



EXISTENCE AND MULTIPLICITY OF SOLUTIONS FOR A CLASS OF FRACTIONAL HAMILTONIAN SYSTEMS WITH SEPARATED VARIABLES

MOHSEN TIMOUMI

Department of Mathematics, Faculty of Sciences, University of Monastir, Monastir 5000, Tunisia

Abstract. In this paper, we study the existence and multiplicity of solutions of a class of fractional Hamiltonian systems with variable separated type nonlinear terms

$$\begin{cases} {}_t D_{\infty}^{\alpha}(-_{\infty} D_t^{\alpha} u)(t) + L(t)u(t) = a(t)\nabla G(u(t)), & t \in \mathbb{R}, \\ u \in H^{\alpha}(\mathbb{R}), \end{cases}$$

where L satisfies a new condition and the potential G satisfies a superquadratic condition weaker than the well-known Ambrosetti-Rabinowitz condition. Moreover, under a new mixed condition, we establish a compact embedding theorem.

Keywords. Fractional Hamiltonian systems; Multiple solutions; Separated variables; Variational methods.

1. INTRODUCTION

In this paper, we are interested in the existence and multiplicity of solutions of a class of fractional Hamiltonian systems of the following form

$$(\mathcal{FHS}) \quad \begin{cases} {}_t D_{\infty}^{\alpha}(-_{\infty} D_t^{\alpha} u)(t) + L(t)u(t) = \nabla W(t, u(t)), & t \in \mathbb{R}, \\ u \in H^{\alpha}(\mathbb{R}), \end{cases}$$

where $_{\infty} D_t^{\alpha}$ and ${}_t D_{\infty}^{\alpha}$ are left and right Liouville-Weyl fractional derivatives of order $\frac{1}{2} < \alpha < 1$ on the whole axis respectively, $L \in C(\mathbb{R}, \mathbb{R}^{N^2})$ is a symmetric matrix valued function unnecessary coercive, and $W : \mathbb{R} \times \mathbb{R}^N \rightarrow \mathbb{R}$ is a continuous function, differentiable in the second variable with continuous derivative $\frac{\partial W}{\partial x}(t, x) = \nabla W(t, x)$.

The existence and multiplicity of solutions of fractional differential equations were established by the tools of nonlinear analysis, such as fixed point theory [1, 16], topological degree theory [7], comparison methods [9], and so on. Over the last four decades, the critical point theory has become a basic tool for studying the existence of solutions of differential and partial differential equations with variational methods; see, e.g., [14, 18] and the references therein.

E-mail address: m.timoumi@yahoo.com

Received April 15, 2023; Accepted July 12, 2023.

Inspired by the classical works in [14, 18], for the first time, the authors [8] demonstrated that the critical point theory and variational methods are an effective approach to tackle the existence of solutions for the following fractional boundary value problem

$$\begin{cases} {}_t D_T^\alpha ({}_0 D_t^\alpha u)(t) = \nabla W(t, u(t)), & t \in [0, T], \\ u(0) = u(T), \end{cases}$$

and obtained the existence of at least one nontrivial solution.

In 2013, Torres [25] used the so-called Ambrosetti-Rabinowitz ((\mathcal{AR}) in short) condition and the Mountain Pass Theorem to obtain the existence of at least one nontrivial solution for problem (\mathcal{FHS}):

(\mathcal{AR}) There exists a constant $\mu > 2$ such that

$$0 < \mu W(t, x) \leq \nabla W(t, x) \cdot x, \quad \forall t \in \mathbb{R}, \forall x \in \mathbb{R}^N \setminus \{0\}.$$

Here and in the following, " \cdot " denotes the standard inner product in \mathbb{R}^N and $|\cdot|$ is the induced norm.

Since then, the existence and multiplicity of solutions of (\mathcal{FHS}) were studied extensively; see, e.g., [3, 4, 5, 6, 12, 13, 15, 19, 20, 21, 22, 24, 25, 26, 27, 28, 29, 31, 32] and the references listed therein. As we know, condition (\mathcal{AR}) is important to achieve mountain pass geometry structure of the energy functional and demonstrates the boundedness of the Palais-Smale sequence. There are many potentials which are superquadratic as $|x| \rightarrow \infty$, but do not satisfy the (\mathcal{AR})–condition. In recent years, authors have paid much attention to weak this condition. In 2014, Chen [4] considered the following generalized superquadratic condition

(1.1) $\tilde{W}(t, x) = \frac{1}{2} \nabla W(t, x) \cdot x - W(t, x) \geq 0$ and there exist constants $c_0, r_0 > 0$ and $\sigma > 1$ such that

$$|W(t, x)|^\sigma \leq c_0 |x|^{2\sigma} \tilde{W}(t, x), \quad \forall (t, x) \in \mathbb{R} \times \mathbb{R}^N, |x| \geq r_0.$$

Instead of (1.1), the authors [4] considered also the superquadratic condition

(1.2) There exist constants $\mu > 2$ and $\rho > 0$ such that

$$\mu W(t, x) \leq \nabla W(t, x) \cdot x + \rho |x|^2, \quad \forall (t, x) \in \mathbb{R} \times \mathbb{R}^N.$$

In 2018, the author [23] considered the following generalized superquadratic condition

(1.3) There exist constant $c_0, r_0 > 0$ and $\nu \in [0, 2]$ such that

$$|W(t, x)| \leq c_0 |x|^{2-\nu} \tilde{W}(t, x), \quad \forall (t, x) \in \mathbb{R} \times \mathbb{R}^N, |x| \geq r_0.$$

Besides, in [21], the author considered the following condition

(1.4) There is $\sigma \geq 1$ such that

$$\tilde{W}(t, sx) \leq \sigma \tilde{W}(t, x), \quad \forall (s, t, x) \in [0, 1] \times \mathbb{R} \times \mathbb{R}^N.$$

Conditions (1.1)-(1.4) can be seen as the generalization or supplements of (\mathcal{AR})–condition. In [30], Yuan and Zhang considered the classical Hamiltonian system

$$(\mathcal{HS}) \quad \ddot{u}(t) - L(t)u(t) + \nabla W(t, u(t)) = 0$$

with variable separated type nonlinear terms $W(t, x) = a(t)G(x)$, where $a \in C(\mathbb{R}, \mathbb{R}_+^*)$ and $G \in C^1(\mathbb{R}^N, \mathbb{R})$. They studied the existence and multiplicity of homoclinic solutions of system (\mathcal{HS}) under suitable assumptions. In particular, they assumed that a satisfies condition $\lim_{|t| \rightarrow \infty} a(t) = 0$, and G satisfies (\mathcal{AR})–condition. In recent years, Wu et al. [27] considered the fractional Hamiltonian system (\mathcal{FHS}) with variable separated type nonlinear terms

$W(t, x) = a(t)G(x)$, where $a \in C(\mathbb{R}, \mathbb{R}_+)$ and $G \in C^1(\mathbb{R}^N, \mathbb{R})$. They studied the existence and multiplicity of solutions of system (\mathcal{FHS}) under suitable assumptions among which the following two conditions

$$(1.5) \quad \frac{a(t)}{l(t)} \longrightarrow 0 \text{ as } |t| \longrightarrow \infty, \text{ where } l(t) = \inf_{|\xi|=1} L(t)\xi \cdot \xi.$$

(1.6) There are $\mu > 0$ and $d_1, \rho_\infty > 0$ satisfying

$$\nabla G(x) \cdot x - \mu G(x) \geq -d_1 |x|^2, \quad \forall |x| \geq \rho_\infty.$$

Condition (1.6) is a generalization of (\mathcal{AR}) -condition.

