we present two examples to illustrate the existence results involved in our Theorems.

Example 6.1. Consider the fourth-order differential equation with singularity of attractive type and time-dependent deviating arguments:

$$\left(x(t) - \frac{1}{10}x(t-\tau)\right)^{(4)} + f(x(t))x'(t) - \frac{1}{4\pi^2}(\sin 2t + 3)x(t - \cos^2 t) + \frac{1}{x^\kappa(t - \cos^2 t)} = \cos 2t \quad (6.1)$$

where $\kappa \geq 1$, f is a continuous function, τ is a constant and $0 \leq \tau < T$.

It is clear that $T = \pi$, $c = \frac{1}{10}$, $\sigma(t) = \cos^2 t$,

$$g(t, x) = -\frac{1}{4\pi^2}(\sin 2t + 3)x(t - \cos^2 t) + \frac{1}{x^\kappa(t - \cos^2 t)}$$

and $m = \frac{1}{\pi^2}$. It is obvious that $(H_1) - (H_4)$ hold. Now we consider

$$\begin{aligned} & \frac{(1 + |c|)|c| + 2mT^2 \left(\frac{T}{2\pi}\right)^2}{|1 - |c||^2} \\ &= \frac{\left(1 + \frac{1}{10}\right) \times \frac{1}{10} + 2 \times \frac{1}{4\pi^2} \times \pi^2 \times \left(\frac{\pi}{2\pi}\right)^2}{\left|1 - \frac{1}{10}\right|^2} \\ &= \frac{61}{81} < 1. \end{aligned}$$

From Theorem 1.2, we know equation (6.1) has at least one positive π -periodic solution.

Example 6.2. Consider the fourth-order equation with singularity of repulsive type:

$$(x(t) + 100x(t-\tau))^{(4)} + \left(e^{\cos x} + \frac{1}{2}\right)x'(t) + \frac{1}{10\pi}(\cos t + 4)x\left(t - \frac{1}{2}\sin t\right) + \frac{1}{x^\rho\left(t - \frac{1}{2}\sin t\right)} = \frac{1}{4}\sin t, \quad (6.2)$$

where $\rho \geq 1$, τ is a constant and $0 \leq \tau < T$. It is clear that $T = 2\pi$, $c = -100$, $\sigma(t) = \frac{1}{2}\sin t$, $g(t, x) = \frac{1}{10\pi}(\cos t + 4)x + \frac{1}{x^\rho}$, $m = \frac{1}{2\pi}$, $f(x) = e^{\cos x} + \frac{1}{2}$, $\alpha = \frac{1}{2}$. It is obvious that (F_2) , (F_4) , (F_5) and (H_3) , equation (1.2) hold. Now we consider

$$\begin{aligned} & \frac{(\alpha|c| + 2(1 + |c|)mT)T \left(\frac{T}{2\pi}\right)^2}{|1 - |c||^2} \\ &= \frac{\frac{1}{2} \times 100 + 2 \times 101 \times \frac{1}{2\pi} \times 2\pi}{99^2} \\ &= \frac{504\pi}{9801} < 1. \end{aligned}$$

Therefore, applying Theorem 1.8, we know equation (6.2) has at least one positive 2π -periodic solution.

7. CONCLUSION

In this paper, we discussed existence of a periodic solution for the fourth-order neutral differential equation with singularities of attractive and repulsive type and time-dependent deviating arguments. Due to the attractive condition is contradicted with the repulsive condition, the methods of [15, 16, 17] are no longer applicable to prove the existence of periodic solutions for the equation (1.4) with singularity of

attractive singularity. We obtained the existence of a positive periodic solution for equation (1.4) in the case that $|c| \neq 1$ by using the coincidence degree theory.

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