In this paper, inspired by the above results, we focus on the existence and multiplicity of solutions of the fractional Hamiltonian system (\mathcal{FHS}) with variable separation nonlinear terms $W(t, x) = a(t)G(x)$, where $a \in C(\mathbb{R}, \mathbb{R}_+^*)$, L satisfies a new condition, and $G \in C^1(\mathbb{R}^N, \mathbb{R})$ satisfies some kind of superquadratic conditions weaker than well-known Ambresetti-Rabinowitz condition. Precisely, we consider the following assumptions

(L_1) $L \in C(\mathbb{R}, \mathbb{R}^{N^2})$ is a symmetric matrix for all $t \in \mathbb{R}$, and there exists a constant $l_0 > 0$ such that

$$L(t)x \cdot x \geq l_0 |x|^2, \quad \forall (t, x) \in \mathbb{R} \times \mathbb{R}^N;$$

(L_2) There is a constant $d > 0$ verifying

$$a(t) \leq dl(t), \quad \forall t \in \mathbb{R};$$

(L_3) There exists a constant $r_0 > 0$ satisfying

$$\lim_{|s| \rightarrow \infty} \text{meas} \left(\left\{ t \in [s - r_0, s + r_0] / \frac{l(t)}{a(t)} < b \right\} \right) = 0, \quad \forall b > 0;$$

$$(G_1) \quad G(0) = 0, \text{ and } \nabla G(x) = o(|x|) \text{ as } |x| \longrightarrow 0;$$

$$(G_2) \quad \lim_{|x| \rightarrow \infty} \frac{G(x)}{|x|^2} = +\infty;$$

$$(G_3) \quad \tilde{G}(t, x) = \frac{1}{2} \nabla G(x) \cdot x - G(x) \geq 0, \quad \forall x \in \mathbb{R}^N;$$

$$(G_4) \quad \lim_{|x| \rightarrow \infty} \frac{\tilde{G}(x)}{G(x)} |x|^2 = +\infty.$$

Our first results are the following:

Theorem 1.1. *If $(L_1) - (L_3)$ and $(G_1) - (G_4)$ hold, then fractional Hamiltonian system (\mathcal{FHS}) has at least one nontrivial solution.*

Theorem 1.2. *Assume that $(L_1) - (L_3)$ and $(G_1) - (G_4)$ are satisfied and G is even. Then fractional Hamiltonian system (\mathcal{FHS}) possesses infinitely many nontrivial solutions.*

Remark 1.3. Consider the following example

$$G(x) = |x|^s + (s-2)|x|^{s-\varepsilon} \sin^2\left(\frac{|x|^\varepsilon}{\varepsilon}\right),$$

where $s > 2$ and $\varepsilon \in]0, s-2[$. It is easy to check that G satisfies conditions $(G_1) - (G_4)$, however G satisfies neither condition (\mathcal{AR}) nor its generalization (1.6).

Next, consider the assumptions

(G_5) There are $d_0 > 0$ and $\nu > 2$ satisfying

$$|G(x)| \leq d_0(|x|^2 + |x|^\nu), \quad \forall x \in \mathbb{R}^N;$$

(G_6) There is a constant $\sigma \geq 1$ satisfying

$$\tilde{G}(sx) \leq \sigma \tilde{G}(x), \quad \forall (s, x) \in [0, 1] \times \mathbb{R}^N.$$

Now, we give our second results

Theorem 1.4. Assume that $(L_1) - (L_3)$, (G_1) , (G_2) , (G_5) , and (G_6) are satisfied. Then fractional Hamiltonian system (\mathcal{FHS}) admits at least one nontrivial solution.

Theorem 1.5. Assume that $(L_1) - (L_3)$, (G_1) , (G_2) , (G_5) , and (G_6) are satisfied and G is even. Then fractional Hamiltonian system (\mathcal{FHS}) possesses infinitely many nontrivial solutions.

Remark 1.6. Let $G(x) = |x|^2 \ln(e + |x|) - \frac{1}{2}|x|^2 + e|x| - e^2(\ln(e + |x|) - 1)$. It is easy to check that (G_1) , (G_2) , (G_5) , and (G_6) hold. However, G satisfies neither condition (\mathcal{AR}) nor its generalization (1.6).

Remark 1.7. Let $G(x) = |x|^2 \ln(1 + |x|^2)$. Then we easily demonstrate that conditions (G_1) , (G_2) , (G_5) , and (G_6) hold. However, G does not satisfy (\mathcal{AR}) -condition.

The remaining of this paper is organized as follows. In Section 2, we introduce some preliminary results and prove an interesting compact embedding theorem. Section 3 is reserved to the proof of our main results.

2. PRELIMINARIES

2.1. Liouville-Weyl fractional calculus. The Liouville-Weyl fractional integrals of order $0 < \alpha < 1$ on the whole axis \mathbb{R} are defined as (see [10, 11, 17])

$$(2.1) \quad {}_{-\infty}I_t^\alpha u(t) = \frac{1}{\Gamma(\alpha)} \int_{-\infty}^t (t-x)^{\alpha-1} u(x) dx,$$

and

$$(2.2) \quad {}_tI_\infty^\alpha u(t) = \frac{1}{\Gamma(\alpha)} \int_t^\infty (x-t)^{\alpha-1} u(x) dx.$$

The Liouville-Weyl fractional derivatives of order $0 < \alpha < 1$ on the whole axis \mathbb{R} are defined as the left-inverse operators of the corresponding Liouville-Weyl fractional integrals (see [10, 11, 17])

$$(2.3) \quad {}_{-\infty}D_t^\alpha u(t) = \frac{d}{dt}({}_{-\infty}I_t^{1-\alpha} u)(t),$$

and

$$(2.4) \quad {}_tD_\infty^\alpha u(t) = -\frac{d}{dt}({}_tI_\infty^{1-\alpha}u)(t).$$

The definitions of (2.3) and (2.4) may be written in an alternative form as follows

$$(2.5) \quad {}_{-\infty}D_t^\alpha u(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^\infty \frac{u(t) - u(t-x)}{x^{\alpha+1}} dx,$$

and

$$(2.6) \quad {}_tD_\infty^\alpha u(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^\infty \frac{u(t) - u(t+x)}{x^{\alpha+1}} dx.$$

2.2. Fractional derivative space. For $\alpha > 0$, define the semi-norm

$$|u|_{I_{-\infty}^\alpha} = \|{}_{-\infty}D_t^\alpha u\|_{L^2}$$

and the norm

$$\|u\|_{I_{-\infty}^\alpha} = (\|u\|_{L^2} + |u|_{I_{-\infty}^\alpha}^2)^{\frac{1}{2}},$$

and let

$$I_{-\infty}^\alpha = \overline{C_0^\infty(\mathbb{R})}^{\|\cdot\|_{I_{-\infty}^\alpha}},$$

where

$$C_0^\infty(\mathbb{R}) = \left\{ u \in C^\infty(\mathbb{R}, \mathbb{R}^N) / \lim_{|t| \rightarrow \infty} u(t) = 0. \right\}.$$

Now, we can define the fractional Sobolev space $H^\alpha(\mathbb{R})$ using the Fourier transform $\widehat{u}(s) = \int_{-\infty}^\infty e^{-ist} u(t) dt$. Choose $0 < \alpha < 1$, define the semi-norm

$$|u|_\alpha = \||s|^\alpha \widehat{u}\|_{L^2}$$

and the norm

$$\|u\|_\alpha = (\|u\|_{L^2} + |u|_\alpha^2)^{\frac{1}{2}},$$

and let

$$H^\alpha(\mathbb{R}) = \overline{C_0^\infty(\mathbb{R})}^{\|\cdot\|_\alpha}.$$

Moreover, we notice that a function $u \in L^2(\mathbb{R})$ belongs to $I_{-\infty}^\alpha$ if and only if

$$|s|^\alpha \widehat{u} \in L^2(\mathbb{R}).$$

Especially, we have

$$|u|_{I_{-\infty}^\alpha} = \||s|^\alpha \widehat{u}\|_{L^2}.$$

Therefore, $I_{-\infty}^\alpha$ and $H^\alpha(\mathbb{R})$ are isomorphic with equivalent semi-norms and norms.

Let $C(\mathbb{R})$ denote the space of continuous functions from \mathbb{R} into \mathbb{R}^N . The following Sobolev lemma is be useful.

Lemma 2.1. [25, Theorem 2.1] *If $\alpha > \frac{1}{2}$, then $H^\alpha(\mathbb{R}) \subset C(\mathbb{R})$, and there exists a constant C_α such that*

$$(2.7) \quad \|u\|_{L^\infty} = \sup_{t \in \mathbb{R}} |u(t)| \leq C_\alpha \|u\|_\alpha, \forall u \in H^\alpha(\mathbb{R}).$$

Let

$$X^\alpha = \left\{ u \in H^\alpha(\mathbb{R}) / \int_{\mathbb{R}} [|_{-\infty}D_t^\alpha u(t)|^2 + L(t)u(t) \cdot u(t)] dt < \infty \right\},$$

then X^α is a reflexive and separable Hilbert space with the inner product

$$\langle u, v \rangle_{X^\alpha} = \int_{\mathbb{R}} [_{-\infty}D_t^\alpha u(t) \cdot _{-\infty}D_t^\alpha v(t) + L(t)u(t) \cdot v(t)] dt$$

and the corresponding norm $\|u\|_{X^\alpha}^2 = \langle u, u \rangle_{X^\alpha}$. Evidently, X^α is continuously embedded into $H^\alpha(\mathbb{R})$. For $p \in [2, \infty[$, define

$$L_a^p(\mathbb{R}) = \left\{ u : \mathbb{R} \longrightarrow \mathbb{R}^N \text{ measurable} / \int_{\mathbb{R}} a(t) |u(t)|^p < \infty \right\}$$

equipped with norm $\|\cdot\|_{L_a^p} = \left(\int_{\mathbb{R}} a(t) |u(t)|^p \right)^{\frac{1}{p}}$. By (L_2) , we have for $u \in X^\alpha$

$$\begin{aligned} \int_{\mathbb{R}} a(t) |u(t)|^2 dt &\leq d \int_{\mathbb{R}} l(t) |u(t)|^2 dt \leq d \int_{\mathbb{R}} L(t)u(t) \cdot u(t) dt \\ &\leq d \int_{\mathbb{R}} [|_{-\infty}D_t^\alpha u(t)|^2 + L(t)u(t) \cdot u(t)] dt \\ &= \eta_2^2 \|u\|_{X^\alpha}^2, \end{aligned}$$

where $\eta_2 = \sqrt{d}$. For $p \in]2, \infty[$ and $u \in X^\alpha$, we have

$$\int_{\mathbb{R}} a(t) |u(t)|^p dt \leq \|u\|_{L^\infty}^{p-2} \int_{\mathbb{R}} a(t) |u(t)|^2 dt \leq C_\alpha^{p-2} \|u\|_{X^\alpha}^{p-2} \|u\|_{L_a^2}^2 \leq \eta_p^p \|u\|_{X^\alpha}^p,$$

where $\eta_p^p = dC_\alpha^{p-2}$. Hence, for all $p \in [2, \infty[$, X^α is continuously embedded in $L_a^p(\mathbb{R})$ and there exists a constant $\eta_p > 0$ such that

$$(2.8) \quad \|u\|_{L_a^p} \leq \eta_p \|u\|_{X^\alpha}, \quad \forall u \in X^\alpha.$$

Lemma 2.2. *Under conditions $(L_1) - (L_3)$, for all $p \in [2, \infty[$, embedding $X^\alpha \hookrightarrow L_a^p(\mathbb{R})$ is compact.*

Proof. Let $\{u_n\} \subset X^\alpha$ be a bounded sequence. Then there exists $M_0 > 0$ such that

$$\|u_n\|_{X^\alpha} \leq M_0, \quad \forall n \in \mathbb{N}.$$

Taking a subsequence if necessary, we can assume that $u_n \rightharpoonup u_0$ in X^α . Setting $v_n = u_n - u_0$, one has $v_n \rightharpoonup 0$ in X^α .

Next, we prove that $v_n \rightarrow 0$ in $L_a^2(\mathbb{R})$. Choose $\{s_i\} \subset \mathbb{R}$ such that $\mathbb{R} = \cup_{i=1}^\infty I_{r_0}(s_i)$ and each $t \in \mathbb{R}$ is contained by two such intervals $I_{r_0}(s_i) = [s_i - r_0, s_i + r_0]$ at most. For $b, r > 0$, set

$$A(b, r) = \left\{ t \in I_r^c(0) : \frac{l(t)}{a(t)} < b \right\}$$

and

$$B(b, r) = \left\{ t \in I_r^c(0) : \frac{l(t)}{a(t)} \geq b \right\}.$$

We have

$$\int_{B(b, r)} a(t) |v_n(t)|^2 dt \leq \frac{1}{b} \int_{B(b, r)} l(t) |v_n(t)|^2 dt \leq \frac{1}{b} \|v_n\|_{X^\alpha}^2 \leq \frac{4M_0^2}{b}.$$

Letting $\varepsilon > 0$, one has that there exists a constant $b_\varepsilon > 0$ such that

$$(2.10) \quad \int_{B(b_\varepsilon, r)} a(t) |v_n(t)|^2 dt < \frac{\varepsilon}{4}, \quad \forall n \in \mathbb{N}, \quad \forall r > 0.$$

Now, let $\beta_r = \sup_{i \in \mathbb{N}} \text{meas}_a(A(b_\varepsilon, r) \cap I_{r_0}(s_i))$. By (2.8) and Hölder's inequality, we obtain

$$\begin{aligned} & \int_{A(b_\varepsilon, r)} a(t) |v_n(t)|^2 dt \\ &= \int_{A(b_\varepsilon, r) \cap \bigcup_{i=1}^{\infty} I_{r_0}(s_i)} a(t) |v_n(t)|^2 dt \\ &\leq \sum_{i=1}^{\infty} \int_{A(b_\varepsilon, r) \cap I_{r_0}(s_i)} a(t) |v_n(t)|^2 dt \\ &\leq \sum_{i=1}^{\infty} \left(\int_{A(b_\varepsilon, r) \cap I_{r_0}(s_i)} a(t) dt \right)^{\frac{1}{2}} \left(\int_{A(b_\varepsilon, r) \cap I_{r_0}(s_i)} a(t) |v_n(t)|^4 dt \right)^{\frac{1}{2}} \\ &\leq \sum_{i=1}^{\infty} (\text{meas}_a(A(b_\varepsilon, r) \cap I_{r_0}(s_i)))^{\frac{1}{2}} \left[\int_{A(b_\varepsilon, r) \cap I_{r_0}(s_i)} a(t) |v_n(t)|^4 dt \right]^{\frac{1}{4}} \\ &\leq \beta_r^{\frac{1}{2}} \sum_{i=1}^{\infty} \left[\int_{A(b_\varepsilon, r) \cap I_{r_0}(s_i)} a(t) |v_n(t)|^4 dt \right]^{\frac{1}{4}} \\ &\leq \beta_r^{\frac{1}{2}} \eta_4^2 \sum_{i=1}^{\infty} \int_{A(b_\varepsilon, r) \cap B_{r_0}(s_i)} [|_{-t} D_\infty^\alpha v_n(t)|^2 + L(t) v_n(t) \cdot v_n(t)] dt \\ &\leq 2\eta_4^2 \beta_r^{\frac{1}{2}} \|v_n\|_{X^\alpha}^2 \leq 8\eta_4^2 \beta_r^{\frac{1}{2}} M_0^2. \end{aligned}$$

By (L_3) , there is a constant $r_\varepsilon > 0$ satisfying

$$(2.11) \quad \int_{A(b_\varepsilon, r_\varepsilon)} a(t) |v_n(t)|^2 dt < \frac{\varepsilon}{4}, \quad \forall n \in \mathbb{N}.$$

Combining (2.10) and (2.11) yields

$$(2.12) \quad \begin{aligned} \int_{I_\varepsilon^c(0)} a(t) |v_n(t)|^2 dt &= \int_{A(b_\varepsilon, r_\varepsilon)} a(t) |v_n(t)|^2 dt + \int_{B(b_\varepsilon, r_\varepsilon)} a(t) |v_n(t)|^2 dt \\ &< \frac{\varepsilon}{2}, \quad \forall n \in \mathbb{N}. \end{aligned}$$

On the other hand, the Sobolev's compact embedding theorem implies that $v_n \rightarrow 0$ in $L_a^2(I_{r_\varepsilon}(0))$. Hence, there exists a constant $n_0 \in \mathbb{N}$ such that

$$(2.13) \quad \int_{I_\varepsilon^c(0)} a(t) |v_n(t)|^2 dt < \frac{\varepsilon}{2}, \quad \forall n \geq n_0,$$

which with (2.12) implies that $v_n \rightarrow 0$ in $L_a^2(\mathbb{R})$. For $p \in]2, \infty[$, we have

$$\begin{aligned} \int_{\mathbb{R}} a(t) |v_n(t)|^p dt &\leq \|v_n\|_{L^\infty}^{p-2} \int_{\mathbb{R}} a(t) |v_n(t)|^2 dt \\ &\leq C_\alpha^{p-2} \|v_n\|_{X^\alpha}^{p-2} \|v_n\|_{L_a^2}^2 \\ &\leq C_\alpha^{p-2} (2M_0)^{p-2} \|v_n\|_{L_a^2}^2. \end{aligned}$$

Hence $v_n \rightarrow 0$ as $n \rightarrow \infty$, and embedding $X^\alpha \hookrightarrow L_a^p(\mathbb{R})$ is compact. \square

The following critical point lemmas is needed in the proof of our results.

Definition 2.3. Let X be a Banach space with norm $\|\cdot\|$. We say that $f \in C^1(X, \mathbb{R})$ satisfies

a) (PS)–condition if any sequence $(u_n) \subset X$ satisfying

$$(f(u_n)) \text{ is bounded and } f'(u_n) \longrightarrow 0 \text{ as } n \longrightarrow \infty$$

has a convergent subsequence,

b) (C)–condition if any sequence $(u_n) \subset X$ satisfying

$$(f(u_n)) \text{ is bounded and } \|f'(u_n)\| (1 + \|u_n\|) \longrightarrow 0 \text{ as } n \longrightarrow \infty$$

possesses a convergent subsequence.

Lemma 2.4. [18] Let X be a real Banach space, and let $f \in C^1(X, \mathbb{R})$ satisfy (PS)-condition. Suppose that $f(0) = 0$ and

(i) there are $\rho, \alpha > 0$, such that $f|_{\partial B_\rho} \geq \alpha$, where $B_\rho = \{u \in X / \|u\| < \rho\}$,

(ii) there is an $e \in X \setminus \bar{B}_\rho$ such that $f(e) < 0$.

Then f has a critical value $c \geq \alpha$. Moreover c can be characterized as

$$c = \inf_{\gamma \in \Gamma} \max_{t \in [0,1]} f(\gamma(t)),$$

where

$$\Gamma = \{\gamma \in C([0,1], X) : \gamma(0) = 0, \gamma(1) = e\}.$$

Lemma 2.5. [18] Let X be an infinite dimensional Banach space, $X = Y \oplus Z$, where Y is finite dimensional space, and let $f \in C^1(X, \mathbb{R})$ satisfy (PS)–condition. Assume that $f(0) = 0$, f is even, and

(a) There exist constants $\rho, \alpha > 0$ such that $f|_{\partial B_\rho \cap Z} \geq \alpha$;

(b) For any finite dimensional subspace $\tilde{X} \subset X$, there is $r = r(\tilde{X}) > 0$ such that $f(u) \leq 0$ on $\tilde{X} \setminus B_r$.

Then f possesses an unbounded sequence of critical values.

Remark 2.6. As in [2], a deformation lemma can be proved with (C)–condition replacing (PS)–condition, and it turns out that Lemmas 2.4 and 2.5 still hold true with (C)–condition instead of (PS)–condition.

3. PROOF OF THEOREM 1.1 AND THEOREM 1.2

Define the energy functional f associated to the fractional Hamiltonian system (\mathcal{FHS})

$$f(u) = \frac{1}{2} \int_{\mathbb{R}} [|_{-\infty}D_t^\alpha u(t)|^2 + L(t)u(t) \cdot u(t)] dt - \int_{\mathbb{R}} W(t, u) dt, \quad u \in X^\alpha$$

defined on the space X^α introduced in Section 2. It is known that, under assumption (G_1) , $f \in C^1(X^\alpha, \mathbb{R})$ and, for all $u, v \in X^\alpha$,

$$\begin{aligned} f'(u)v &= \int_{\mathbb{R}} [_{-\infty}D_t^\alpha u(t) \cdot _{-\infty}D_t^\alpha v(t) + L(t)u(t) \cdot v(t)] dt - \int_{\mathbb{R}} \nabla W(t, u) \cdot v(t) dt \\ &= \frac{1}{2} \langle u, v \rangle_{X^\alpha} - \int_{\mathbb{R}} \alpha(t) \nabla G(u(t)) \cdot v(t) dt. \end{aligned}$$

Moreover, the critical points of f on X^α are solutions to $(\mathcal{F}\mathcal{H}\mathcal{S})$. We shall prove that problem $(\mathcal{F}\mathcal{H}\mathcal{S})$ has mountain pass type solutions. For this purpose, we apply Lemmas 2.4 and 2.5 to functional f on X^α . We claim that, under (G_1) and (G_3) ,

$$(3.1) \quad G(x) \geq 0, \quad \forall x \in \mathbb{R}.$$

In fact, for $x \in \mathbb{R}^N \setminus \{0\}$, set $\varphi(s) = \frac{G(sx)}{s^2}$ for $s > 0$. By (G_3) , we have, for $s \in]0, \infty[$,

$$\varphi'(s) = \frac{2}{s^3} \left[\frac{1}{2} \nabla G(sx) \cdot sx - G(sx) \right] \geq 0,$$

which means that φ is non-decreasing in $]0, \infty[$. Now, we have by (G_1) and the Hopital's property

$$\lim_{s \rightarrow 0} |\varphi(s)| = \lim_{s \rightarrow 0} \frac{|G(sx)|}{s^2} = \lim_{s \rightarrow 0} \frac{|\nabla G(sx) \cdot x|}{2s} \leq \lim_{s \rightarrow 0} \frac{1}{2} \frac{|\nabla G(sx)|}{|sx|} |x|^2 = 0.$$

Hence, we have $\varphi(s) \geq 0$ for all $s \in]0, \infty[$. In particular $\varphi(1) \geq 0$, which is (3.1).

Lemma 3.1. *Under conditions $(L_1) - (L_3)$ and (G_1) , there are constants $\rho, \nu > 0$ satisfying $f|_{\partial B_\rho(0)} \geq \nu$.*

Proof. By (G_1) , there is $r > 0$ verifying

$$(3.2) \quad |G(x)| \leq \frac{1}{4d} |x|^2, \quad \forall |x| \leq r.$$

Set $\rho = \frac{r}{\eta_\infty}$ and $\nu = \frac{\rho^2}{4}$. By (3.2) and (L_2) , we have, for $\|u\|_{X^\alpha} = \rho$,

$$(3.3) \quad \begin{aligned} f(u) &= \frac{1}{2} \|u\|_{X^\alpha}^2 - \int_{\mathbb{R}} a(t) G(u(t)) dt \\ &\geq \frac{1}{2} \|u\|_{X^\alpha}^2 - \frac{1}{4d} \int_{\mathbb{R}} a(t) |u(t)|^2 dt \\ &\geq \frac{1}{2} \|u\|_{X^\alpha}^2 - \frac{1}{4} \int_{\mathbb{R}} l(t) |u(t)|^2 dt \\ &\geq \frac{1}{4} \|u\|_{X^\alpha}^2 = \nu. \end{aligned}$$

The proof of Lemma 3.1 is completed. \square

Lemma 3.2. *Assume that $(L_1) - (L_3)$ and (G_1) are satisfied. Then $\nabla G(u_n) \rightarrow \nabla G(u)$ in $L_a^2(\mathbb{R})$ if $u_n \rightharpoonup u$ in X^α .*

Proof. Let $u_n \rightharpoonup u$ in X^α . Then there exists $K > 0$ such that

$$(3.4) \quad \sup_{n \in \mathbb{N}} \|u_n\|_{X^\alpha} \leq K \text{ and } \|u_n\|_{L^\infty} \leq K, \quad \forall n \in \mathbb{N}.$$

We claim that $\nabla G(u_n) \rightarrow \nabla G(u)$ in $L_a^2(\mathbb{R})$. Otherwise, by Lemma 2.2, there is a subsequence (u_{n_k}) satisfying

$$(3.5) \quad u_{n_k} \rightarrow u \text{ in } L_a^2(\mathbb{R}) \text{ and } u_{n_k}(t) \rightarrow u(t) \text{ a.e.}$$

and

$$(3.6) \quad \int_{\mathbb{R}} a(t) |\nabla G(u_{n_k}(t)) - \nabla G(u(t))| dt \geq \varepsilon_0, \quad \forall k \in \mathbb{N}$$

for some $\varepsilon_0 > 0$. By (3.5) and going to a subsequence if necessary, we can assume that $\sum_{k=1}^{\infty} \|u_{n_k} - u\|_{L_a^2} < \infty$. Let $v(t) = \sum_{k=1}^{\infty} |u_{n_k}(t) - u(t)|$ for all $t \in \mathbb{R}$. Then $v \in L_a^2(\mathbb{R})$. From (G_1) and (3.4), we can find a constant $K_1 > 0$ such that

$$(3.7) \quad |\nabla G(u_{n_k}(t))| \leq K_1 |u_{n_k}(t)| \text{ and } |\nabla G(u(t))| \leq K_1 |u(t)|, \forall k \in \mathbb{N},$$

which implies

$$\begin{aligned} |\nabla G(u_{n_k}(t)) - \nabla G(u(t))|^2 &\leq K_1^2 [|u_{n_k}(t)| + |u(t)|]^2 \\ &\leq K_1^2 [|u_{n_k}(t) - u(t)| + 2|u(t)|]^2 \\ &\leq 8K_1^2 [|v(t)| + |u(t)|]^2 = h(t). \end{aligned}$$

Since $h \in L_a^2(\mathbb{R})$, then the Lebesgue's dominated convergence theorem implies

$$\lim_{k \rightarrow \infty} \int_{\mathbb{R}} a(t) |\nabla G(u_{n_k}(t)) - \nabla G(u(t))|^2 dt = \int_{\mathbb{R}} a(t) \lim_{k \rightarrow \infty} |\nabla G(u_{n_k}(t)) - \nabla G(u(t))|^2 dt = 0,$$

which contradict (3.6). Hence the claim above is true and the proof of Lemma 3.2 is completed. \square

Lemma 3.3. *Under assumptions $(L_1) - (L_3)$, (G_1) , (G_2) , and (G_4) , f verifies the (C)-condition.*

Proof. Let $\{u_n\} \subset X^\alpha$ be a (C)-sequence of f , that is, $(f(u_n))$ is bounded and $\|f'(u_n)\| (1 + \|u_n\|) \rightarrow 0$ as $n \rightarrow \infty$. Then there exists a constant $c_1 > 0$ such that

$$(3.8) \quad |f(u_n)| \leq c_1 \text{ and } \|f'(u_n)\| (1 + \|u_n\|_{X^\alpha}) \leq c_1, \forall n \in \mathbb{N}.$$

We claim that (u_n) is bounded. Otherwise, we assume that $\|u_n\|_{X^\alpha} \rightarrow \infty$ as $n \rightarrow \infty$. Setting $v_n = \frac{u_n}{\|u_n\|_{X^\alpha}}$, one has $\|v_n\|_{X^\alpha} = 1$, which implies that there is a subsequence of (v_n) , still denoted by (v_n) , such that $v_n \rightharpoonup v_0$ in X^α . We have

$$\left| \int_{\mathbb{R}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt - \frac{1}{2} \right| = \frac{|-f(u_n)|}{\|u_n\|^2} \leq \frac{c_1}{\|u_n\|^2},$$

which implies that

$$(3.9) \quad \int_{\mathbb{R}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt \rightarrow \frac{1}{2} \text{ as } n \rightarrow \infty.$$

We will discuss two cases.

Case 1: $v_0 \neq 0$.

Let $\Lambda = \{t \in \mathbb{R} / v_0(t) \neq 0\}$. Then we can see that $meas_a(\Lambda) > 0$. So there exists a constant $R > 0$ such that $meas_a(\Omega) > 0$, where $\Omega = \Lambda \cap B_R(0)$. Since $\|u_n\|_{X^\alpha} \rightarrow \infty$ as $n \rightarrow \infty$, we have $|u_n(t)| = |v_n(t)| \|u_n\|_{X^\alpha} \rightarrow +\infty$ as $n \rightarrow \infty$ for a.e $t \in \Omega$. By (G_2) , (3.1), and Fatou's lemma, we have

$$\begin{aligned} \liminf_{n \rightarrow \infty} \int_{\mathbb{R}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt &\geq \liminf_{n \rightarrow \infty} \int_{\Omega} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt \\ &\geq \int_{\Omega} \liminf_{n \rightarrow \infty} \frac{a(t)G(u_n(t))}{|u_n(t)|^2} |v_n(t)|^2 dt \\ &= +\infty, \end{aligned}$$

which can contradict (3.9). Hence (u_n) is bounded.

Case 2: $v_0 = 0$.

By (G_1) , there exists a constant $r > 0$ such that

$$(3.10) \quad 0 \leq G(x) \leq |x|^2, \quad \forall |x| \leq r.$$

By (G_4) , for any $M > 0$, there exists $R > r$ such that

$$(3.11) \quad \frac{\tilde{G}(x)}{G(x)} |x|^2 \geq M, \quad \forall |x| \geq R.$$

Combining (3.10) and (3.11) yields

$$\begin{aligned} 0 &\leq \int_{\mathbb{R}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt \leq \int_{\{t \in \mathbb{R}/|u_n| \leq r\}} \frac{a(t)G(u_n(t))}{|u_n(t)|^2} |v_n(t)|^2 dt \\ &+ \int_{\{t \in \mathbb{R}/r < |u_n| \leq R\}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt + \int_{\{t \in \mathbb{R}/|u_n| \geq R\}} \frac{a(t)G(u_n(t))}{|u_n(t)|^2} |v_n(t)|^2 dt \\ &\leq \int_{\{t \in \mathbb{R}/|u_n| \leq r\}} a(t) |v_n(t)|^2 dt + \int_{\{t \in \mathbb{R}/r < |u_n| \leq R\}} \frac{a(t)G(u_n(t))}{r^2 \|u_n\|^2} |u_n(t)|^2 dt \\ &+ \|v_n\|_{L^\infty} \int_{\{t \in \mathbb{R}/|u_n| \geq R\}} \frac{a(t)G(u_n(t))}{|u_n(t)|^2} dt \\ &\leq \|v_n\|_{L_a^2}^2 + \frac{1}{r^2} \max_{|x| \leq r} G(x) \int_{\{t \in \mathbb{R}/r < |u_n| \leq R\}} a(t) |v_n(t)|^2 dt \\ &+ \frac{1}{M} \|v_n\|_{L^\infty} \int_{\{t \in \mathbb{R}/|u_n| \geq R\}} a(t) \left[\frac{1}{2} \nabla G(u_n(t)) \cdot u_n(t) - G(u_n(t)) \right] dt \\ &\leq \left(1 + \frac{1}{r^2} \max_{|x| \leq r} G(x)\right) \|v_n\|_{L_a^2}^2 + \frac{1}{M} \|v_n\|_{L^\infty} [f(u_n) - \frac{1}{2} f'(u_n)u_n] \\ &\leq \left(1 + \frac{1}{r^2} \max_{|x| \leq r} G(x)\right) \|v_n\|_{L_a^2}^2 + \frac{3c_1}{2M} \|v_n\|_{L^\infty}. \end{aligned}$$

By arbitrariness of M and Lemma 2.2, we obtain

$$\int_{\mathbb{R}} \frac{a(t)G(u_n(t))}{\|u_n\|^2} dt < \frac{1}{3}$$

for n large enough, which contradicts (3.9). Hence (u_n) is bounded in X^α . Up to a subsequence if necessary, we can assume that $u_n \rightharpoonup u$ in X^α , which yields

$$(f'(u_n) - f'(u))(u_n - u) \longrightarrow 0 \text{ as } n \longrightarrow \infty,$$

and it follows from Hölder's inequality and Lemma 3.2 that

$$\begin{aligned} &\left| \int_{\mathbb{R}} a(t) (\nabla G(u_n(t)) - \nabla G(u(t))) \cdot (u_n(t) - u(t)) dt \right| \\ &\leq \|\nabla G(u_n) - \nabla G(u)\|_{L_a^2} \|u_n - u\|_{L_a^2} \longrightarrow 0 \text{ as } n \rightarrow \infty. \end{aligned}$$

Hence, we deduce that

$$\|u_n - u\|_{X^\alpha}^2 = (f'(u_n) - f'(u))(u_n - u) + \int_{\mathbb{R}} a(t) (\nabla G(u_n(t)) - \nabla G(u(t))) \cdot (u_n(t) - u(t)) dt \longrightarrow 0$$

as $n \longrightarrow \infty$. The proof of Lemma 3.3 is completed. \square

Proof of Theorem 1.1.

Lemma 3.4. *Suppose that $(L_1) - (L_3)$ and (G_2) hold. Then there exists $e \in X^\alpha$ such that $\|e\|_{X^\alpha} > \rho$ and $f(e) \leq 0$, where ρ is defined in Lemma 3.1.*

Proof. Set $e_0 \in C_0^\infty([-1, 1])$ with $\|e_0\|_{X^\alpha} = 1$. For $M > (2 \int_{-1}^1 a(t) |e_0(t)|^2 dt)^{-1}$, it follows from (G_2) that there exists a constant $R > 0$ such that

$$(3.12) \quad G(x) \geq M|x|^2, \quad \forall |x| \geq R.$$

Let $D = \frac{1}{M} \max_{|x| \leq R} G(x)$. Then (3.12) implies

$$(3.13) \quad G(x) \geq M(|x|^2 - D), \quad \forall |x| \geq R.$$

By (3.13), for every $\xi \in \mathbb{R}$, we have

$$\begin{aligned} f(\xi e_0) &= \frac{\xi^2}{2} \|e_0\|_{X^\alpha}^2 - \int_{-1}^1 a(t) G(\xi e_0(t)) dt \\ &\leq \frac{\xi^2}{2} - \int_{-1}^1 a(t) M(\xi^2 |e_0(t)|^2 - D) dt \\ &\leq \frac{\xi^2}{2} - M\xi^2 \int_{-1}^1 a(t) |e_0(t)|^2 dt + MD \int_{-1}^1 a(t) dt \\ &\leq \frac{\xi^2}{2} (1 - 2M \int_{-1}^1 a(t) |e_0(t)|^2 dt) + MD \int_{-1}^1 a(t) dt, \end{aligned}$$

which implies that

$$f(\xi e_0) \longrightarrow -\infty \text{ as } |\xi| \longrightarrow +\infty.$$

Hence there exists $\xi_0 \in \mathbb{R}$ such that $\|\xi_0 e_0\|_{X^\alpha} > \rho$ and $f(\xi_0 e_0) < 0$. Letting $e(t) = \xi_0(t) e_0(t)$, we finish the proof of Lemma 3.4. \square

By Lemmas 2.4, 3.1-3.4, and the fact $f(0) = 0$, we see that f possesses at least one nontrivial critical point u satisfying $f(u) \geq \alpha$. Since $f(0) = 0 < \alpha$, then u is a nontrivial solution of (\mathcal{FHS}) .

Proof of Theorem 1.2.

Lemma 3.5. *Assume that $(L_1) - (L_3)$, (G_1) , and (G_4) are satisfied. Then, for each finite-dimensional subspace $\tilde{X} \subset X^\alpha$, there exists a constant $r = r(\tilde{X}) > 0$ such that $f \leq 0$ on $\tilde{X} \setminus B_r(0)$.*

Proof. Let $\tilde{X} \subset X^\alpha$ be a finite-dimensional subspace. We claim that there is a constant $\varepsilon_0 > 0$ such that

$$(3.14) \quad \text{meas}_a(\{t \in \mathbb{R} / |u(t)| \geq \varepsilon_0 \|u\|_{X^\alpha}\}) < \varepsilon_0, \quad \forall u \in \tilde{X} \setminus \{0\}.$$

If not, for any $n \in \mathbb{N}$, there is $u_n \in \tilde{X} \setminus \{0\}$ such that

$$\text{meas}_a\left(\left\{t \in \mathbb{R} / |u_n(t)| \geq \frac{1}{n} \|u_n\|_{X^\alpha}\right\}\right) < \frac{1}{n}.$$

Let $v_n = \frac{u_n}{\|u_n\|}$. Then $\|v_n\|_{X^\alpha} = 1$ and

$$(3.15) \quad \text{meas}_a\left(\left\{t \in \mathbb{R} / |v_n(t)| \geq \frac{1}{n}\right\}\right) \leq \frac{1}{n}, \quad \forall n \in \mathbb{N}.$$

Since \tilde{X} is finite-dimensional, then taking a subsequence if necessary, we may assume that $v_n \rightarrow v_0$ in \tilde{X} for some $v_0 \in \tilde{X}$. Clearly $\|v_0\|_{X^\alpha} = 1$. Note that, up to a subsequence, Lemma 2.2 implies that

$$(3.16) \quad \int_{\mathbb{R}} a(t) |v_n - v_0|^2 \longrightarrow 0 \text{ as } n \longrightarrow \infty.$$

We claim that there is a constant $\delta_0 > 0$ satisfying

$$(3.17) \quad meas_a(\{t \in \mathbb{R}, |v_0(t)| \geq \delta_0\}) \geq \delta_0.$$

If not, for each fixed $n \in \mathbb{N}$ and $m > n$, we have

$$meas_a\left(\left\{t \in \mathbb{R}, |v_0(t)| \geq \frac{1}{n}\right\}\right) \leq meas_a\left(\left\{t \in \mathbb{R}, |v_0(t)| \geq \frac{1}{m}\right\}\right) \leq \frac{1}{m}.$$

Letting $m \rightarrow \infty$, we have $meas_a(\{t \in \mathbb{R}, |v_0(t)| \geq \frac{1}{n}\}) = 0$. Consequently,

$$\begin{aligned} meas_a(\{t \in \mathbb{R}/v_0(t) \neq 0\}) &= meas_a\left(\bigcup_{n=1}^{\infty} \left\{t \in \mathbb{R}, |v_0(t)| \geq \frac{1}{n}\right\}\right) \\ &\leq \sum_{n=1}^{\infty} meas_a\left(\left\{t \in \mathbb{R}, |v_0(t)| \geq \frac{1}{n}\right\}\right) = 0 \end{aligned}$$

which implies that $v_0 = 0$ and contradicts $\|v_0\|_{X^\alpha} = 1$. Then (3.17) holds. For any $n \in \mathbb{N}$, let

$$\Lambda_0 = \{t \in \mathbb{R}/|v_0(t)| \geq \delta_0\}, \quad \Lambda_n = \left\{t \in \mathbb{R}/|v_n(t)| < \frac{1}{n}\right\}.$$

Then, for n large enough, we have from (3.15) and (3.17) that

$$meas_a(\Lambda_0 \cap \Lambda_n) \geq meas_a(\Lambda_0) - meas_a(\Lambda_n^c) \geq \delta_0 - \frac{1}{n} \geq \frac{\delta_0}{2}.$$

Therefore, for n large enough, one obtains

$$\begin{aligned} \int_{\mathbb{R}} a(t) |v_n - v_0|^2 dt &\geq \int_{\Lambda_0 \cap \Lambda_n} a(t) |v_n - v_0|^2 dt \\ &\geq \frac{1}{2} \int_{\Lambda_0 \cap \Lambda_n} a(t) |v_0|^2 dt - \int_{\Lambda_0 \cap \Lambda_n} a(t) |v_n|^2 dt \\ &\geq \left(\frac{\delta_0^2}{2} - \frac{1}{n^2}\right) meas_a(\Lambda_0 \cap \Lambda_n) \\ &\geq \left(\frac{\delta_0^2}{2} - \frac{1}{n^2}\right) \frac{\delta_0}{2} \geq \frac{\delta_0^3}{8}, \end{aligned}$$

which contradicts (3.16). Hence (3.14) holds. For $u \in \tilde{X} \setminus \{0\}$, set

$$\Lambda_{\varepsilon_0}(u) = \{t \in \mathbb{R}/|u(t)| \geq \varepsilon_0 \|u\|_{X^\alpha}\}.$$

Since $meas_a(\Lambda_{\varepsilon_0}(u)) \geq \varepsilon_0$, $\forall u \in \tilde{X} \setminus \{0\}$, there exists $\rho > 0$ satisfying

$$(3.18) \quad meas_a(\Lambda_{\varepsilon_0}(u) \cap B_\rho(0)) \geq \frac{\varepsilon_0}{2}, \quad \forall u \in \tilde{X} \setminus \{0\}.$$

By (G_2) , there exists $R > 0$ such that

$$(3.19) \quad G(u(t)) \geq \frac{2}{\varepsilon_0^3} |u(t)|^2 \geq \frac{2}{\varepsilon_0} \|u\|^2$$

for all $u \in \tilde{X} \setminus \{0\}$ and $t \in \Omega_{\varepsilon_0}(u) = \Lambda_{\varepsilon_0}(u) \cap B_\rho(0)$ with $\|u\|_{X^\alpha} \geq R$. Then, for any $u \in \tilde{X} \setminus B_R(0)$, it follows from (3.1), (3.18), and (3.19) that

$$\begin{aligned}
f(u) &= \frac{1}{2} \|u\|_{X^\alpha}^2 - \int_{\mathbb{R}} a(t)G(u(t))dt \\
&= \frac{1}{2} \|u\|_{X^\alpha}^2 - \int_{\Omega_{\varepsilon_0}(u)} a(t)G(u(t))dt - \int_{\mathbb{R} \setminus \Omega_{\varepsilon_0}(u)} a(t)G(u(t))dt \\
&\leq \frac{1}{2} \|u\|_{X^\alpha}^2 - \int_{\Omega_{\varepsilon_0}(u)} a(t)G(u(t))dt \\
&\leq \frac{1}{2} \|u\|_{X^\alpha}^2 - \frac{2}{\varepsilon_0^3} \int_{\Omega_{\varepsilon_0}(u)} a(t) |u(t)|^2 dt \\
&\leq \frac{1}{2} \|u\|_{X^\alpha}^2 - \frac{2}{\varepsilon_0} \int_{\Omega_{\varepsilon_0}(u)} a(t) \|u\|_{X^\alpha}^2 dt \\
&\leq \frac{1}{2} \|u\|_{X^\alpha}^2 - \frac{2}{\varepsilon_0} \text{meas}_a(\Omega_{\varepsilon_0}(u)) \|u\|_{X^\alpha}^2 \\
&\leq \frac{1}{2} \|u\|_{X^\alpha}^2 - \|u\|_{X^\alpha}^2 = -\frac{1}{2} \|u\|_{X^\alpha}^2.
\end{aligned}$$

Thus there exists $r > R$ such that $f|_{\tilde{X} \setminus B_r(0)} \leq 0$. \square

The functional f is even and $f(0) = 0$, so Lemmas 3.1, 3.3, and 3.5 imply that f satisfies all the conditions of Lemma 2.5. Consequently, f possesses an unbounded sequence of critical values which proves Theorem 1.2.

4. PROOF OF THEOREM 1.3 AND THEOREM 1.4

Lemma 4.1. *Assume that $(L_1) - (L_3)$, (G_1) , (G_2) , (G_5) , and (G_6) are satisfied. Then f verifies (C) -sequence.*

Proof. Let $(u_n) \subset X^\alpha$ be a (C) -sequence. Then there is $c_1 > 0$ satisfying

$$(4.1) \quad |f(u_n)| \leq c_1 \text{ and } \|f'(u_n)\| (1 + \|u_n\|_{X^\alpha}) \leq c_1, \forall n \in \mathbb{N}.$$

We claim that (u_n) is bounded. Assume indirectly that (u_n) is unbounded. Taking a subsequence if necessary, we may assume that

$$(4.2) \quad \|u_n\|_{X^\alpha} \longrightarrow +\infty \text{ and } v_n = \frac{u_n}{\|u_n\|_{X^\alpha}} \rightarrow v_0 \text{ as } n \longrightarrow \infty.$$

By Lemma 2.2 and (4.2), without loss of generality, we have

$$(4.3) \quad v_n \longrightarrow v_0 \text{ both in } L_a^2(\mathbb{R}) \text{ and } L_a^V(\mathbb{R}) \text{ and } v_n(t) \longrightarrow v_0(t) \text{ a.e. } t \in \mathbb{R}$$

as $n \longrightarrow \infty$.

Case 1. $v_0 \neq 0$ occurs. The proof is similar to the case 1 in the proof of Lemma 3.3.

Case 2. $v_0 = 0$ occurs. Let $(s_n) \subset [0, 1]$ be a sequence such that

$$f(s_n u_n) = \max_{s \in [0, 1]} f(s u_n).$$

By (G_5) and (4.3), we obtain

$$\begin{aligned} & \left| \int_{\mathbb{R}} a(t)G(4\sqrt{\sigma c_1}v_n(t))dt \right| \\ & \leq d_0 \left[16\sigma c_1 \int_{\mathbb{R}} a(t)|v_n(t)|^2 dt + (4\sqrt{\sigma c_1})^v \int_{\mathbb{R}} a(t)|v_n(t)|^v dt \right] \longrightarrow 0 \text{ as } n \longrightarrow \infty, \end{aligned}$$

which implies

$$(4.4) \quad \int_{\mathbb{R}} a(t)G(4\sqrt{\sigma c_1}v_n(t))dt \longrightarrow 0 \text{ as } n \longrightarrow \infty.$$

By the definition of s_n and (4.4), for n large enough, we have

$$(4.5) \quad \begin{aligned} f(s_n u_n) & \geq f\left(\frac{4\sqrt{\sigma c_1}}{\|u_n\|^2}u_n\right) = f(4\sqrt{\sigma c_1}v_n) \\ & = 8\sigma c_1 - \int_{\mathbb{R}} a(t)G(4\sqrt{\sigma c_1}v_n(t))dt \geq 4\sigma c_1. \end{aligned}$$

Since $f(0) = 0$ and $|f(u_n)| \leq c_1$, then $s_n \in]0, 1[$. Hence, one has

$$(4.6) \quad \|s_n u_n\|^2 - \int_{\mathbb{R}} a(t)\nabla G(s_n u_n) \cdot s_n u_n dt = f'(s_n u_n)s_n u_n = s_n \frac{d}{ds}(f(su_n))|_{s=s_n} = 0.$$

It follows from (4.6) and (G_6) that

$$\begin{aligned} \int_{\mathbb{R}} a(t)\left[\frac{1}{2}\nabla G(u_n) \cdot u_n - G(u_n)\right]dt & = \int_{\mathbb{R}} a(t)\tilde{G}(u_n(t))dt \\ & \geq \frac{1}{\sigma} \int_{\mathbb{R}} a(t)\tilde{G}(s_n u_n)dt \\ & = \frac{1}{\sigma} \int_{\mathbb{R}} a(t)\left[\frac{1}{2}\nabla G(s_n u_n) \cdot s_n u_n - G(s_n u_n)\right]dt \\ & = \frac{1}{\sigma} \left[\frac{1}{2}\|s_n u_n\|_{X^\alpha}^2 - \int_{\mathbb{R}} a(t)G(s_n u_n)dt\right] \\ & = \frac{1}{\sigma} f(s_n u_n), \end{aligned}$$

which together with (4.5) implies that

$$(4.7) \quad \int_{\mathbb{R}} a(t)\left[\frac{1}{2}\nabla G(u_n)u_n - G(u_n)\right]dt \geq 4c_1,$$

for n large enough. However, we can deduce from (4.1) that

$$\left| \int_{\mathbb{R}} a(t)\left[\frac{1}{2}\nabla G(u_n)u_n - G(u_n)\right]dt \right| = \frac{1}{2} |2f(u_n) - f'(u_n)u_n| \leq \frac{3}{2}c_1,$$

for all $n \in \mathbb{N}$, which contradicts (4.7). Hence (u_n) is bounded in X^α . Similar to the proof of Lemma 3.3, we can prove that f satisfies (C)-condition. The proof of Lemma 4.1 is completed. \square

Proof of Theorem 1.3. The condition $f(0) = 0$ and Lemmas 3.1, 3.4, and 4.1 imply that functional f verifies all the conditions of Lemma 2.4. Therefore, Lemma 2.4 implies that f possesses a critical point u satisfying $f(u) \geq \alpha > 0$. Hence problem (\mathcal{FHS}) possesses a nontrivial solution.

Proof of Theorem 1.4. Since f is even, then condition $f(0) = 0$ and Lemmas 3.1, 3.5, and 4.1 imply that functional f verifies all the conditions of Lemma 2.5. Therefore, Lemma 2.5 implies that f has an unbounded sequence of critical values. Hence problem (\mathcal{FHS}) has infinitely many nontrivial solutions.

Acknowledgements

The author would like to thank very much the editors and the referees for carefully reading the manuscript and giving valuable suggestions.

REFERENCES

- [1] Z. Bai, H. Lü, Positive solutions for boundary value problem of nonlinear fractional differential equation, *J. Math. Anal. Appl.* 311 (2005) 495-505.
- [2] T. Bartolo, V. Benci, D. Fortunato, Abstract critical point theorems and applications to some nonlinear problems with strong resonance at infinity, *Nonlinear Anal.* 7 (1983) 981-1012.
- [3] G. Chai, W. Liu, Existence and multiplicity of solutions for fractional Hamiltonian systems, *Boundary Value Prob.* 2019 (2019) 71.
- [4] F. Chen, X. He, X.H. Tang, Infinitely many solutions for a class of fractional Hamiltonian systems via critical point theory, *Math. Meth. Appl. Sci.* 39 (2016) 1005-1019.
- [5] G.A.M. Cruz, C.E.T. Ledesma, Multiplicity of solutions for fractional Hamiltonian systems with Liouville-Weyl fractional derivatives, *Fract. Calc. Appl. Anal.* 18 (2015) 875-890.
- [6] Z. Guo, Q. Zhang, Existence of solutions to fractional Hamiltonian systems with local superquadratic conditions, *Electron. J. Differential Equations* 2020 (2020), No. 29.
- [7] W. Jiang, The existence of solutions for boundary value problems of fractional differential equations at resonance, *Nonlinear Anal.* 74 (2011) 1987-1994.
- [8] F. Jiao, Y. Zhou, Existence results for fractional boundary value problem via critical point theory, *Int. J. Bif. Chaos* 22 (2012) 1-17.
- [9] W. Jiang, The existence of solutions to boundary value problems of fractional differential equations at resonance, *Nonlinear Anal.* 74 (2011) 1987-1994.
- [10] A.A. Kilbas, O.I. Marichev, G. Samko, *Fractional Integrals and Derivatives, Theory and Applications*, Gordon and Breach, Switzerland 1997.
- [11] A.A. Kilbas, H.M. Srivastawa, J.J. Trujillo, *Theory and Applications of Fractional Differential Equations*, North-Holland Mathematical Studies; Vol. 204, Singapore 2005.
- [12] C.E.T. Ledesma, Existence of solutions for fractional Hamiltonian systems with nonlinear derivative dependence in \mathbb{R} , *J. Fractional Calc. Appl.* 7 (2016) 74-87.
- [13] Y. Li, B. Dai, Existence and multiplicity of nontrivial solutions for Liouville-Weyl fractional nonlinear Schrödinger equation, *Rev. R. Acad. Cienc. Exactas Fis. Nat. Ser. A Math. RACSAM* 112 (2018) 957-967.
- [14] J. Mawhin, M. Willem, *Critical point theory and Hamiltonian systems*, Applied Mathematical Sciences, Springer, New York, 1989. doi: 10.1007/978-1-4757-2061-7.
- [15] N. Nyamoradi, Y. Zhou, B. Ahmad, A. Alsaedi, Variational approach to homoclinic solutions for fractional Hamiltonian systems, *J. Optim. Theory Appl.* 174 (2017) 223-237.
- [16] V. Obukhovskii, G. Petrosyan, C.-F. Wen, V. Bocharov, On semilinear fractional differential inclusions with a nonconvex-valued right-hand side in Banach spaces, *J. Nonlinear Var. Anal.* 6 (2022) 185-197.
- [17] I. Pollubny, *Fractional Differential Equations*, Academic Press, 1999.
- [18] P.H. Rabinowitz, *Minimax methods in critical point theory with applications to differential equations*, In: CBMS Reg. Conf. Ser. in Math., Vol. 65, American Mathematical Society, Providence, R.I, 1985.
- [19] K. Tang, Multiple homoclinic solutions for a class of fractional Hamiltonian systems, *Progress in Fractional Differentiation and Applications* 2 (2016) 265-276.
- [20] M. Timoumi: Ground state solutions for a class of superquadratic fractional Hamiltonian systems, *J. Elliptic Parabol. Equ.* 7 (2021) 171-197.

- [21] M. Timoumi, Infinitely many solutions for a class of superquadratic fractional Hamiltonian systems, *Fract. Differ. Calc.* 8 (2018) 309-326.
- [22] M. Timoumi, Infinitely many solutions for two classes of fractional Hamiltonian systems, *Commun. Optim. Thory* 2021 (2021) Article ID 6.
- [23] M. Timoumi, Multiple solutions for a class of superquadratic fractional Hamiltonian systems, *Universal J. Math. Appl.* 1 (2018) 186-195.
- [24] M. Timoumi, Multiple solutions for fractional Hamiltonian systems locally defined near the origin, *Fractional Differential Calculus*, 10 (2020) 189–212.
- [25] C. Torres, Existence of solutions for fractional Hamiltonian systems, *Electron. J. Differential Equations* 2013 (2013), 259.
- [26] C. Torres, Ground state solution for differential equations with left and right fractional derivatives, *Math. Meth. Appl. Sci.* 38 (2015) 5063-5077.
- [27] D.L. Wu, C. Li, P. Yuan, Multiplicity solutions for a class of fractional Hamiltonian systems with concave-convex potentials, *Mediterr. J. Math.* 15 (2018) 35.
- [28] X. Wu, Z. Zhang, Solutions for perturbed fractional Hamiltonian systems without coercive conditions, *Bound. Value Probl.* 2015 (2015) 149.
- [29] F. Zhang, R. Yuan, Existence of solutions to fractional Hamiltonian systems with combined nonlinearities, *Electr. J. differential equations* 2016 (2016) 40.
- [30] R. Yuan, Z. Zhang, Homoclinic solutions for a class of second order Hamiltonian systems, *Results Math.* 61 (2012) 195-208.
- [31] Z. Zhang, R. Yuan, Solutions for subquadratic fractional Hamiltonian systems without coercive conditions, *Math. Meth. Appl. Sci.* 37 (2014) 2934-2945.
- [32] Z. Zhang, R. Yuan, Variational approach to solutions for a class of fractional Hamiltonian systems, *Math. Meth. Appl. Sci.* 37 (2014) 1873-1887.